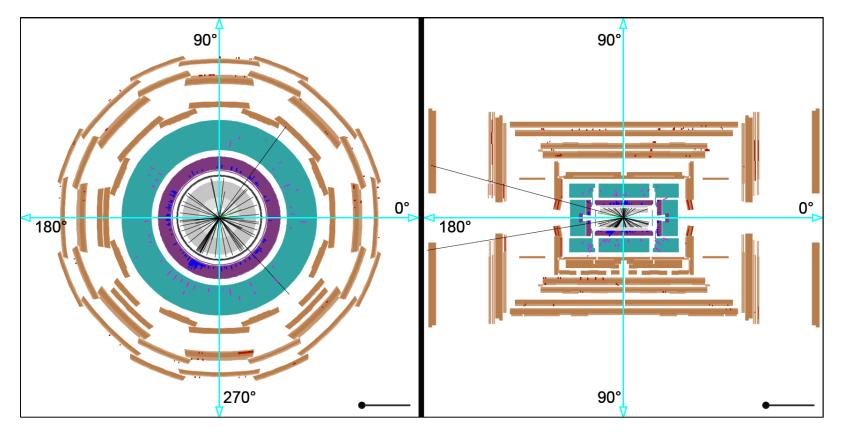
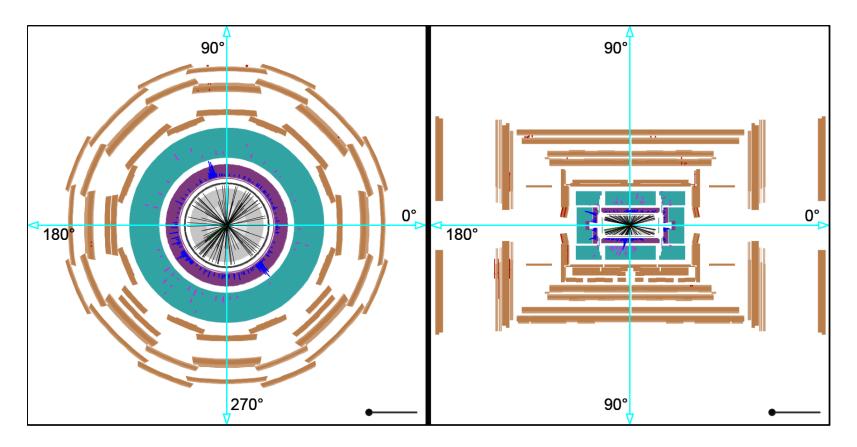
ATLAS-W2D2

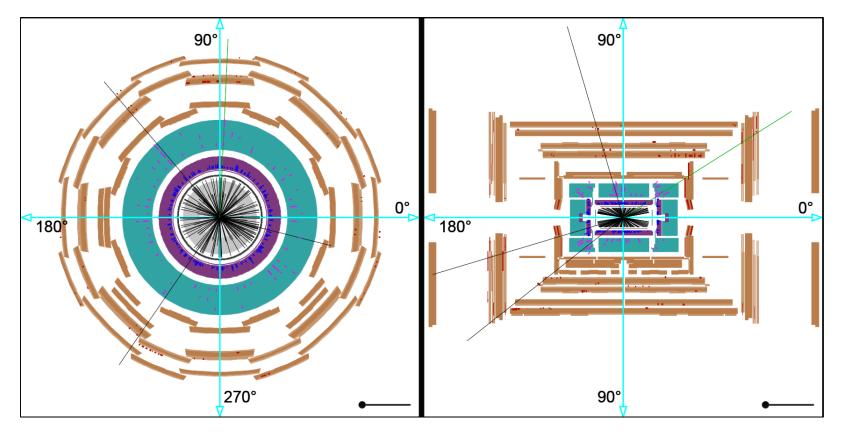
Measurement for Masterclass-in-a-box Data Set 2



