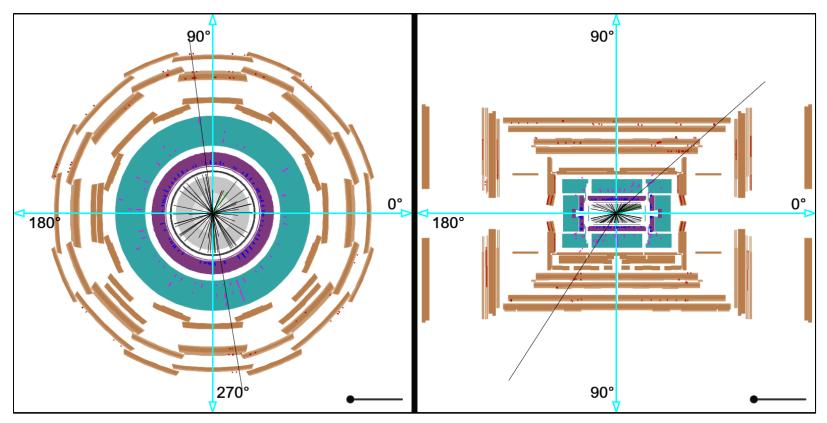
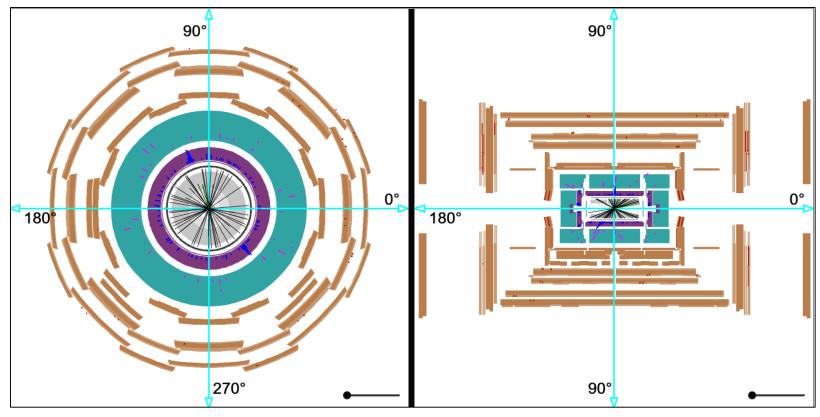
ATLAS-W2D2

Measurement for
Masterclass-in-a-box
Data Set 1



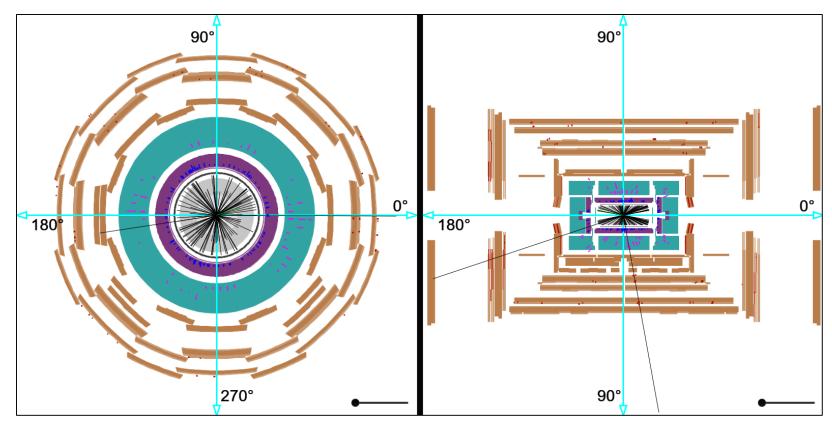
x-y view: measure $\boldsymbol{\varphi}$

z-y view: measure $\boldsymbol{\theta}$



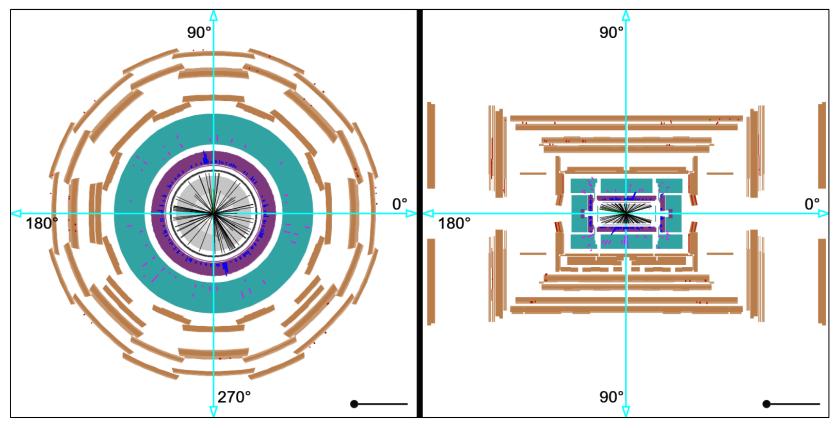
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



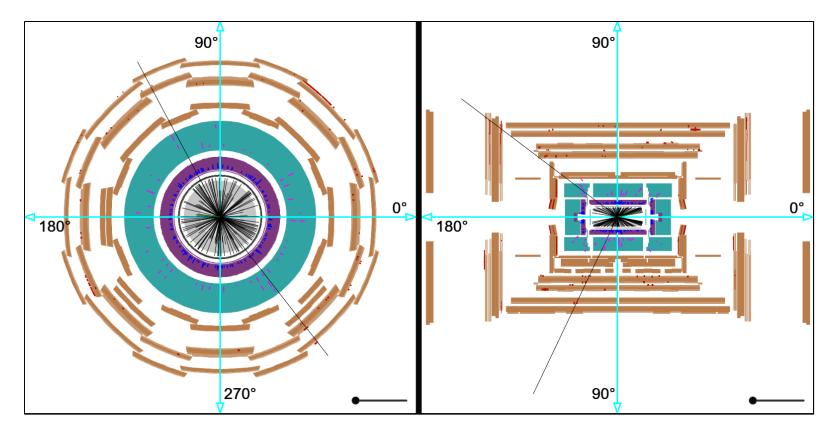
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



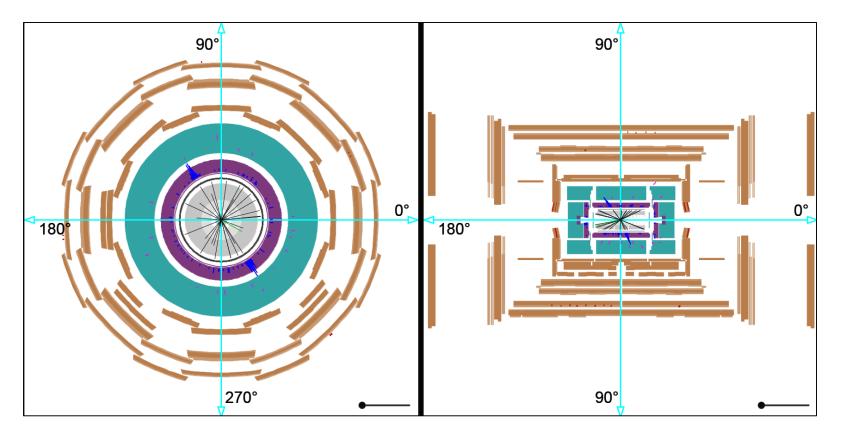
x-y view: measure $\boldsymbol{\varphi}$

z-y view: measure $\boldsymbol{\theta}$



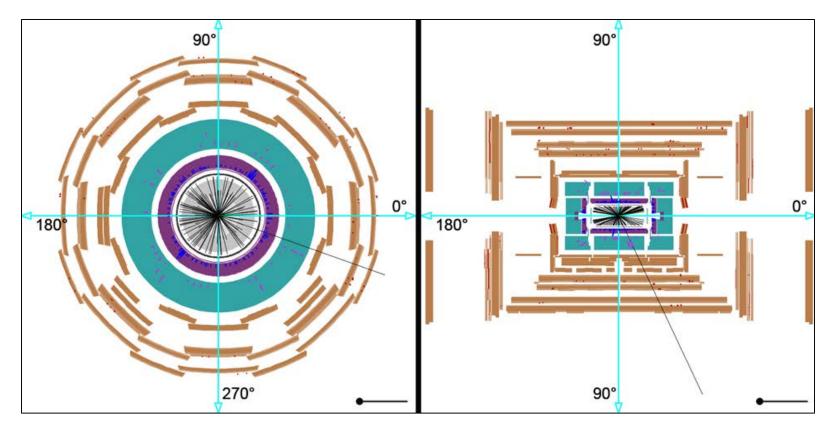
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



