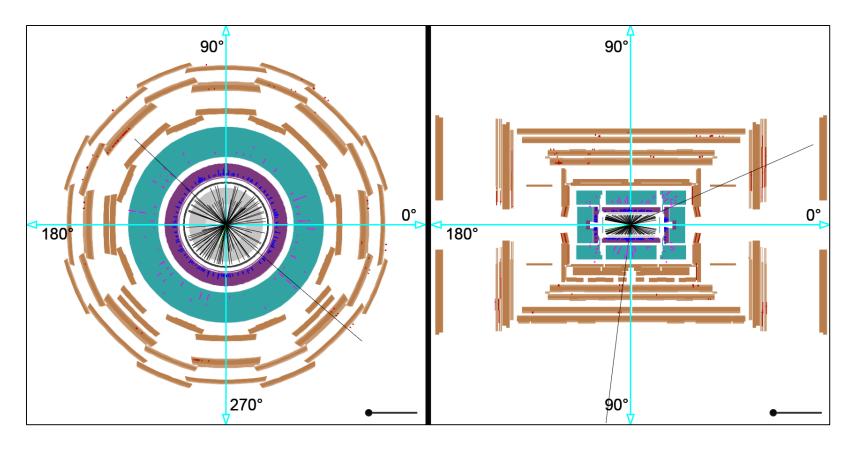
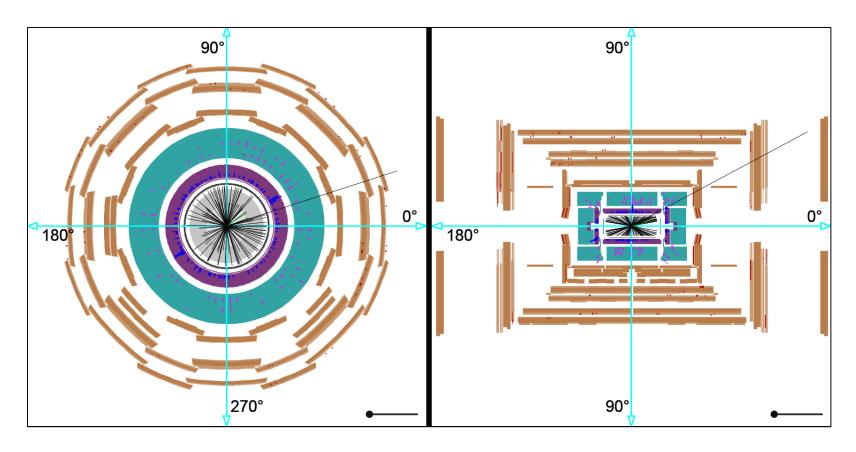
ATLAS-W2D2

Measurement for
Masterclass-in-a-box
Data Set 3



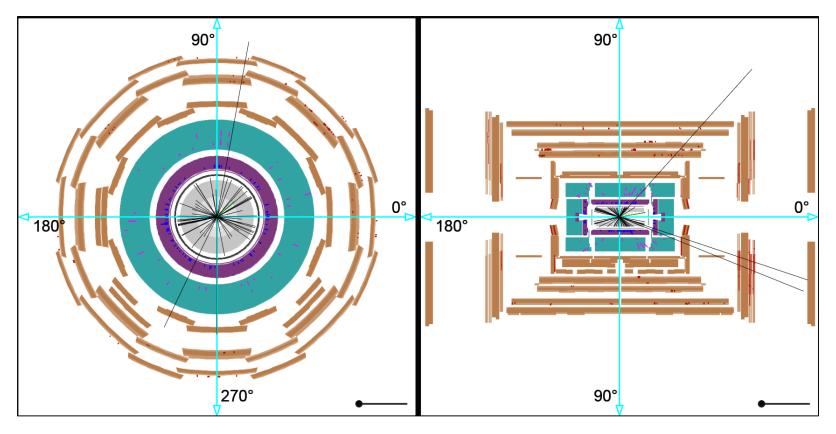
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