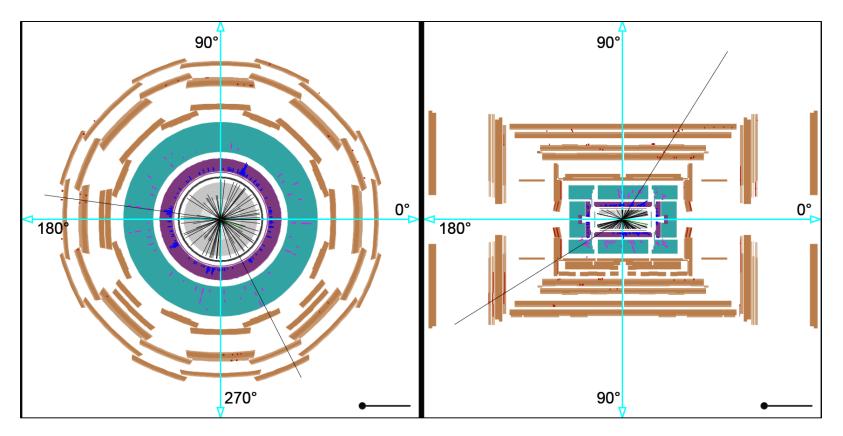
z-y view: measure $\boldsymbol{\theta}$



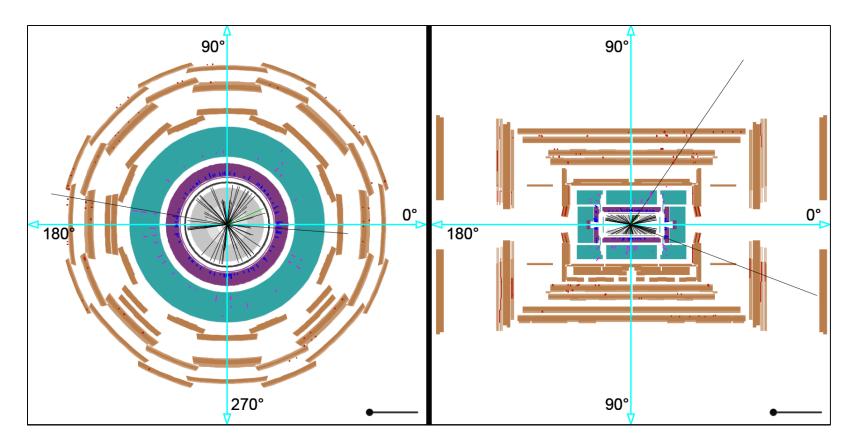
z-y view: measure θ



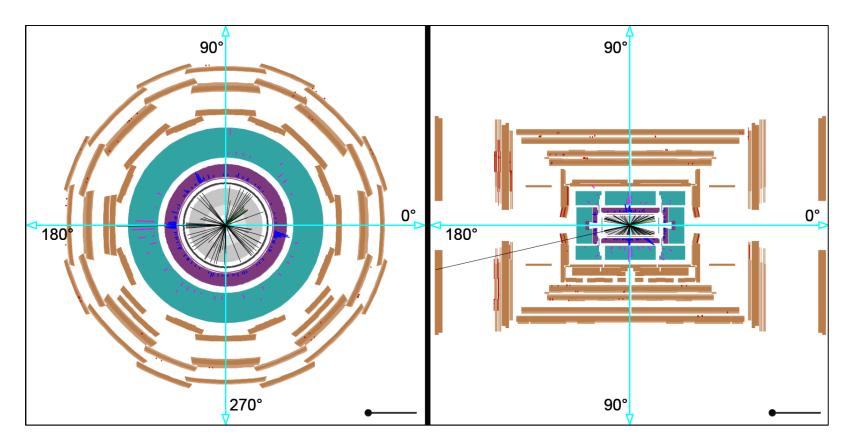
z-y view: measure θ



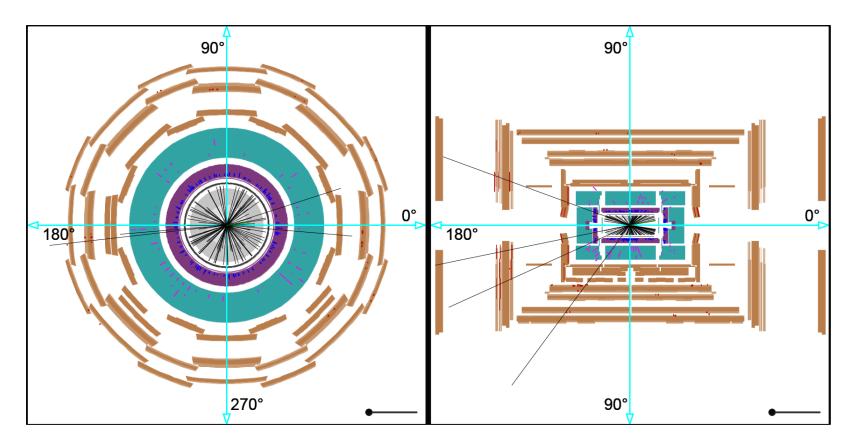
z-y view: measure θ



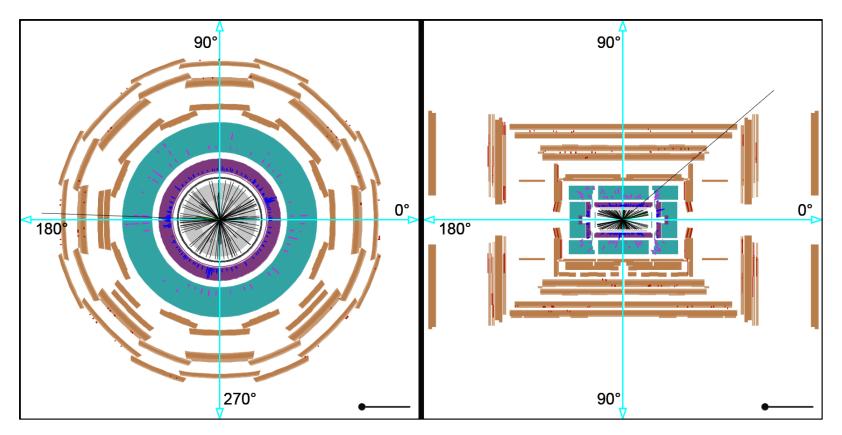
z-y view: measure θ



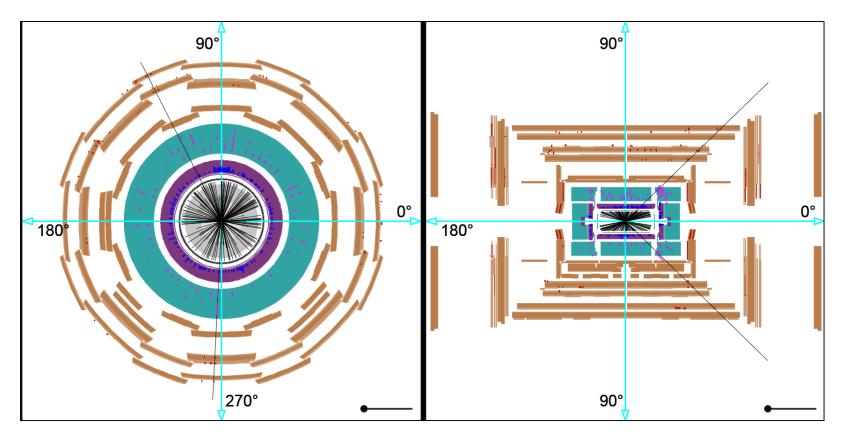
z-y view: measure θ



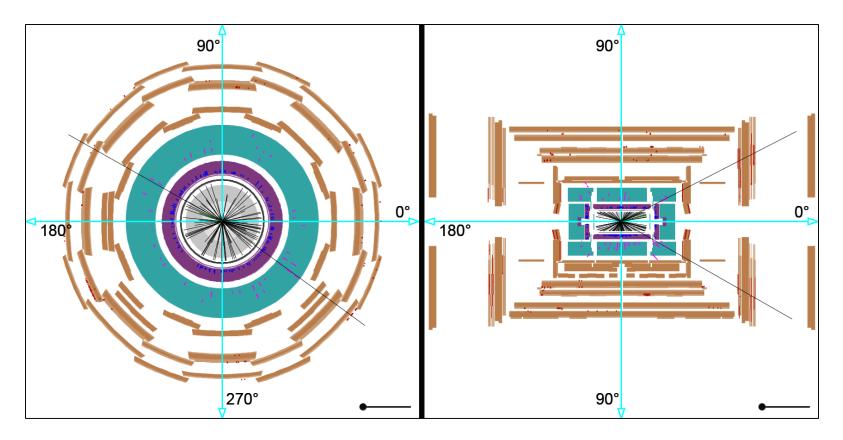
z-y view: measure θ



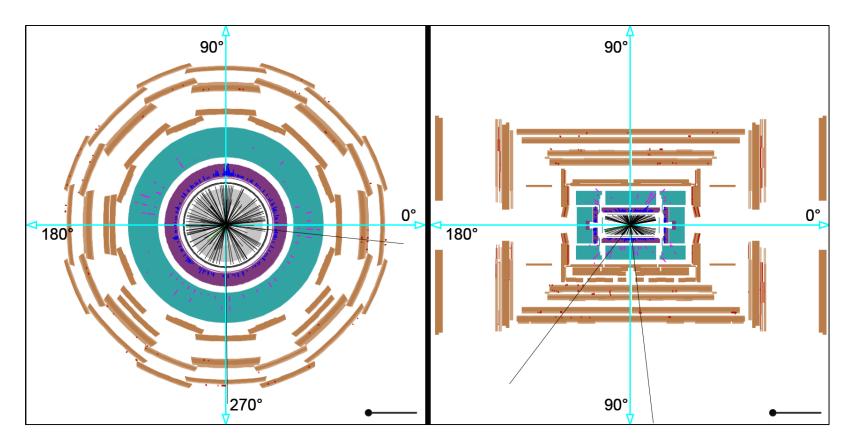