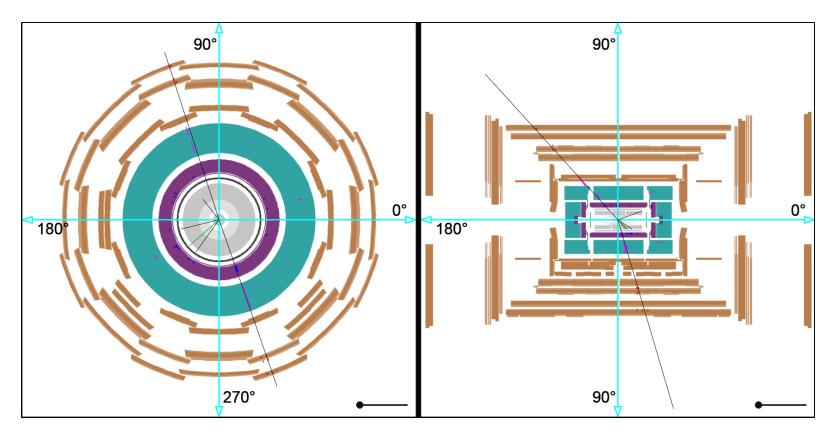
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



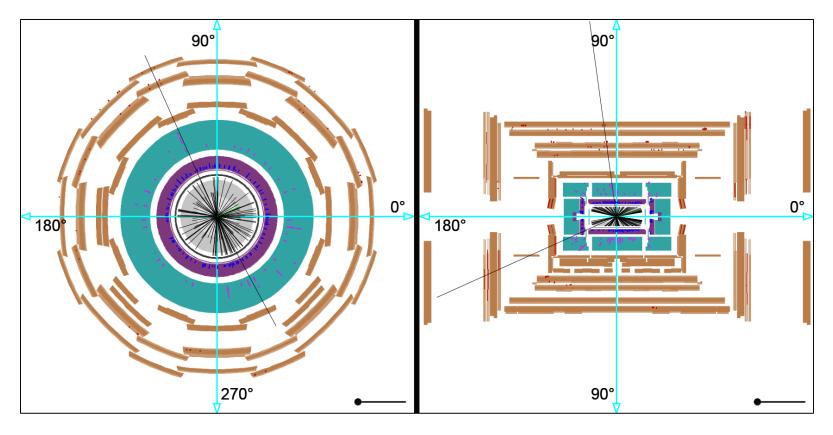
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



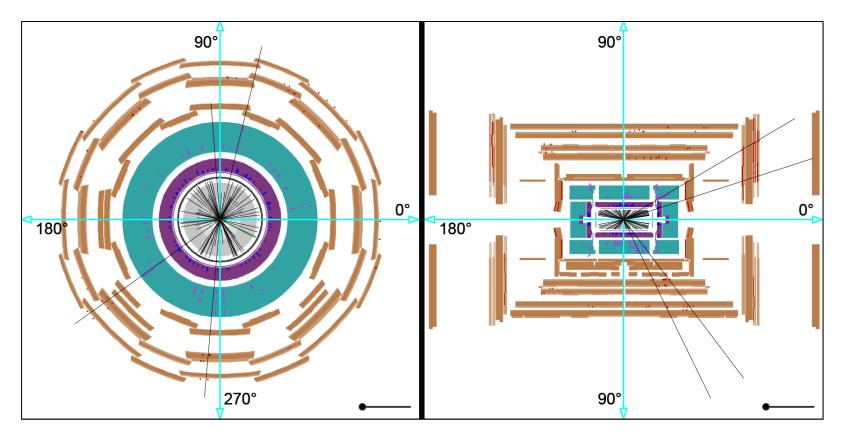
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



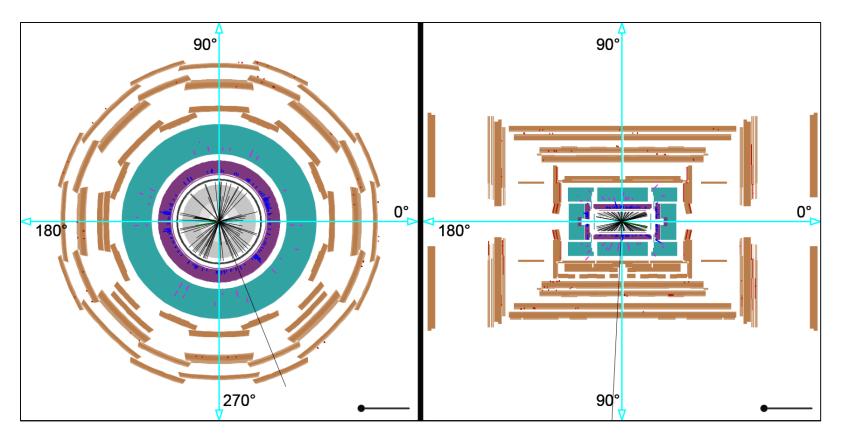
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



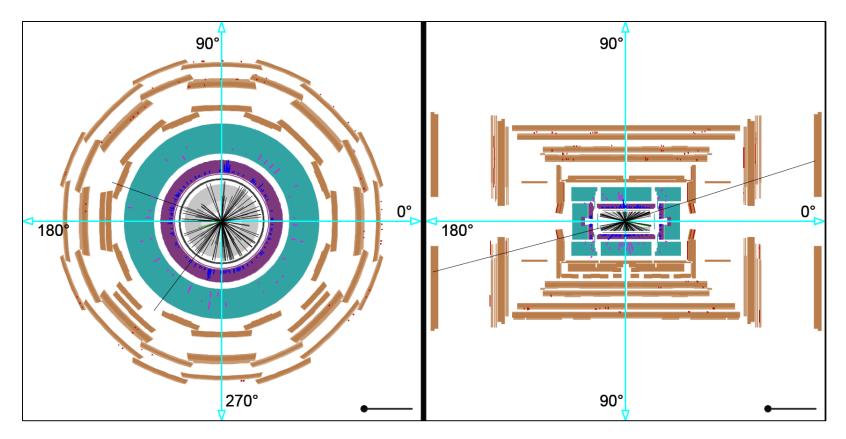
x-y view: measure $\boldsymbol{\varphi}$

z-y view: measure $\boldsymbol{\theta}$



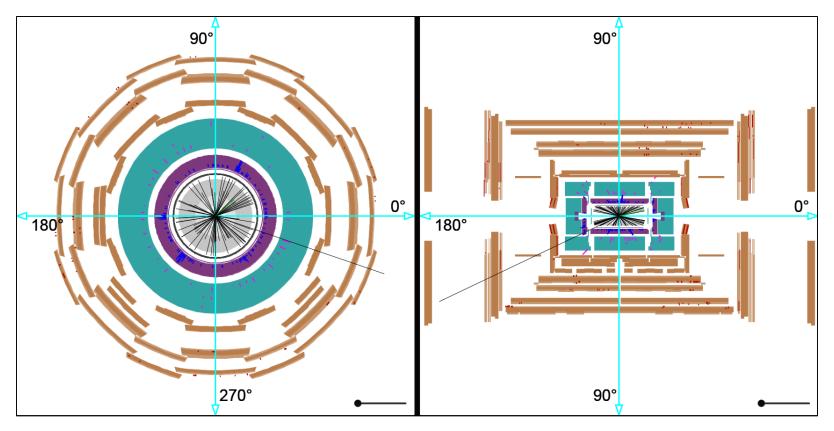
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