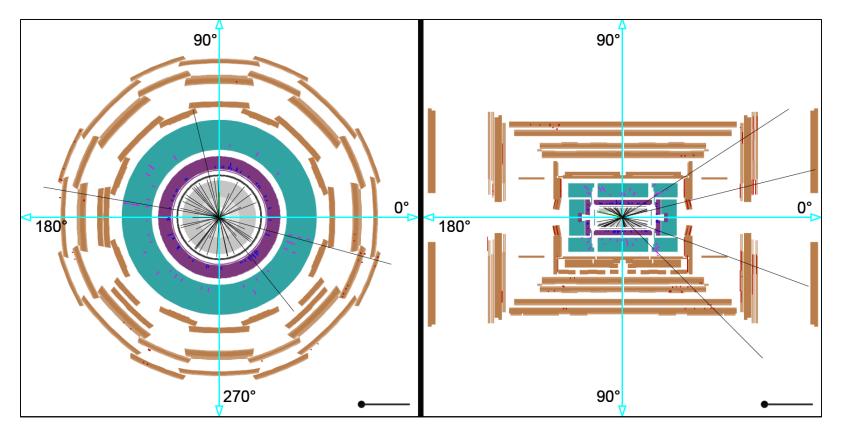
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



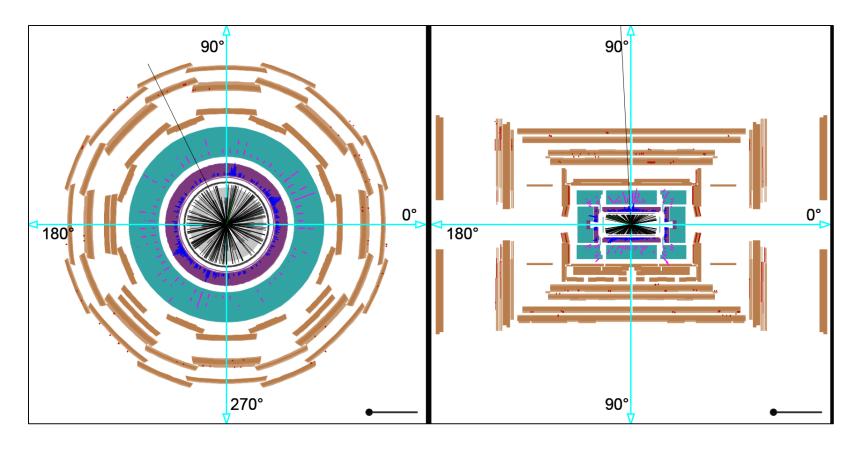
x-y view: measure $\boldsymbol{\varphi}$

z-y view: measure $\boldsymbol{\theta}$



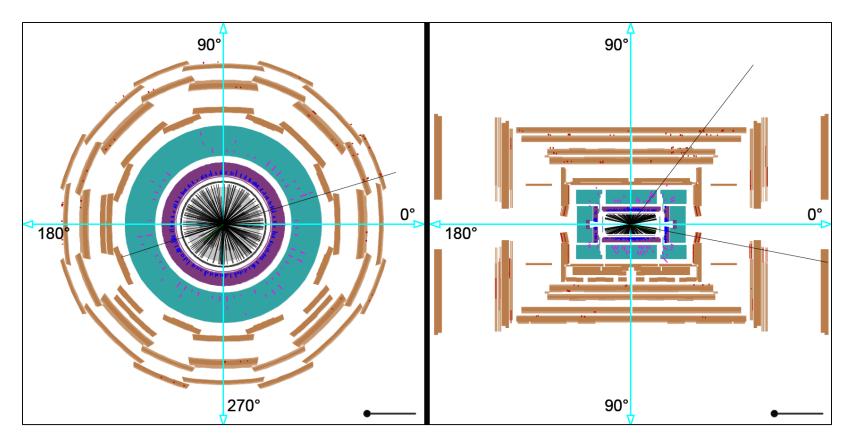
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