z-y view: measure $\boldsymbol{\theta}$



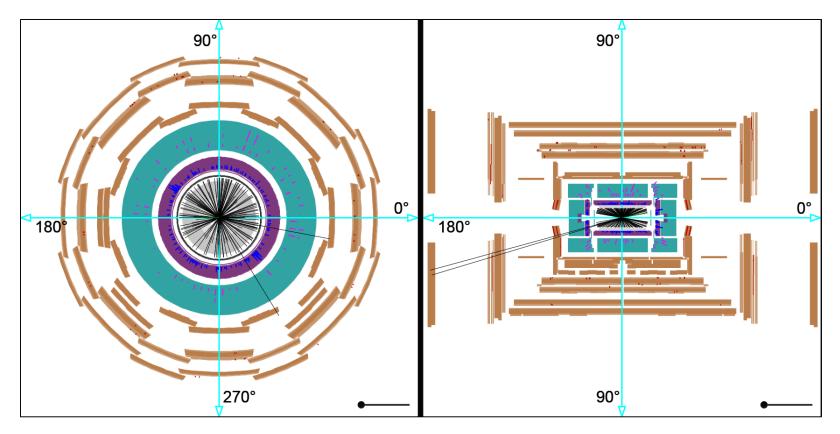
z-y view: measure $\boldsymbol{\theta}$



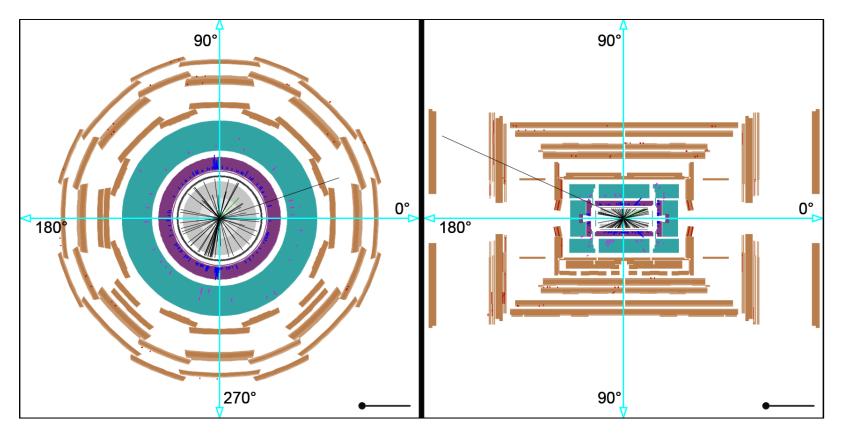
z-y view: measure θ



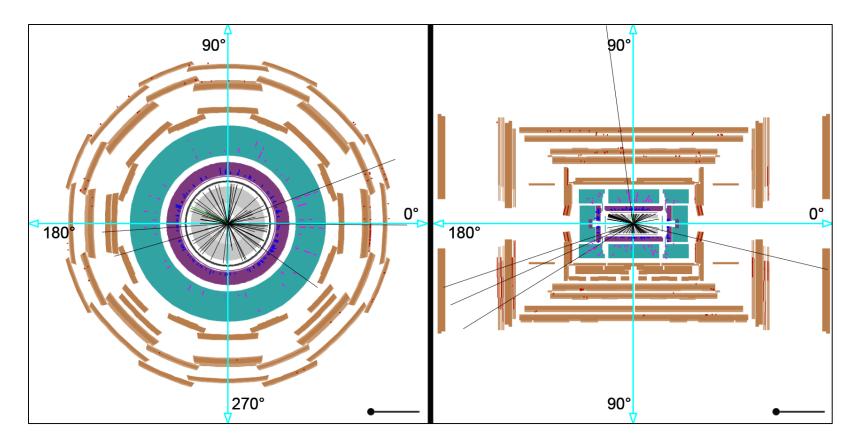
z-y view: measure θ



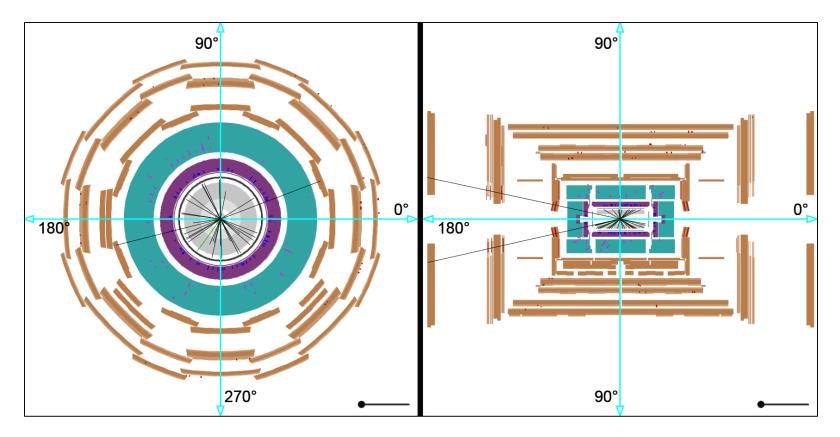
z-y view: measure θ



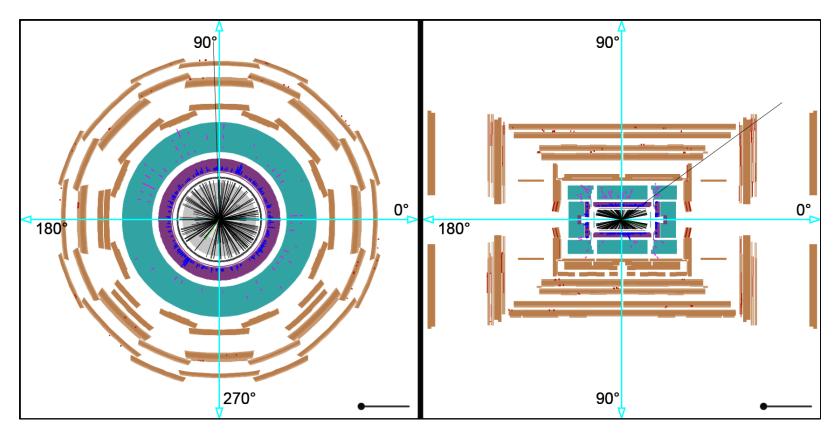
z-y view: measure θ



z-y view: measure heta

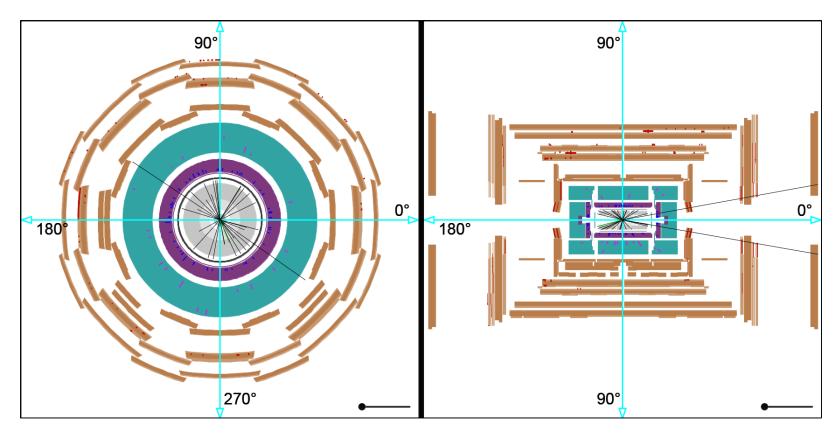