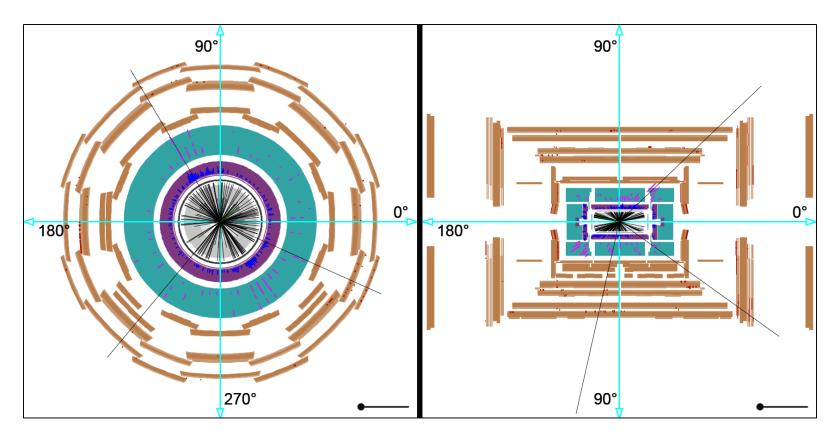
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



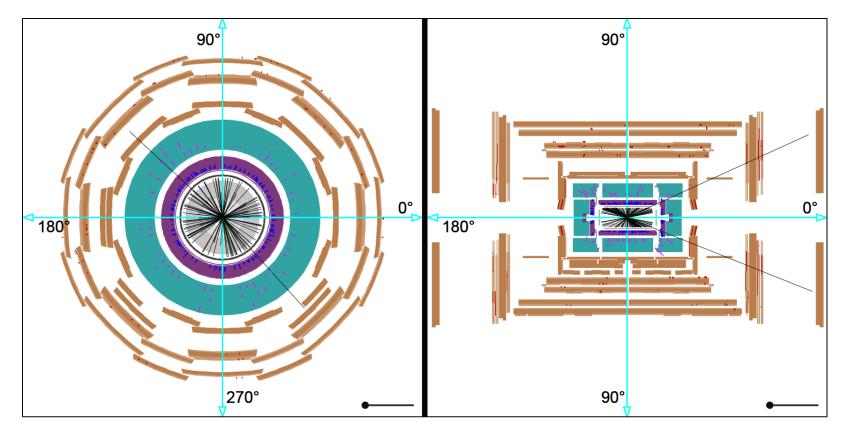
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



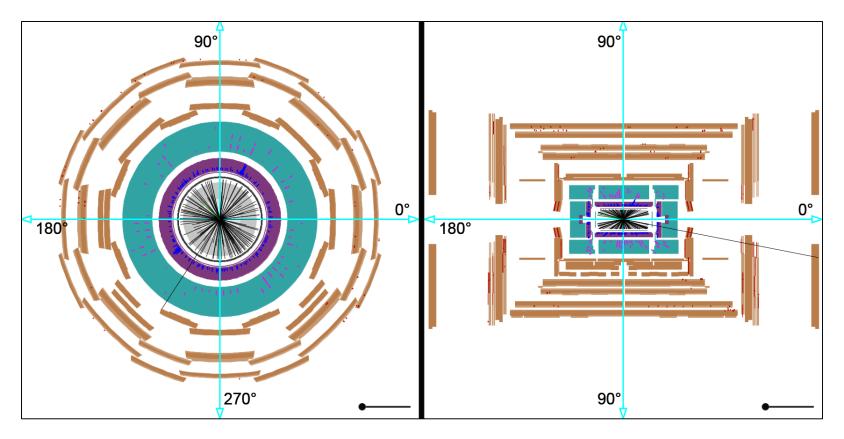
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



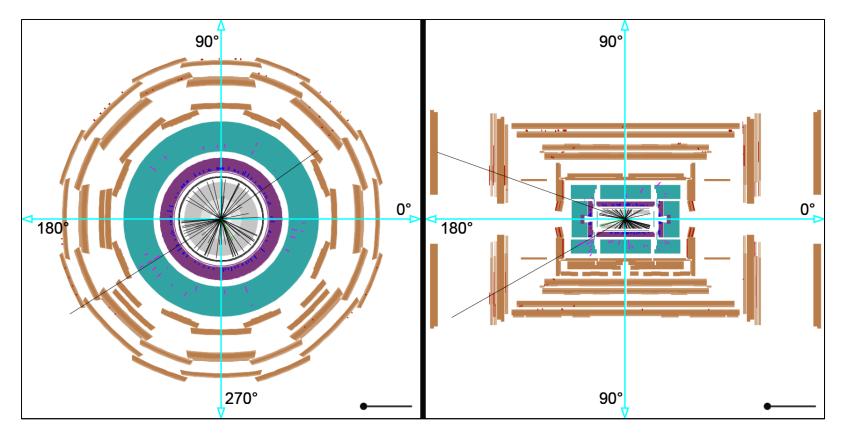
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



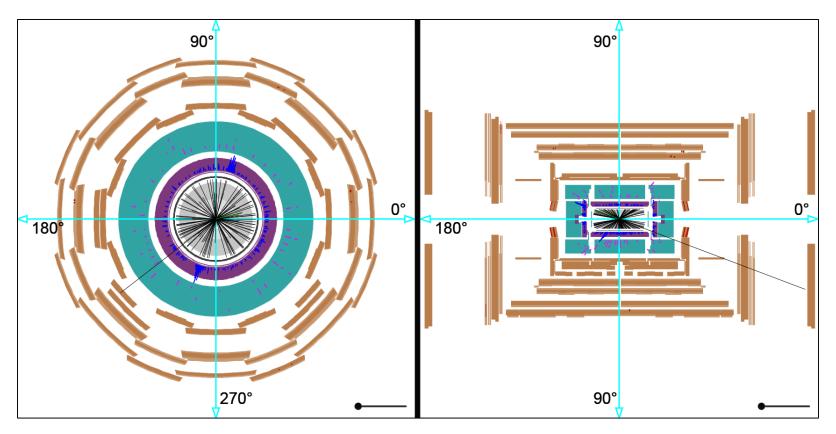
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



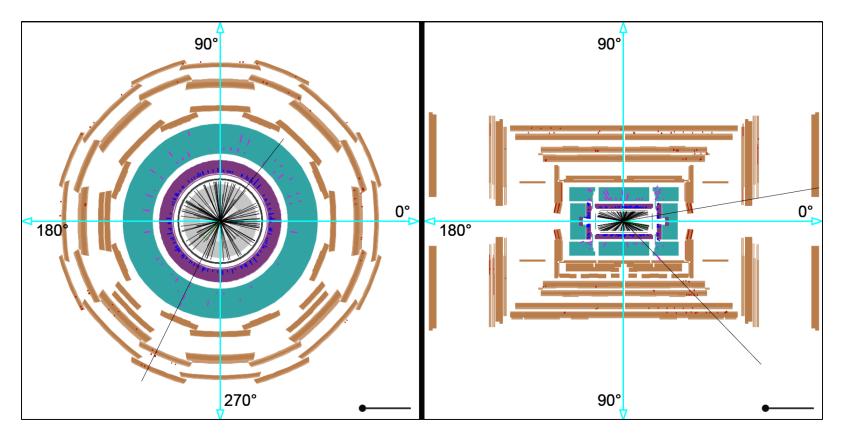
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