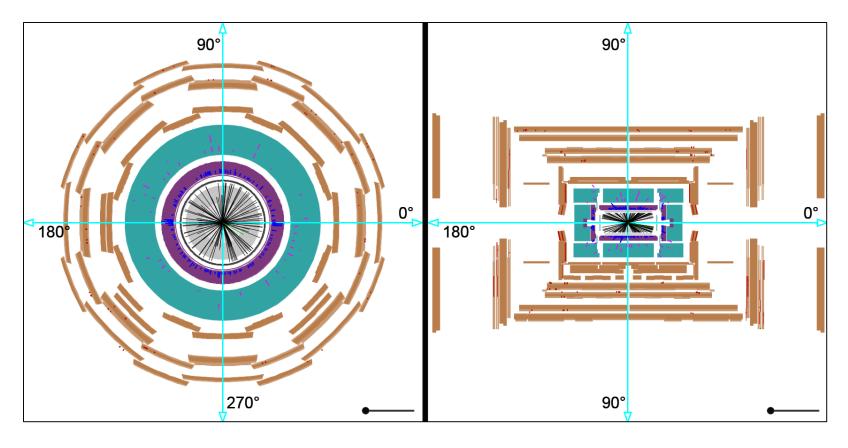
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



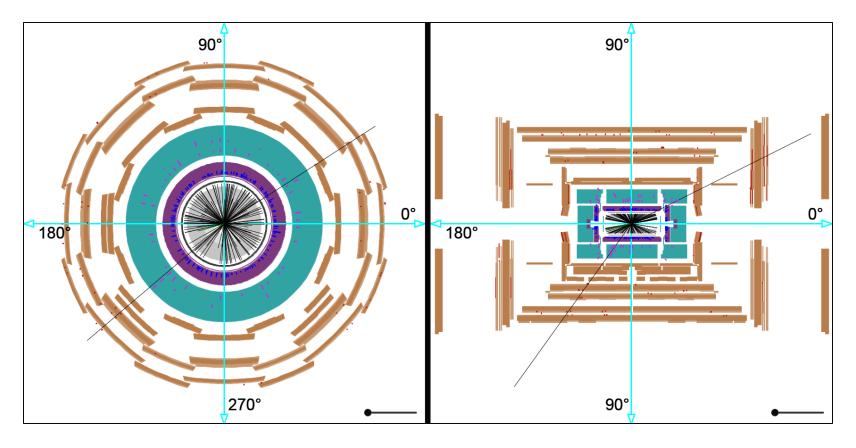
x-y view: measure φ

z-y view: measure $\boldsymbol{\theta}$



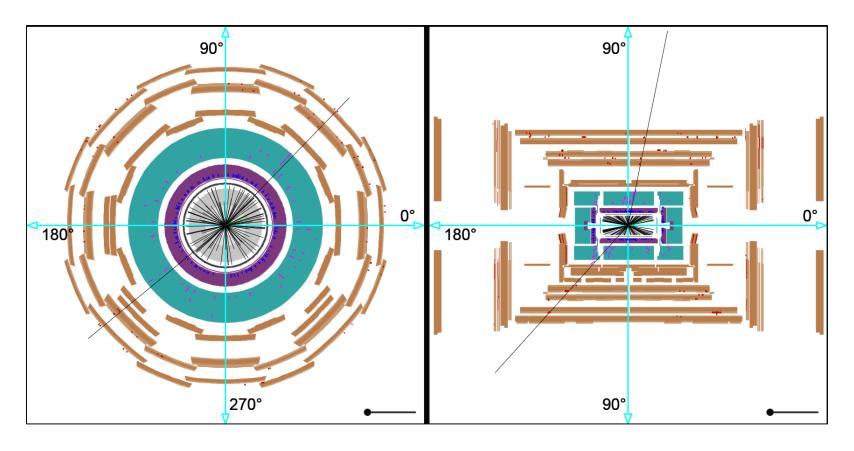
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