z-y view: measure $\boldsymbol{\theta}$

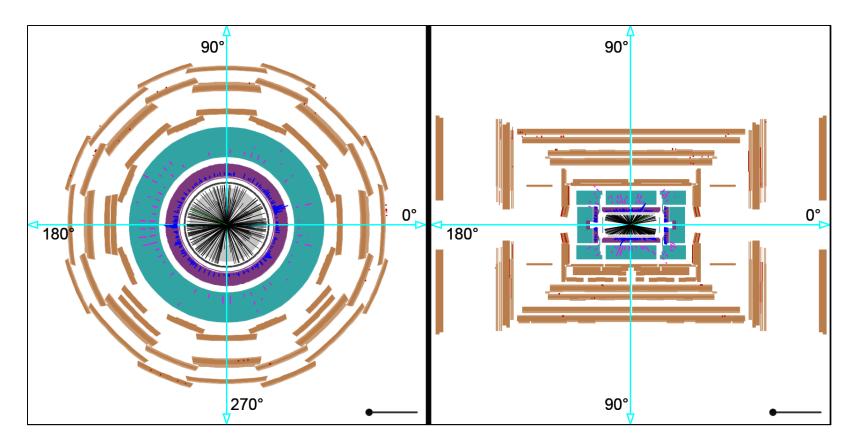


x-y view: measure ϕ

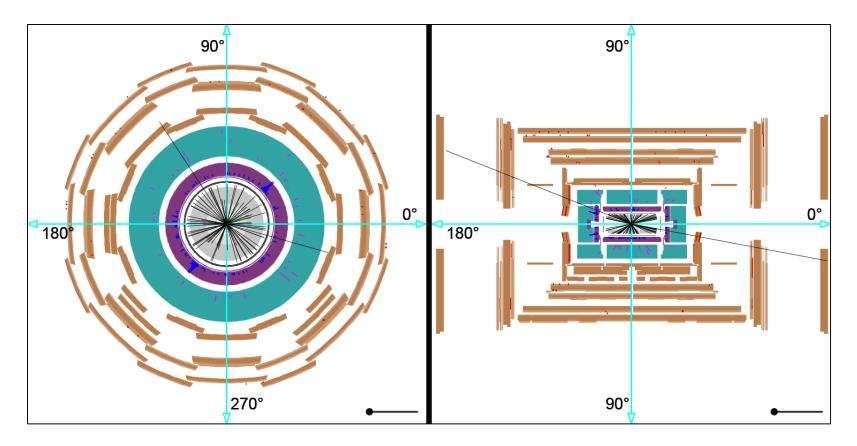
z-y view: measure $\boldsymbol{\theta}$



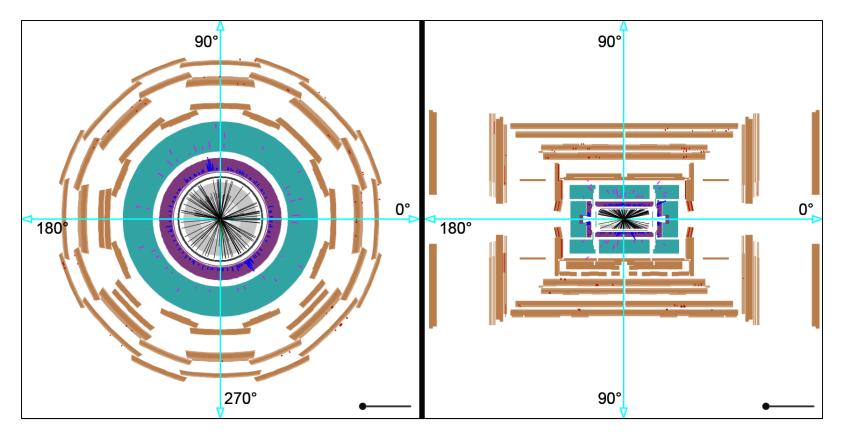
z-y view: measure θ



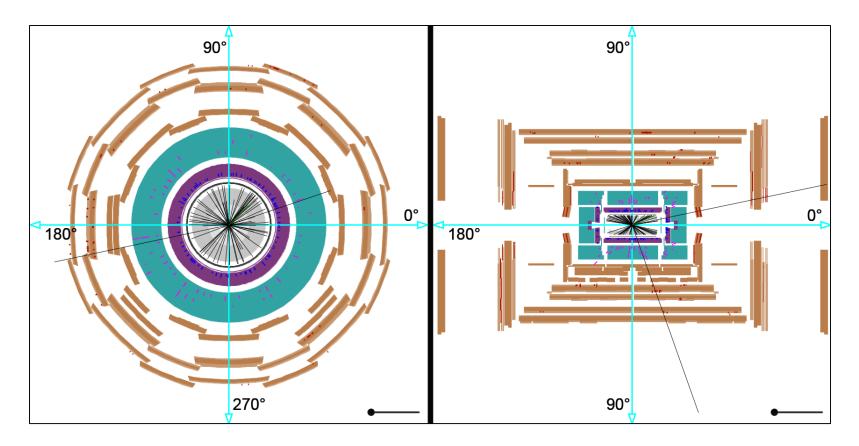
z-y view: measure θ



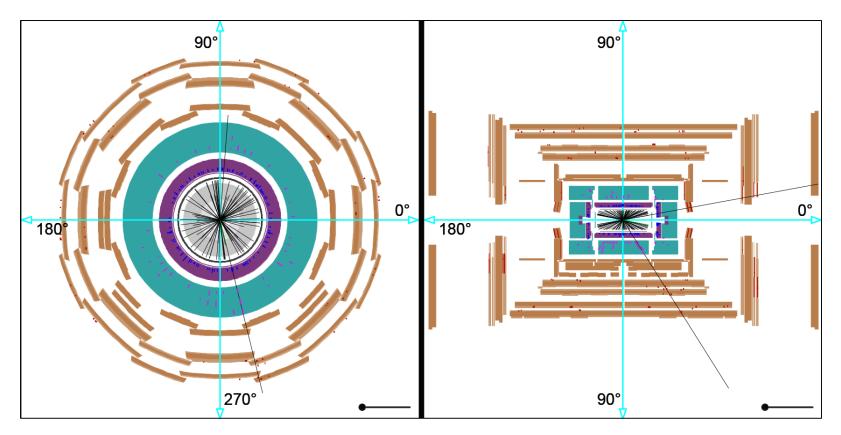
z-y view: measure θ



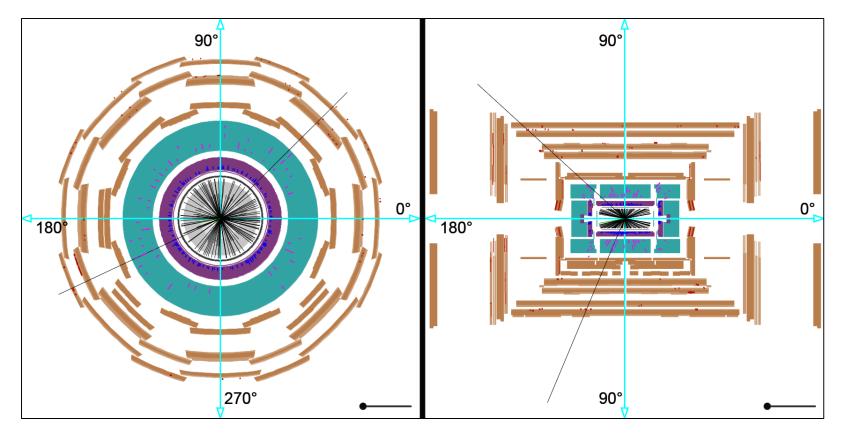
z-y view: measure θ



z-y view: measure θ

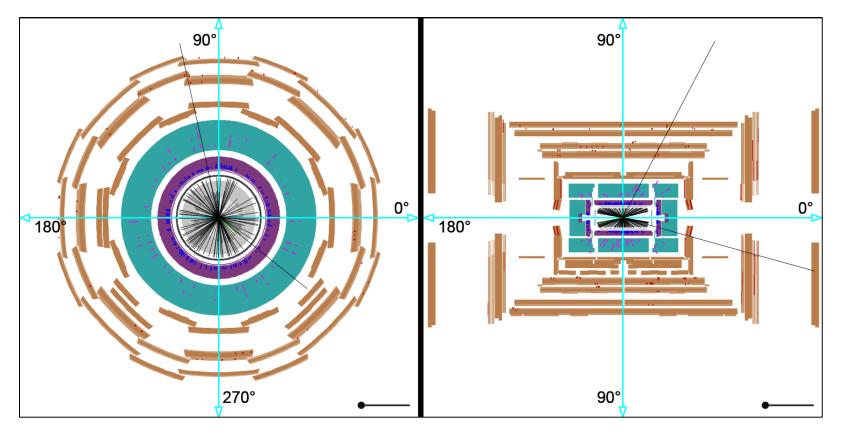