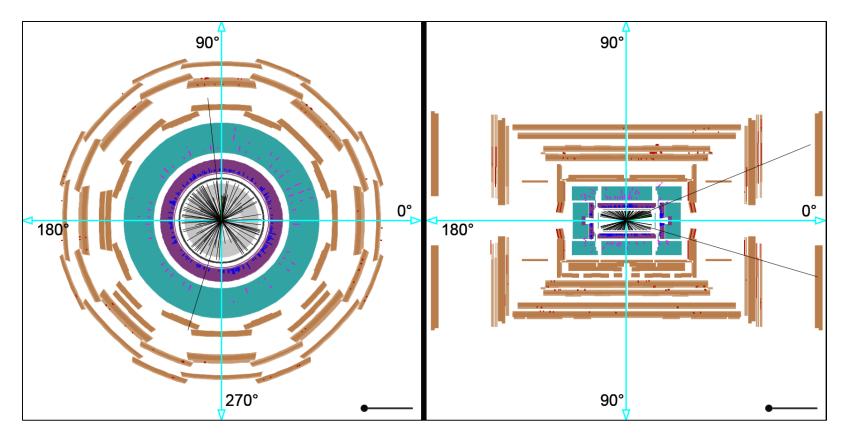
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



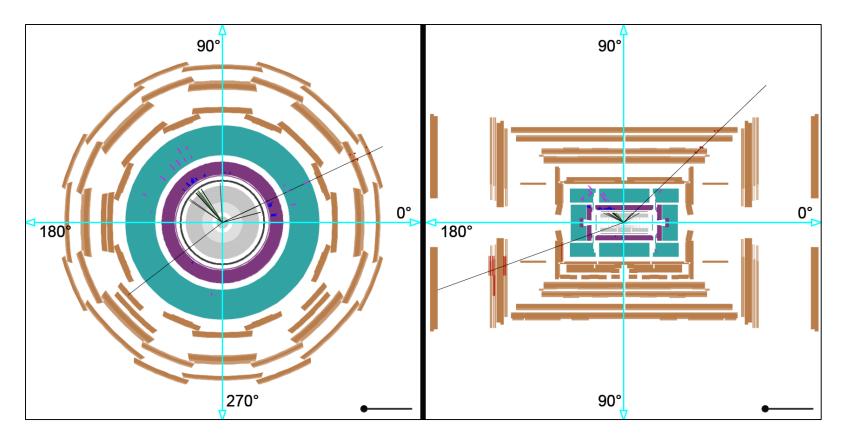
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



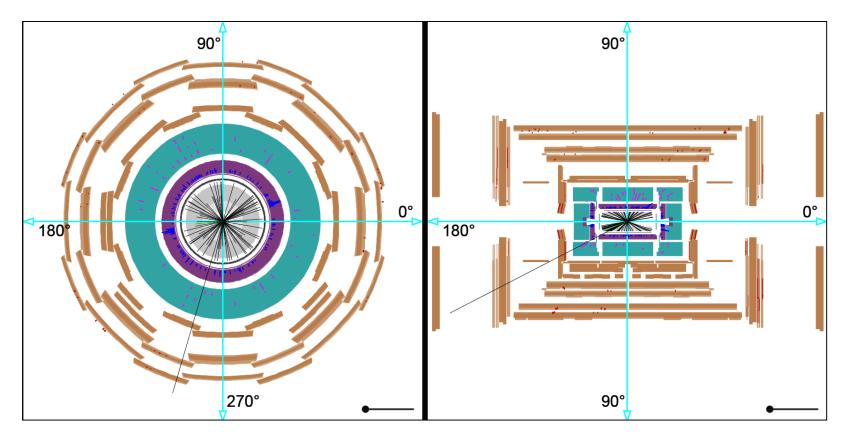
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



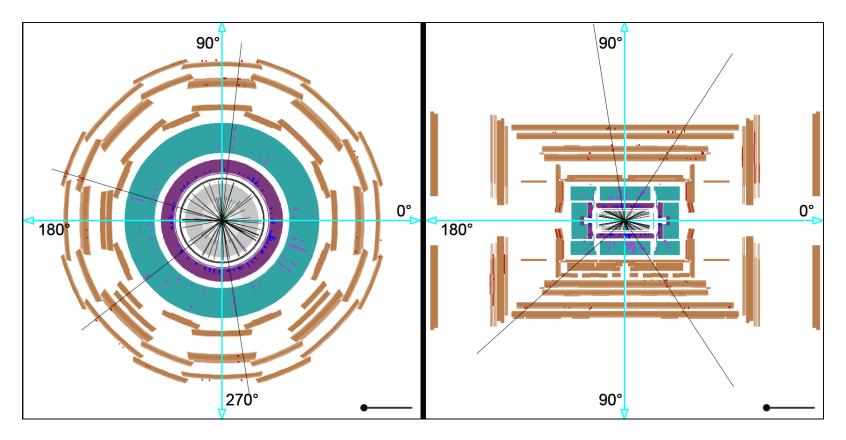
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



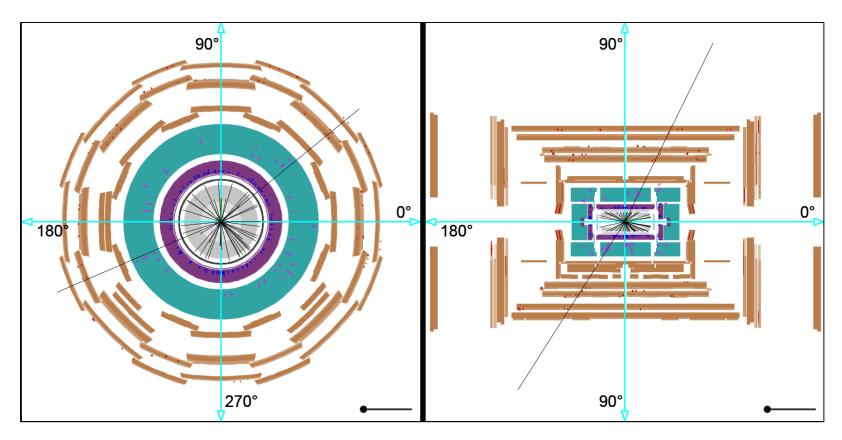
x-y view: measure $\boldsymbol{\varphi}$

z-y view: measure $\boldsymbol{\theta}$



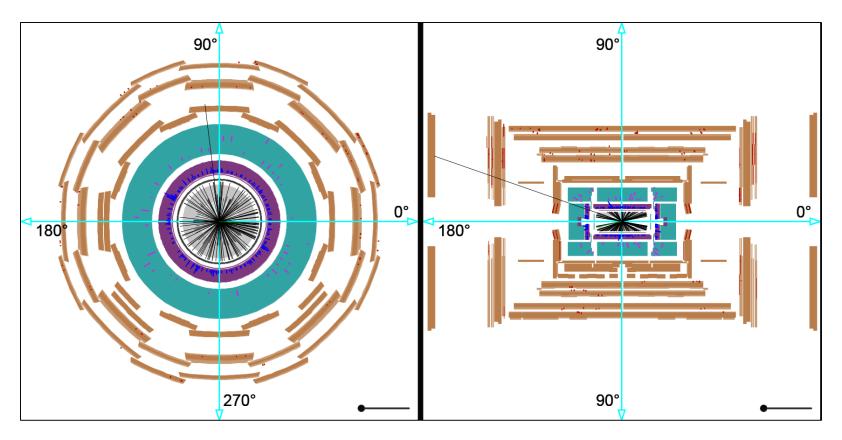
x-y view: measure $\boldsymbol{\varphi}$

z-y view: measure $\boldsymbol{\theta}$



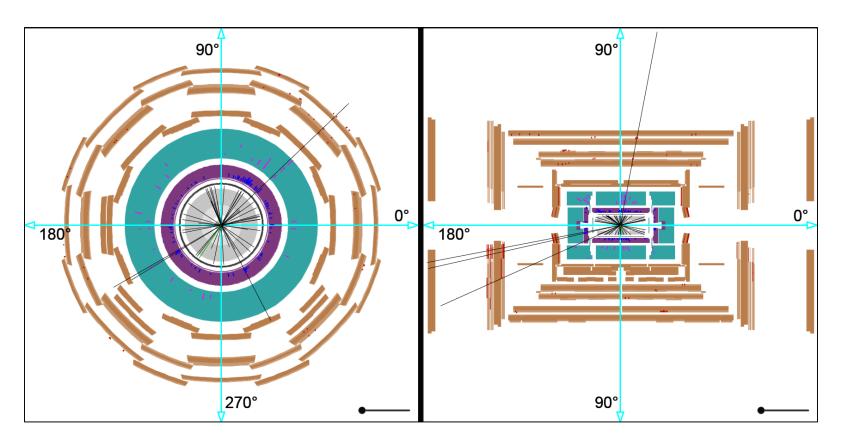
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