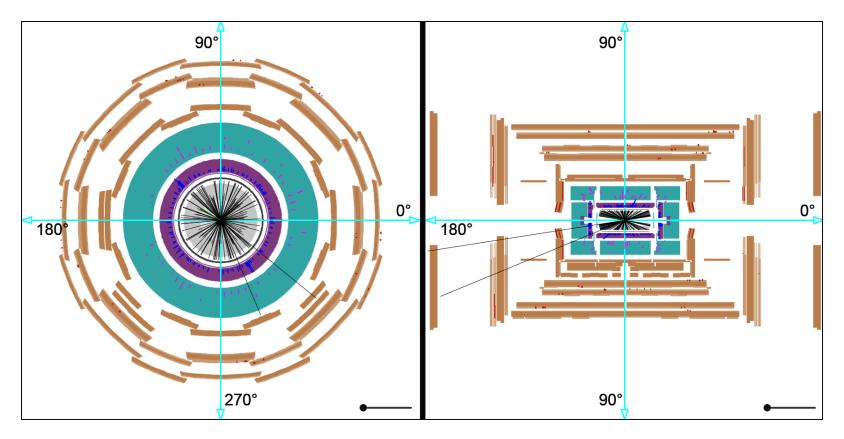
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



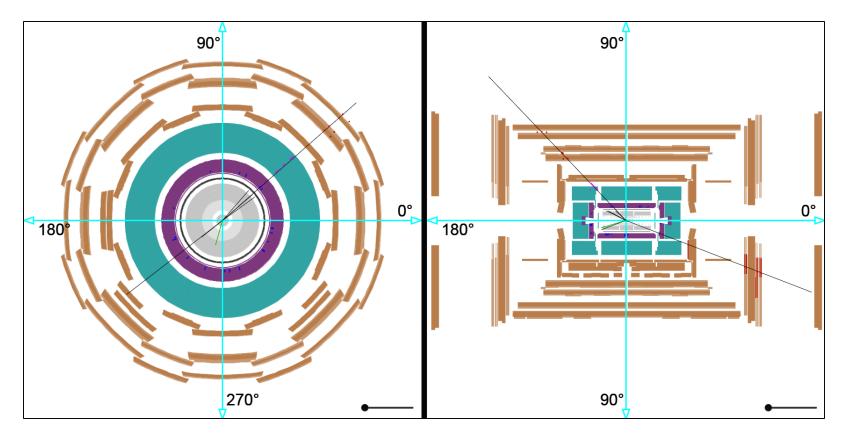
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



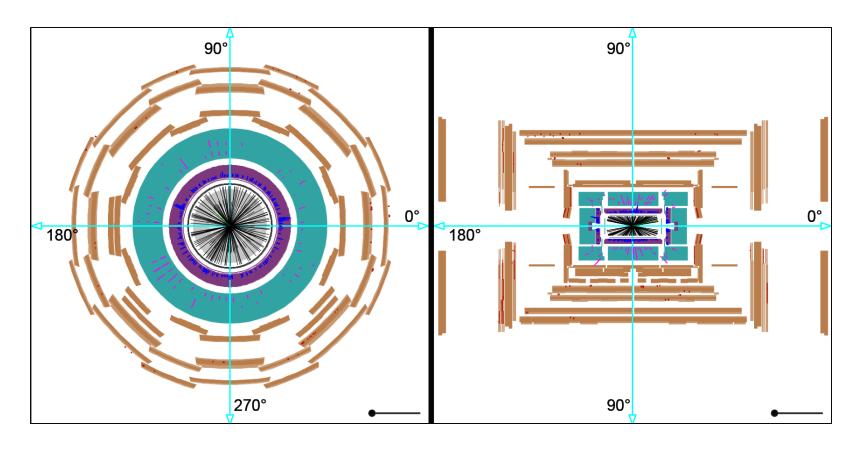
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



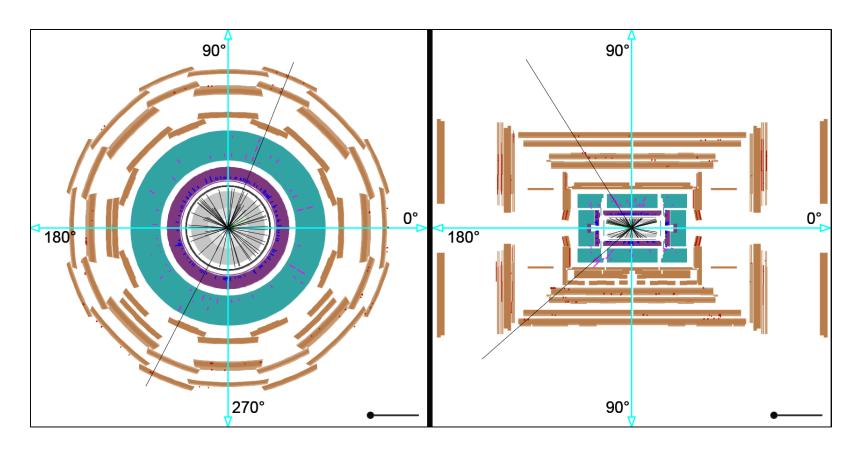
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