z-y view: measure θ

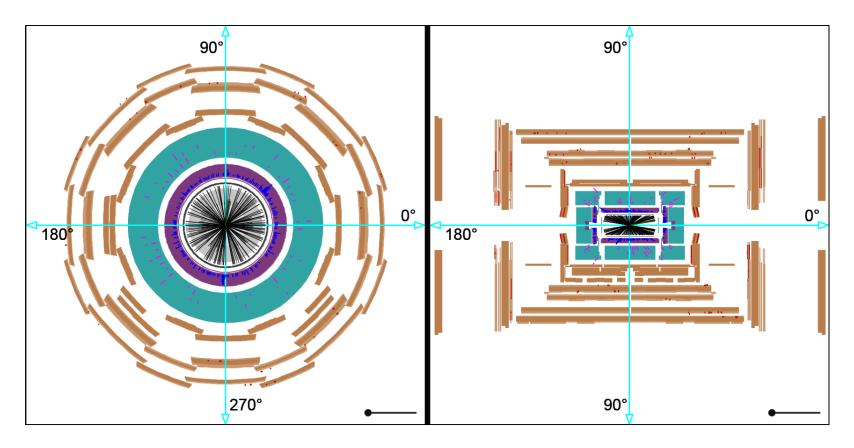


x-y view: measure ϕ

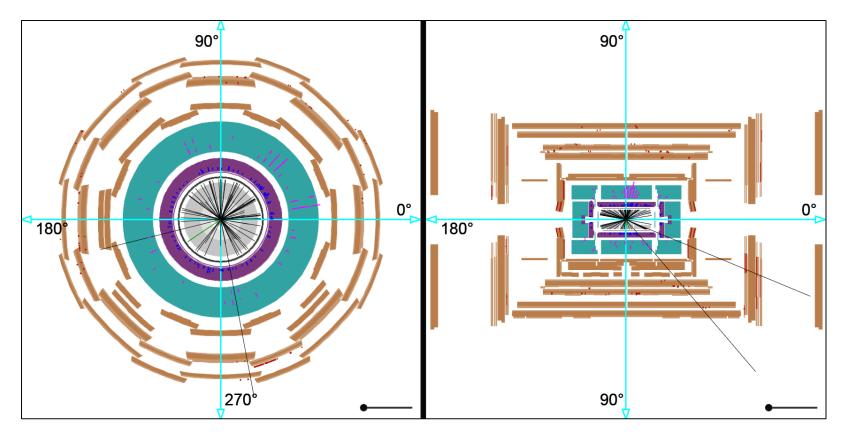
z-y view: measure $\boldsymbol{\theta}$



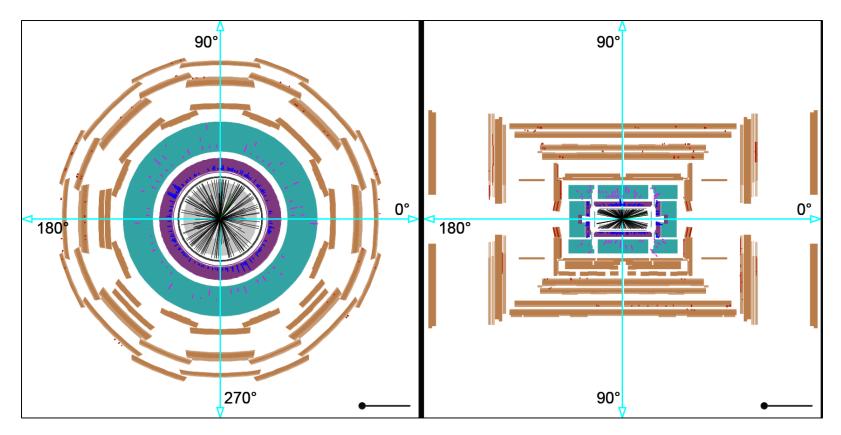
z-y view: measure θ



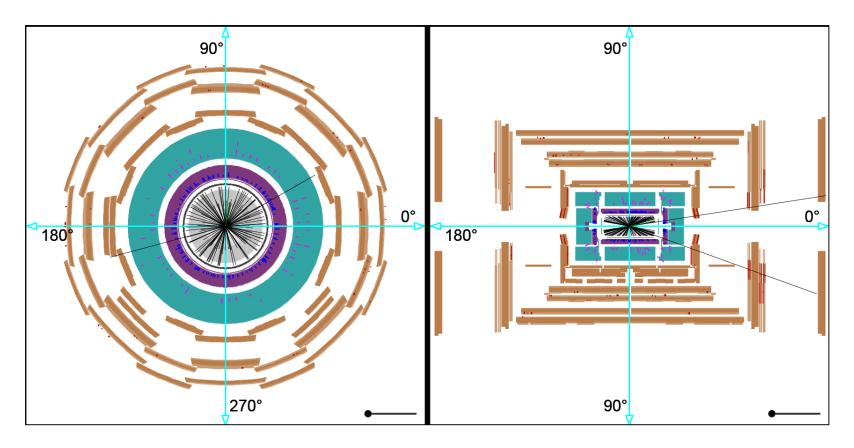
z-y view: measure $\boldsymbol{\theta}$



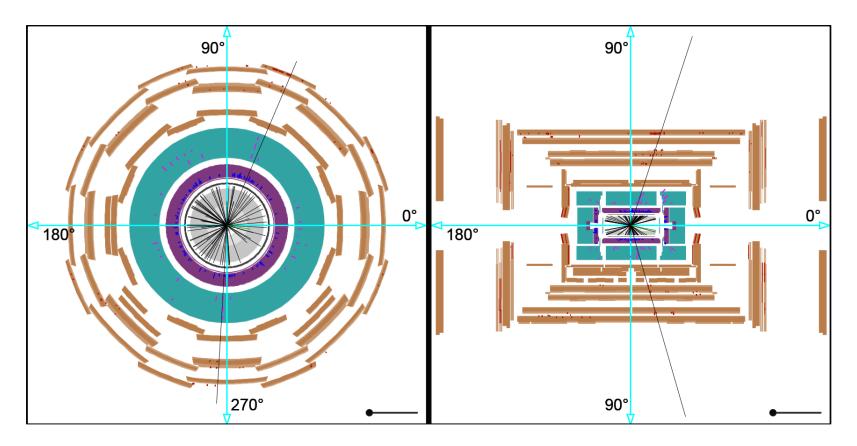
z-y view: measure $\boldsymbol{\theta}$



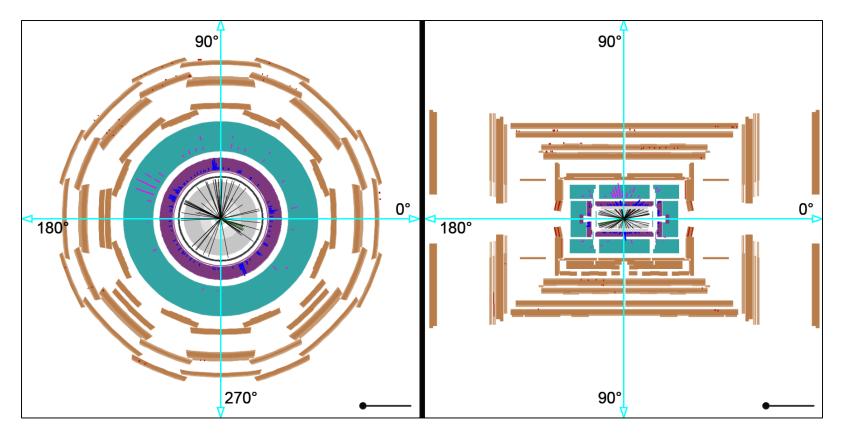
z-y view: measure $\boldsymbol{\theta}$