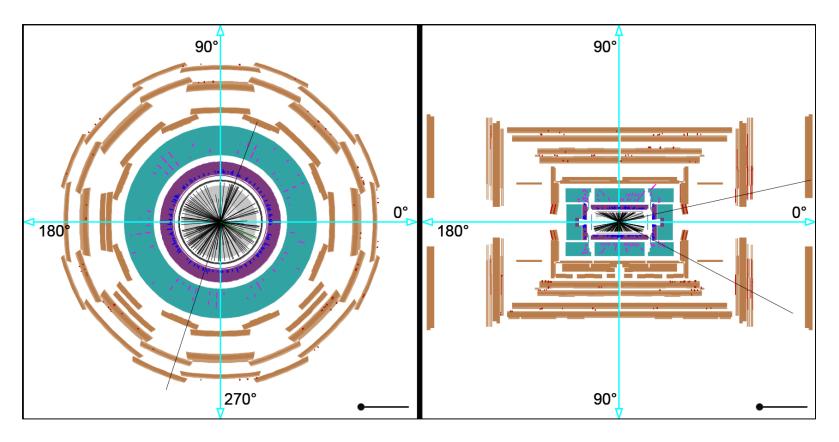
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



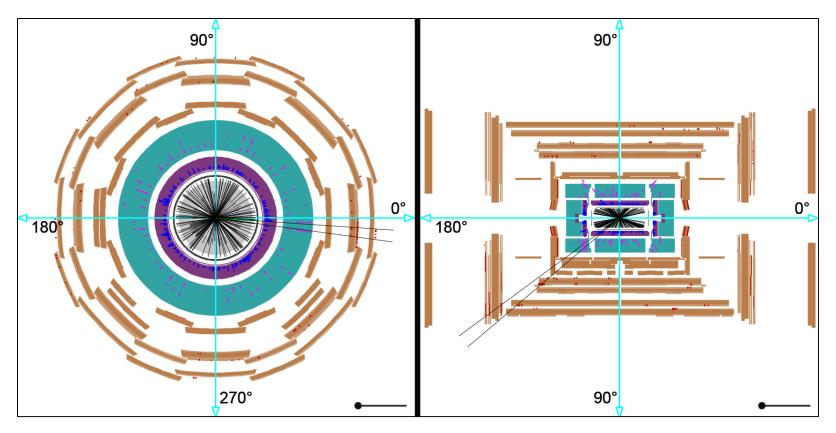
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



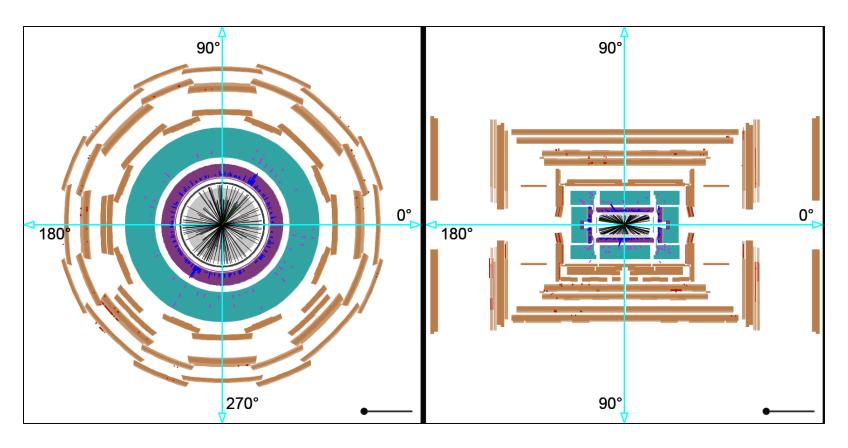
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



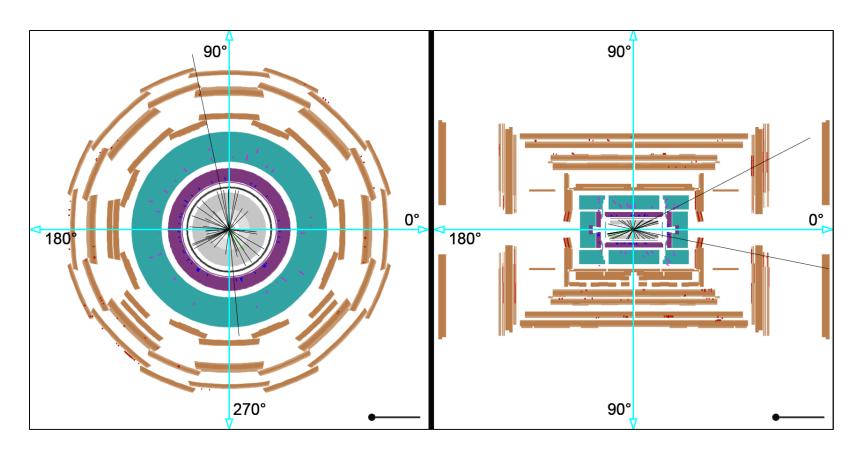
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



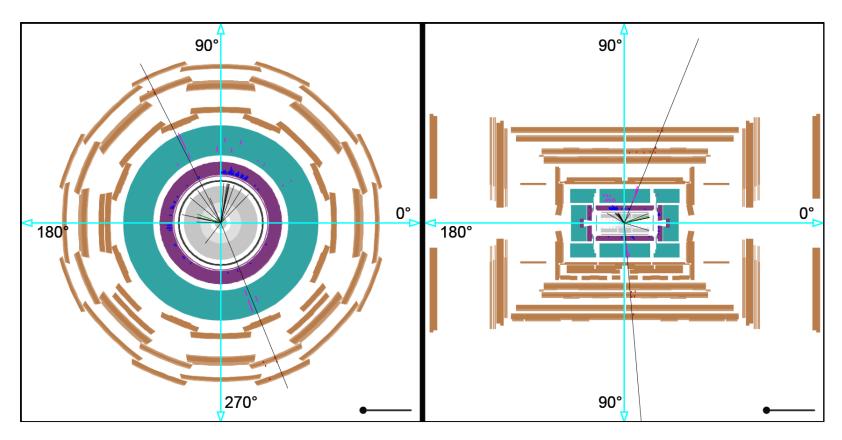
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



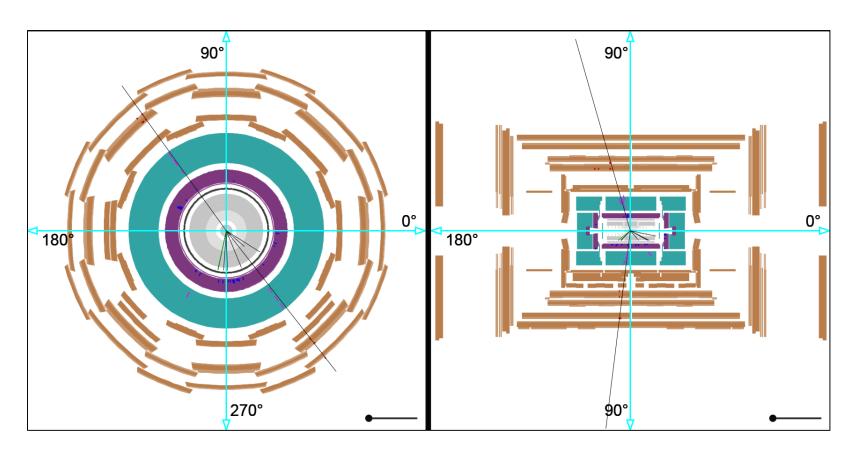
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