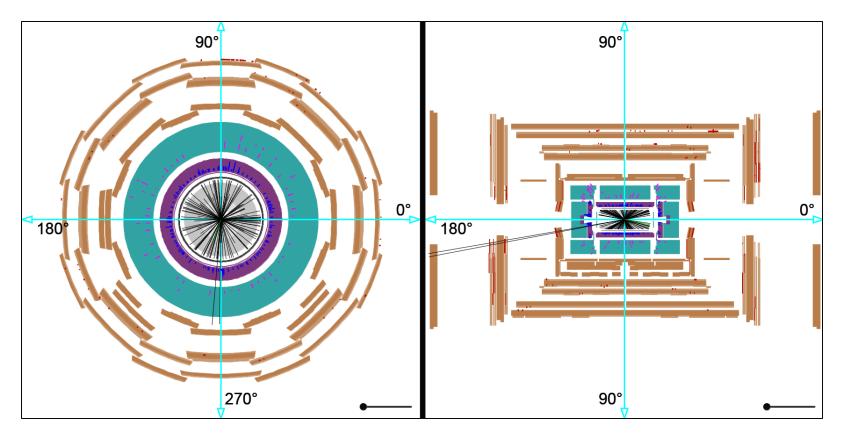
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



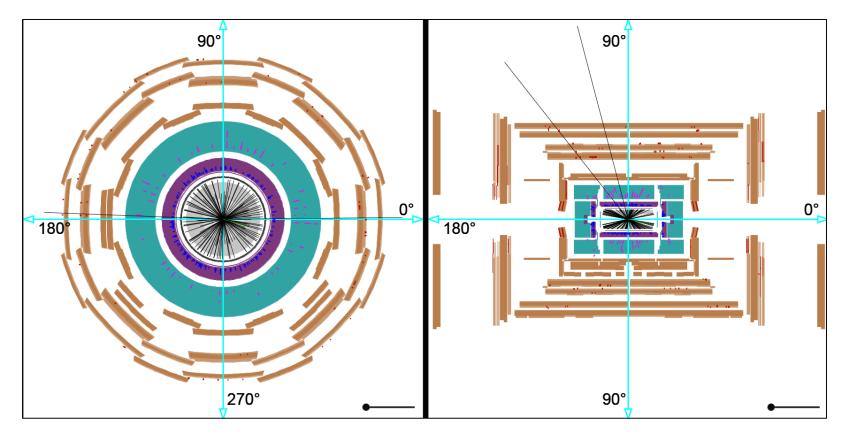
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



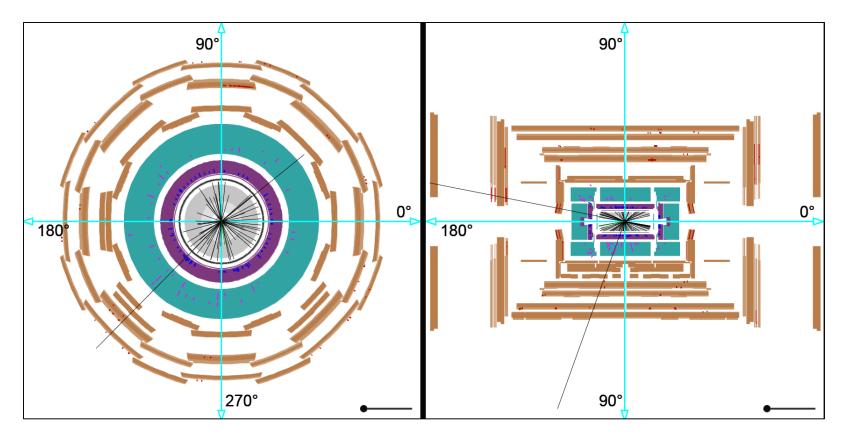
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