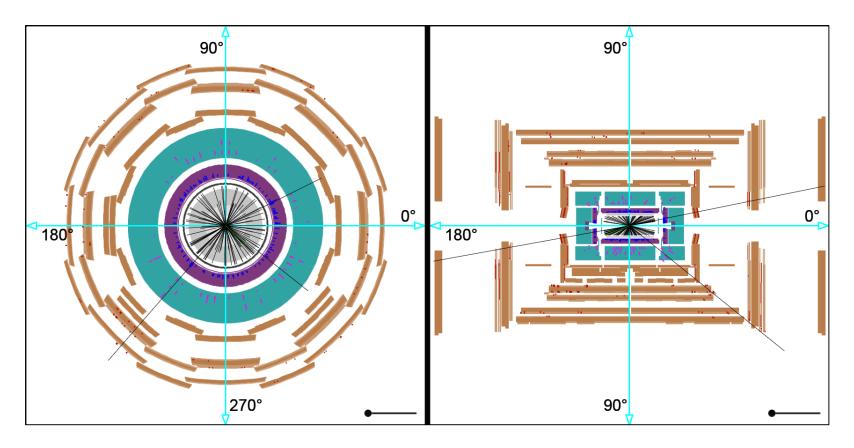
z-y view: measure $\boldsymbol{\theta}$



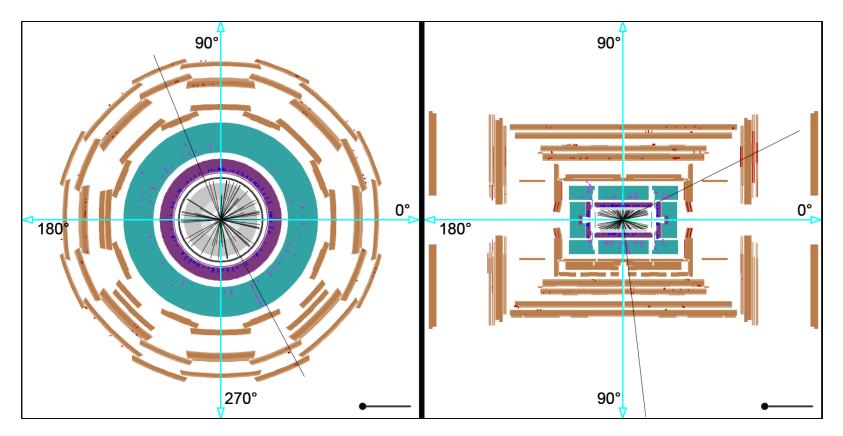
z-y view: measure $\boldsymbol{\theta}$



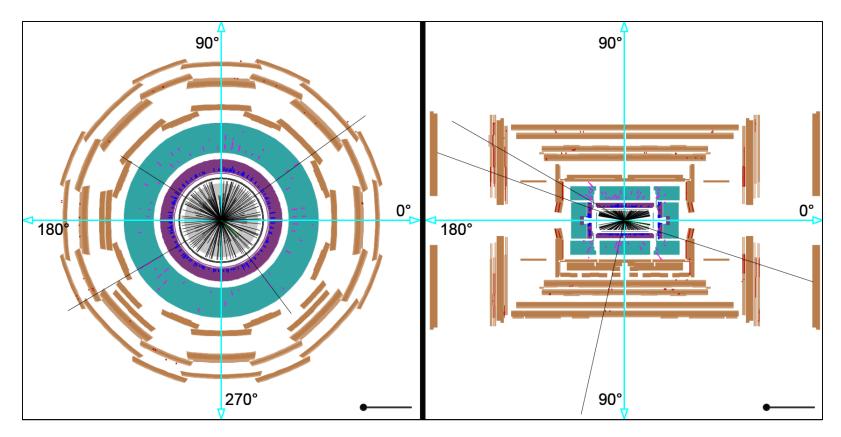
z-y view: measure θ



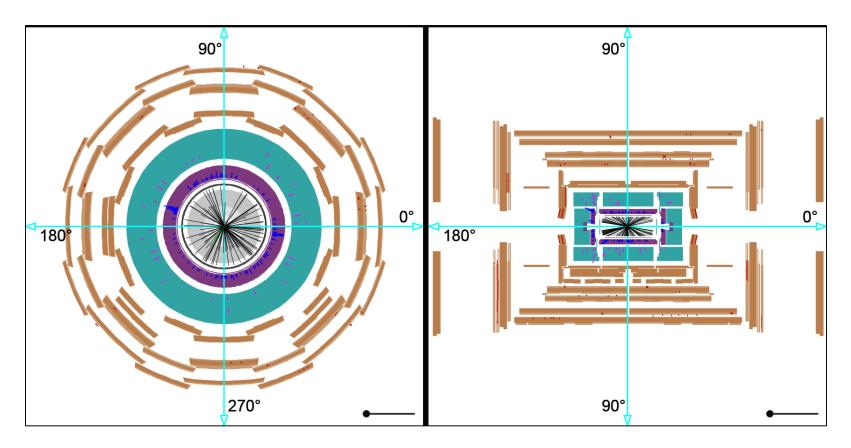
z-y view: measure $\boldsymbol{\theta}$



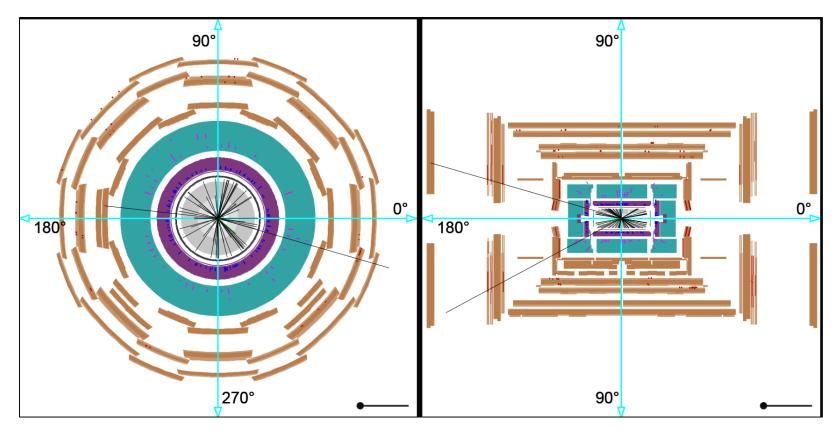
z-y view: measure θ



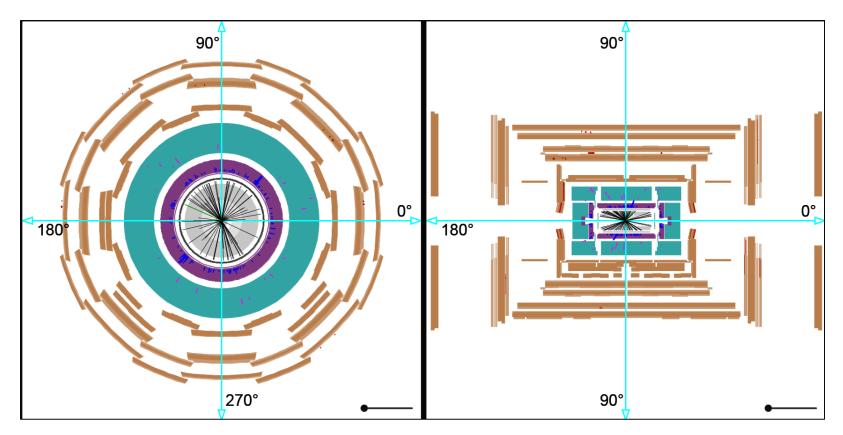
z-y view: measure $\boldsymbol{\theta}$



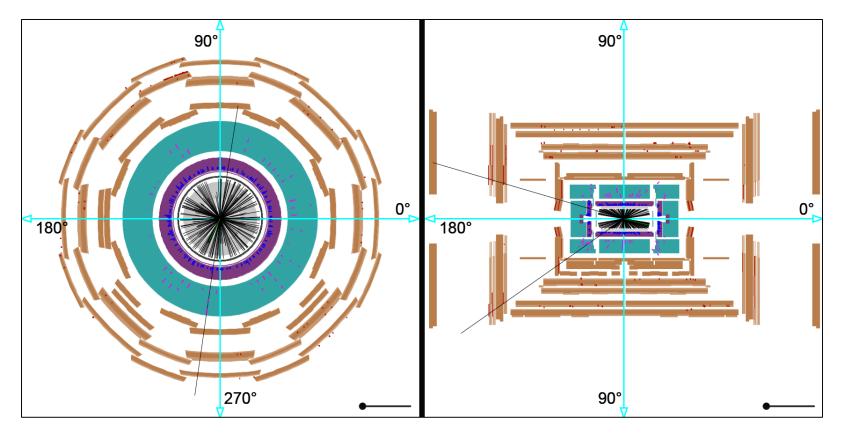