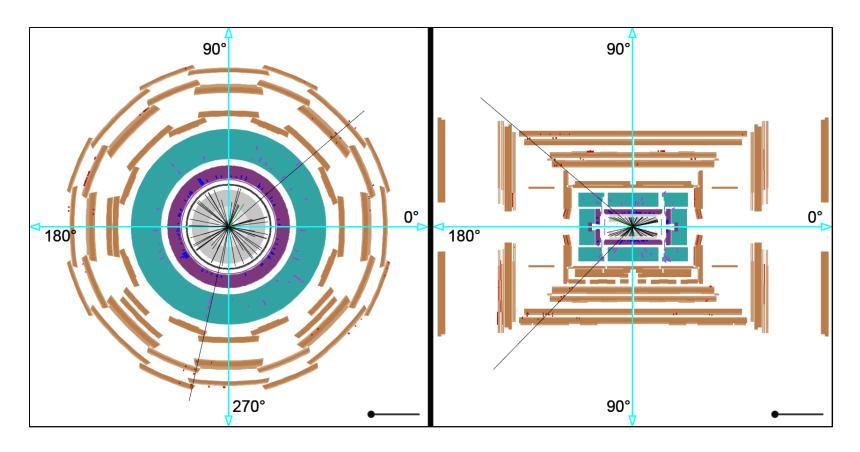
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



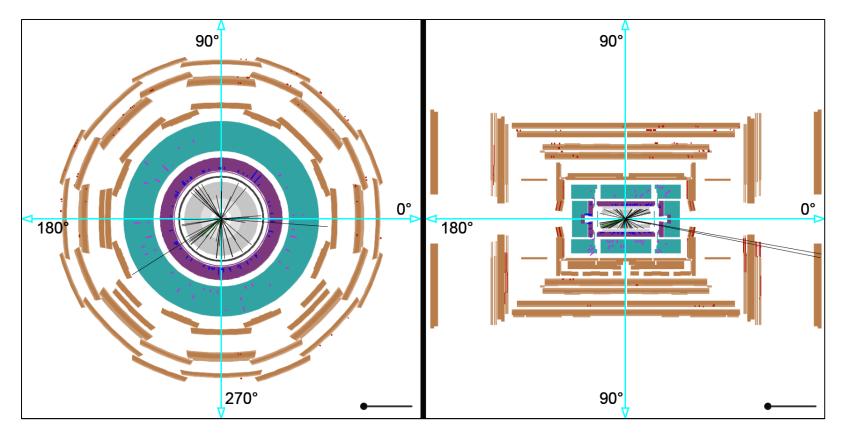
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



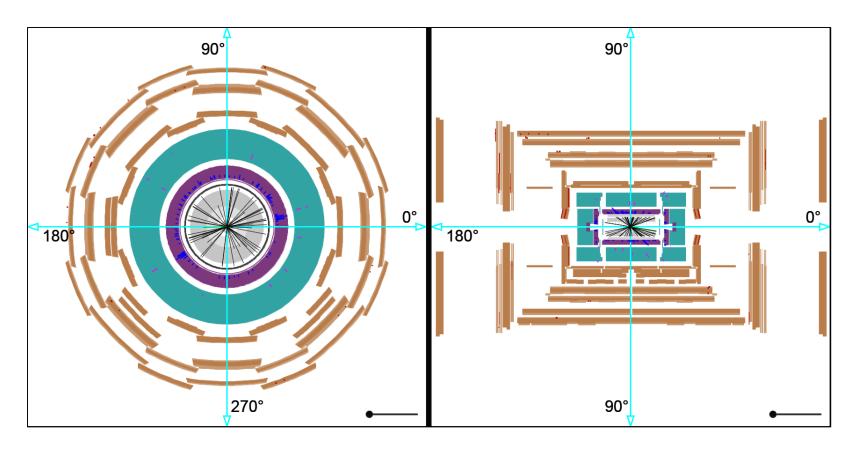
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



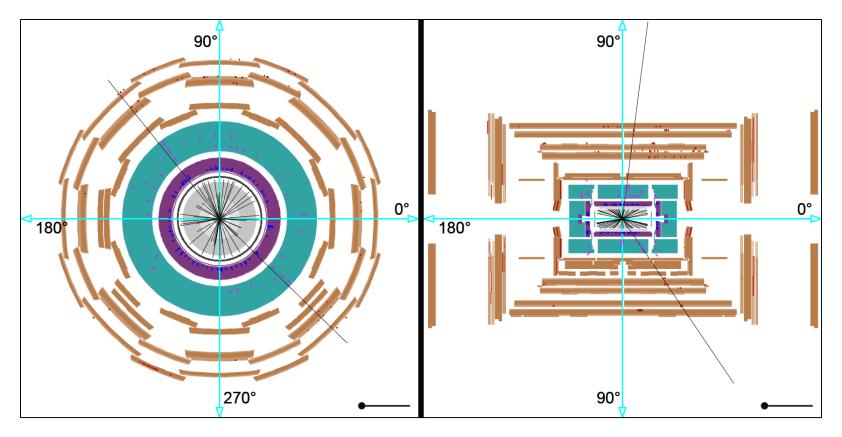
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



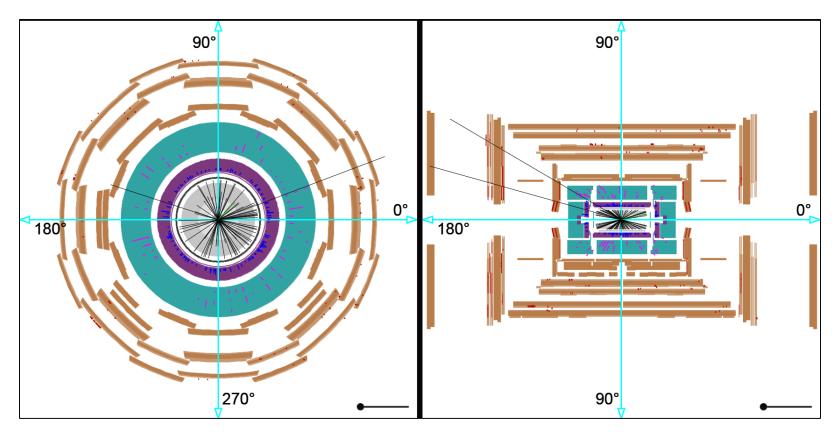
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



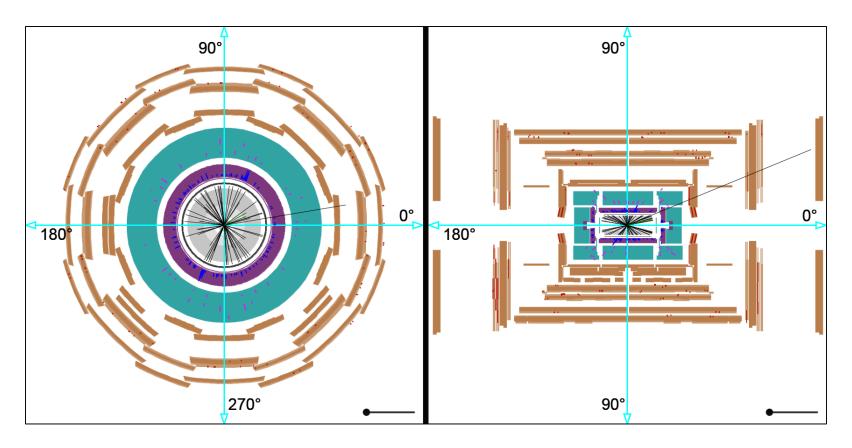
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



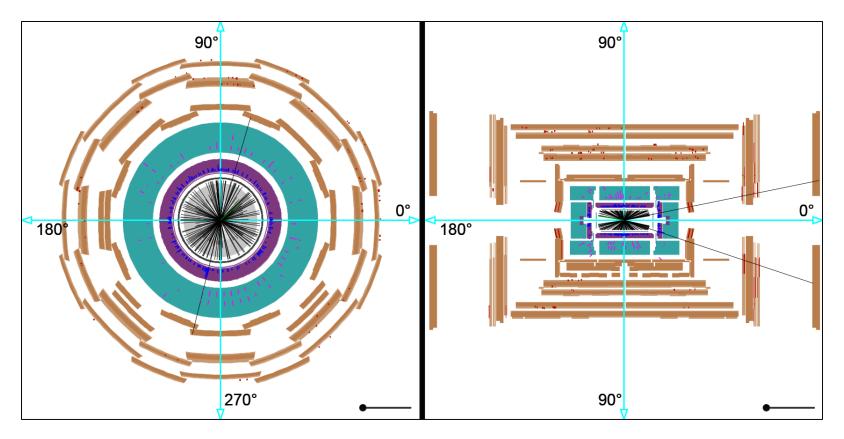
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



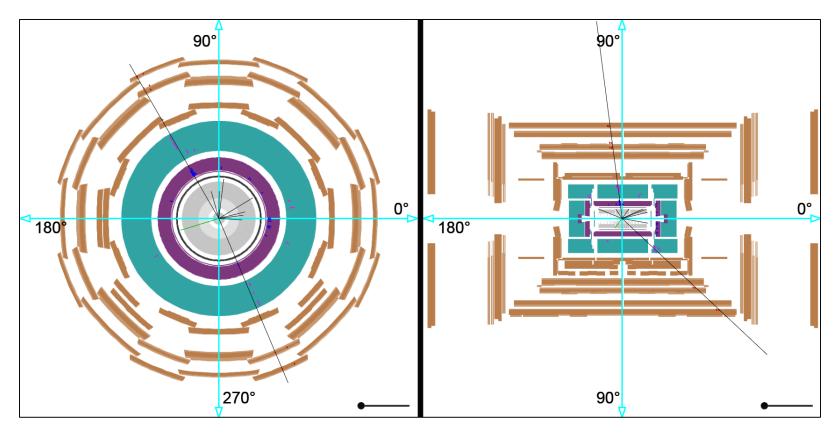
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



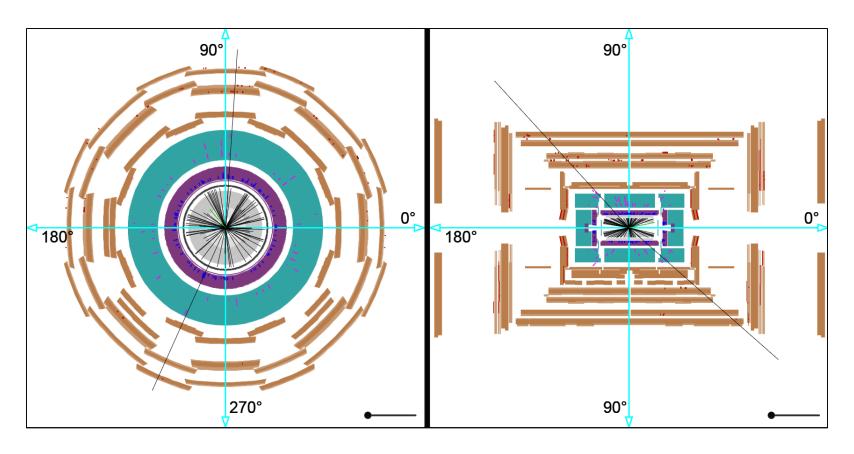
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



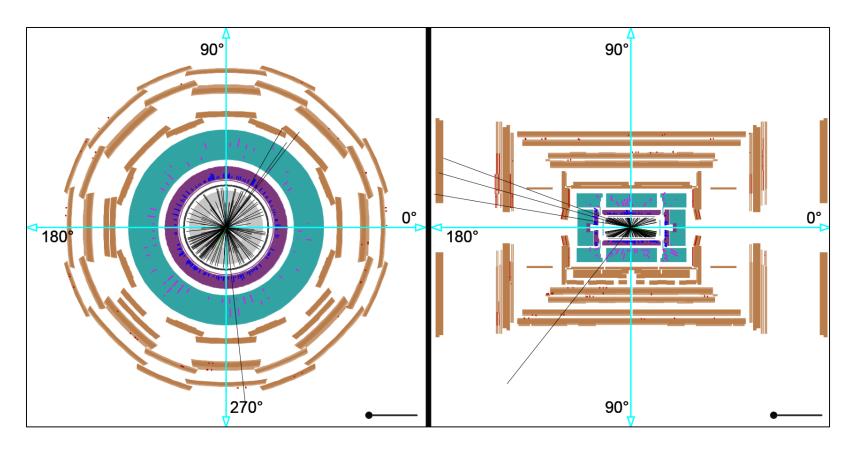
x-y view: measure $\boldsymbol{\varphi}$

z-y view: measure $\boldsymbol{\theta}$



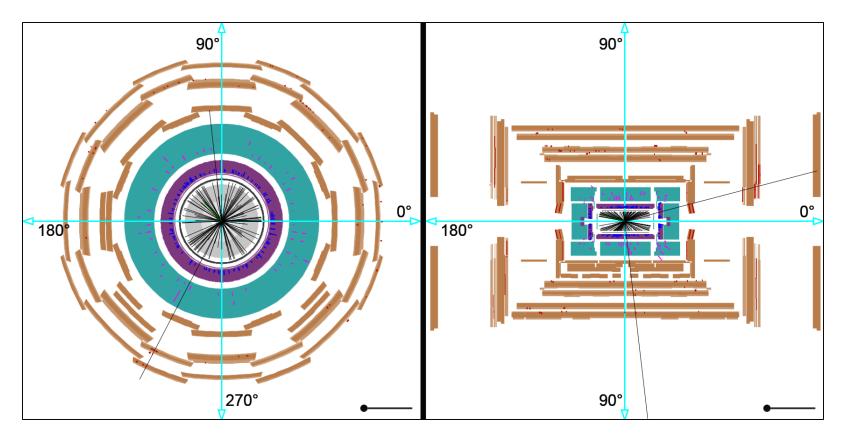
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



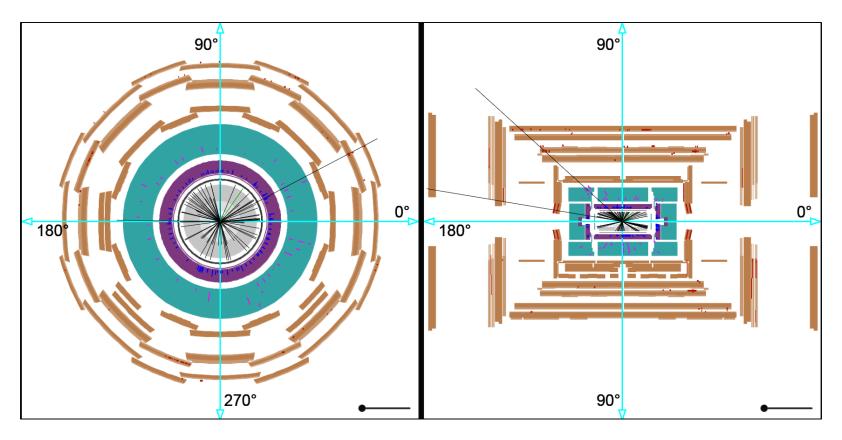
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