z-y view: measure $\boldsymbol{\theta}$



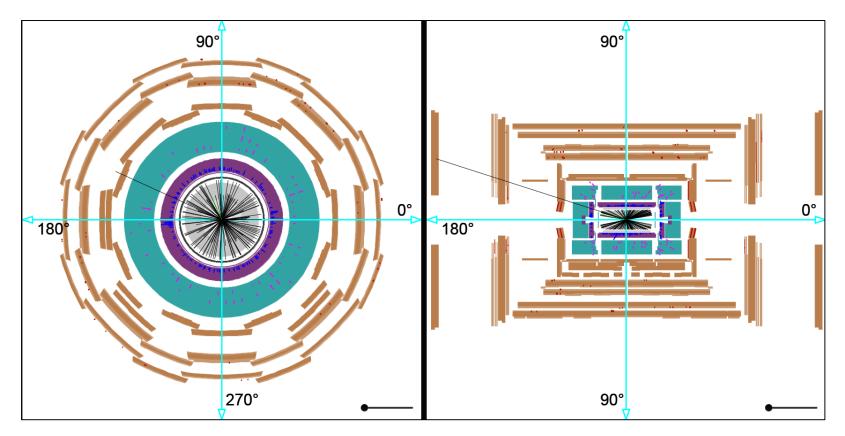
z-y view: measure θ



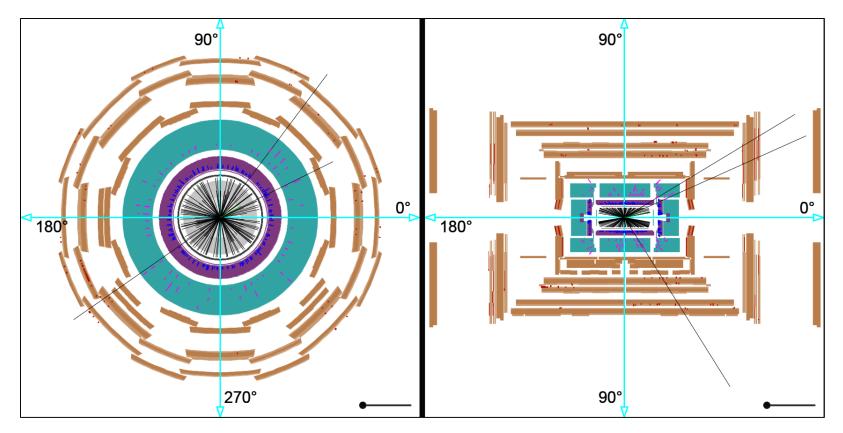
z-y view: measure θ



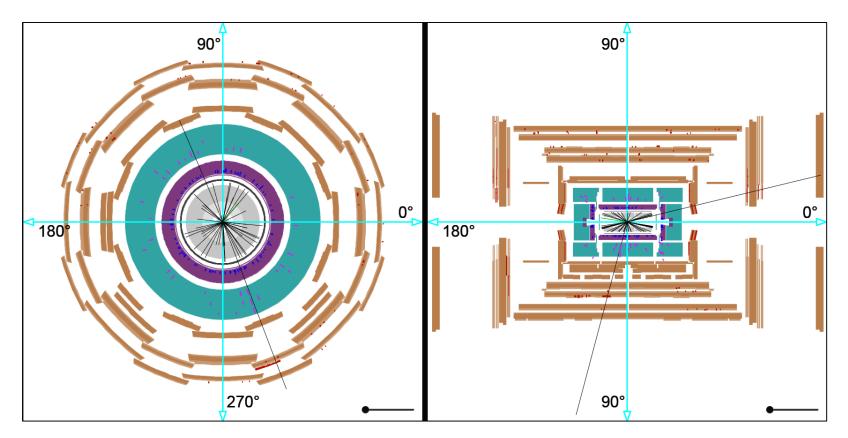
z-y view: measure θ



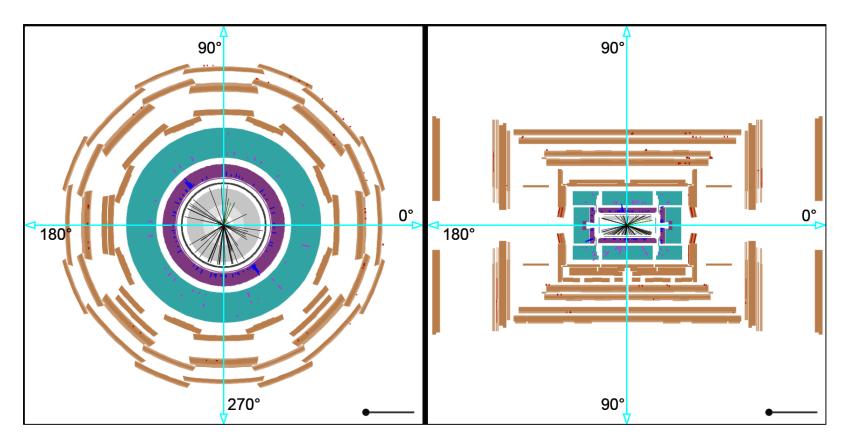
z-y view: measure heta



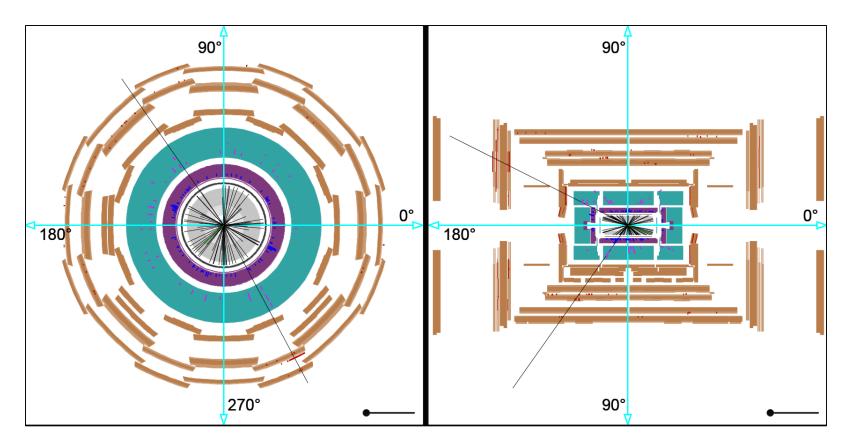
z-y view: measure θ



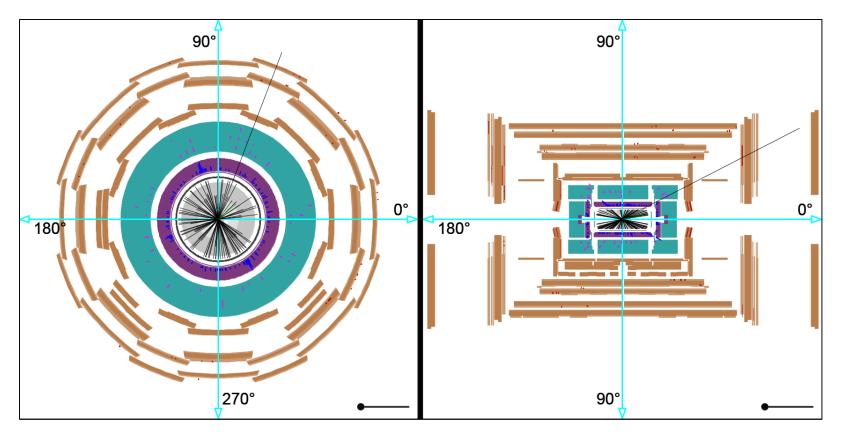
z-y view: measure $\boldsymbol{\theta}$



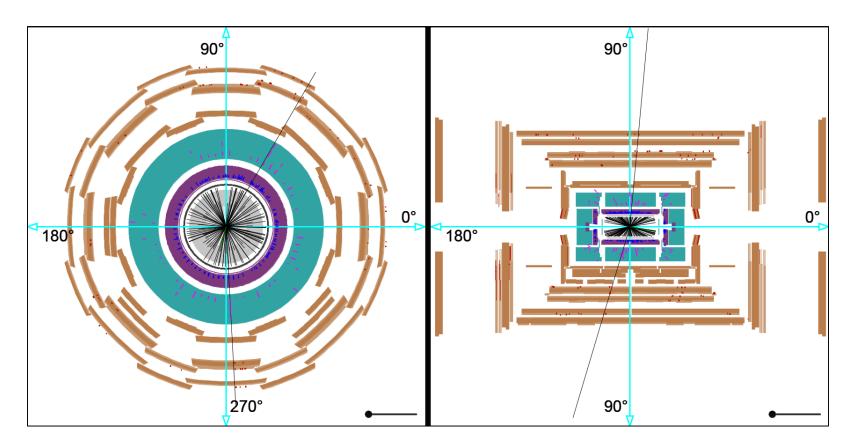
z-y view: measure θ



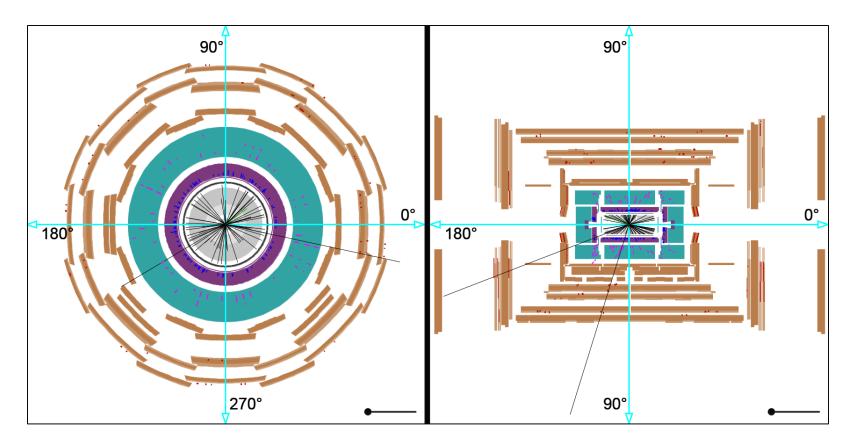
z-y view: measure θ



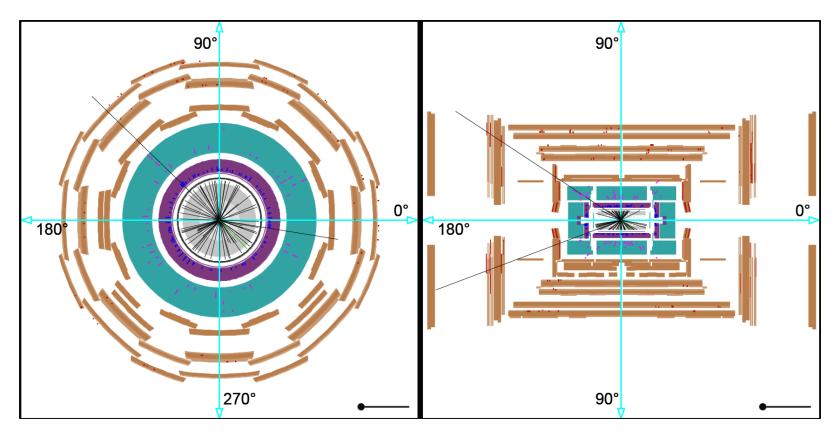
z-y view: measure θ



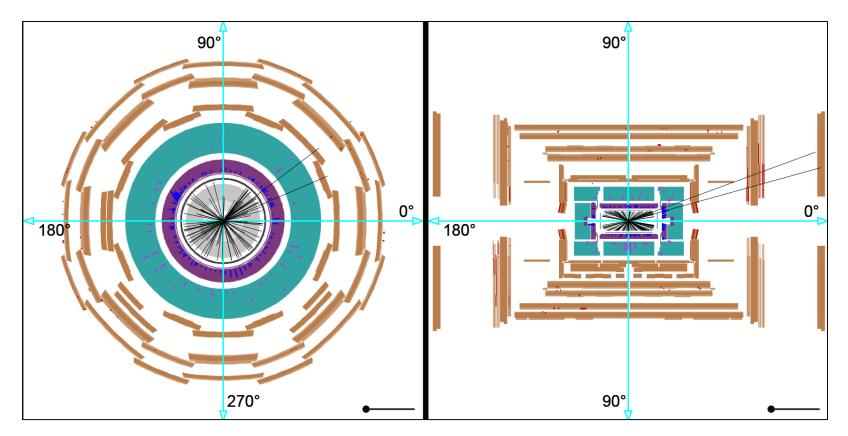
z-y view: measure θ



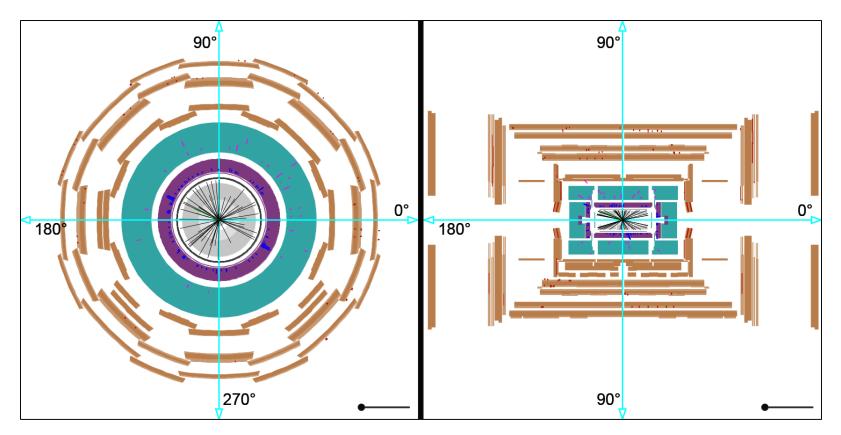
z-y view: measure θ



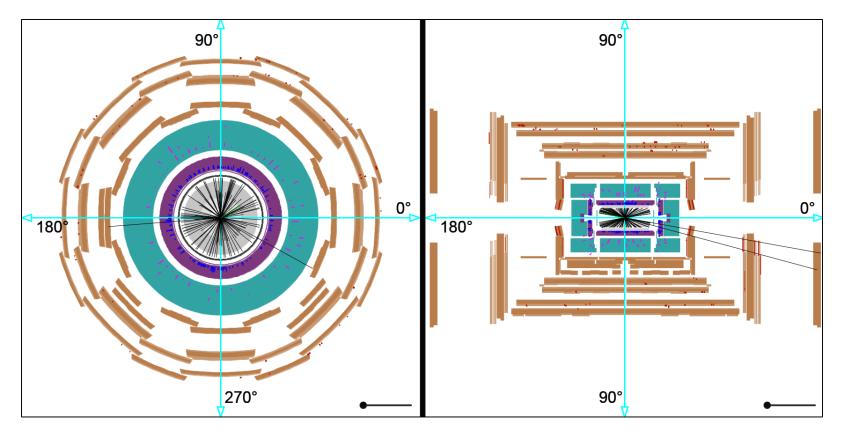
z-y view: measure θ



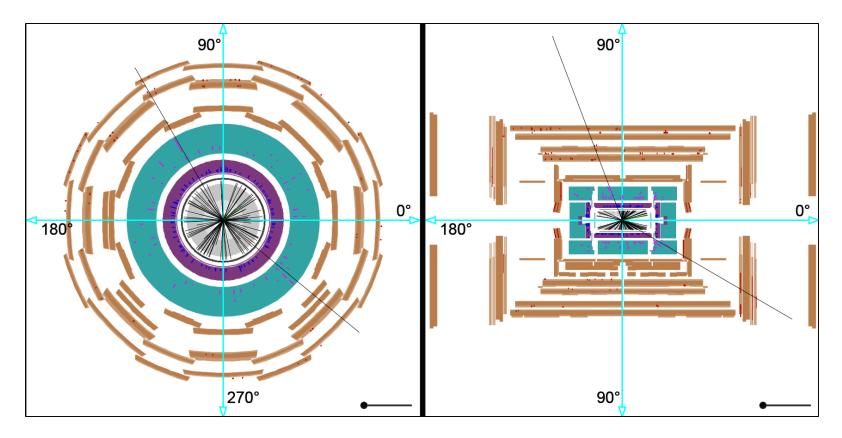
z-y view: measure heta



z-y view: measure θ



z-y view: measure θ



z-y view: measure θ