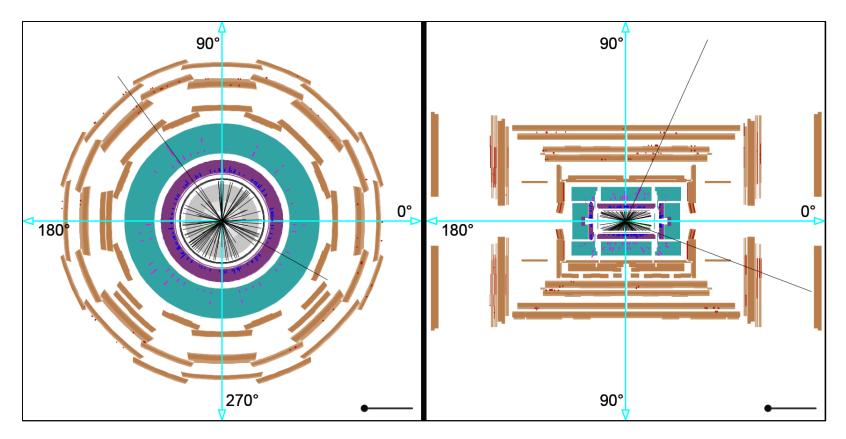
x-y view: measure ϕ

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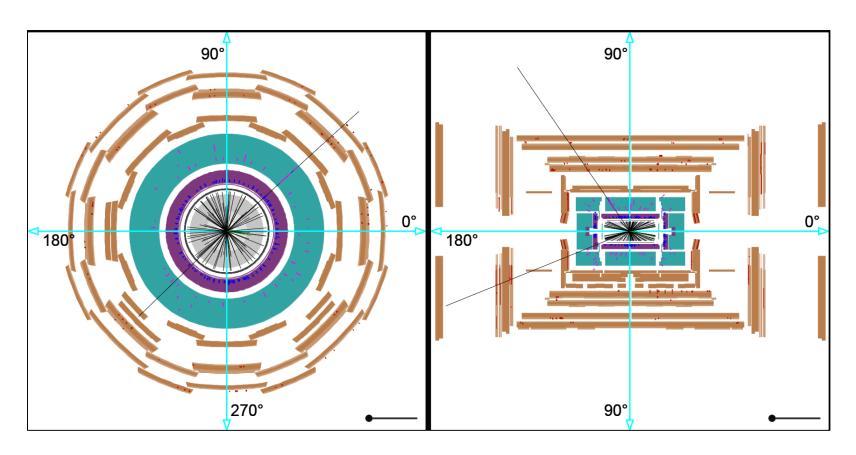
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



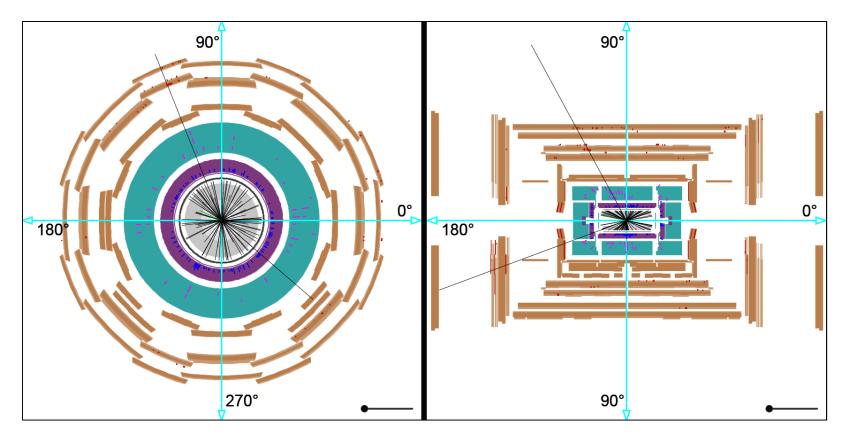
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



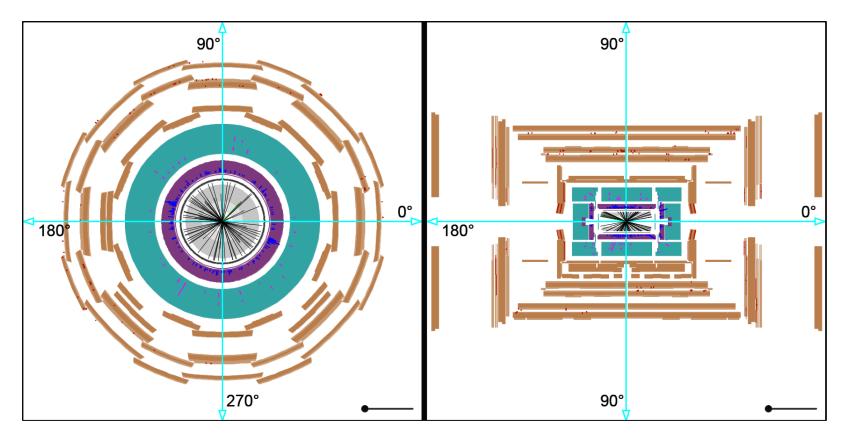
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



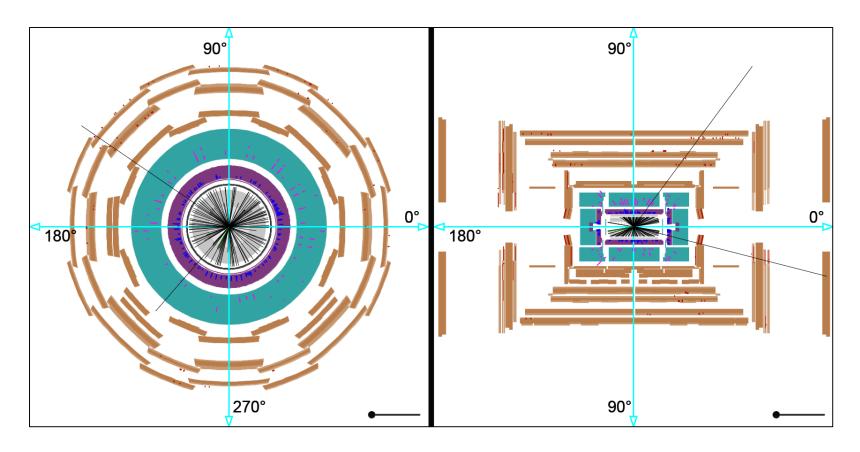
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



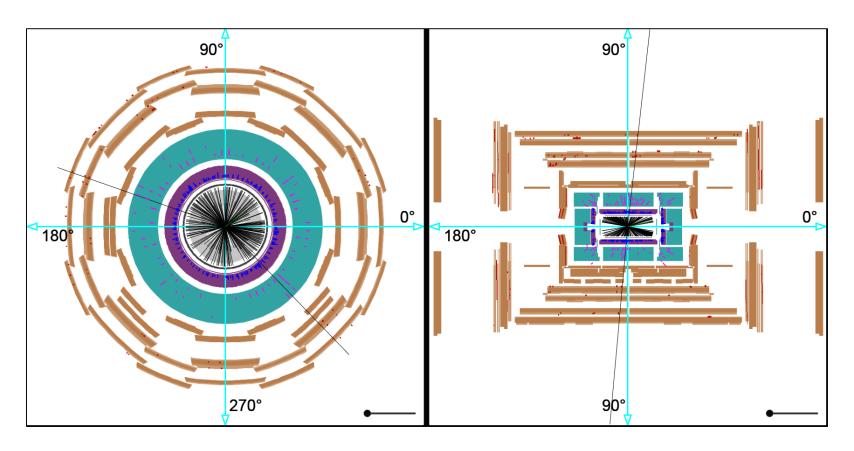
x-y view: measure $\boldsymbol{\varphi}$

z-y view: measure $\boldsymbol{\theta}$



x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$