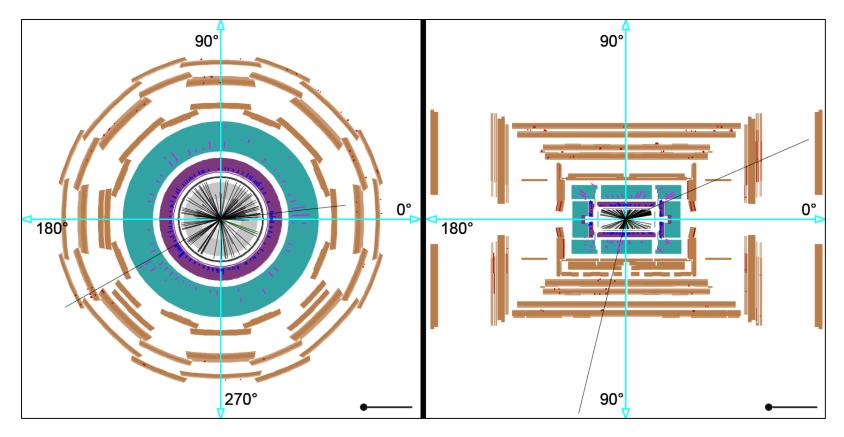
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



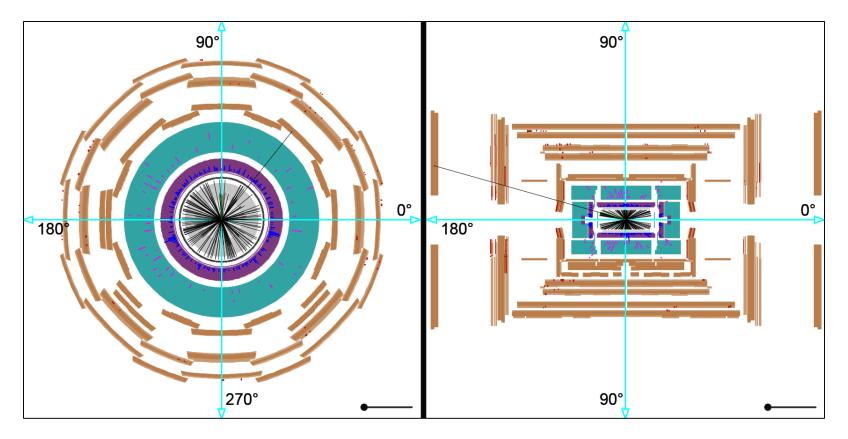
x-y view: measure $\boldsymbol{\varphi}$

z-y view: measure $\boldsymbol{\theta}$



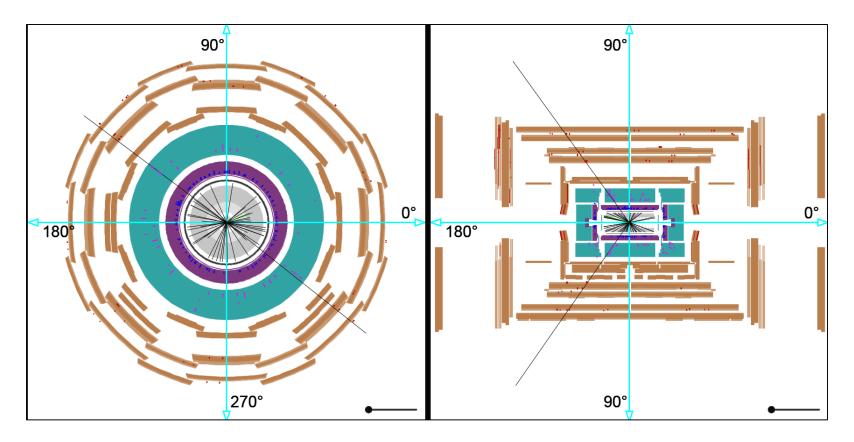
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



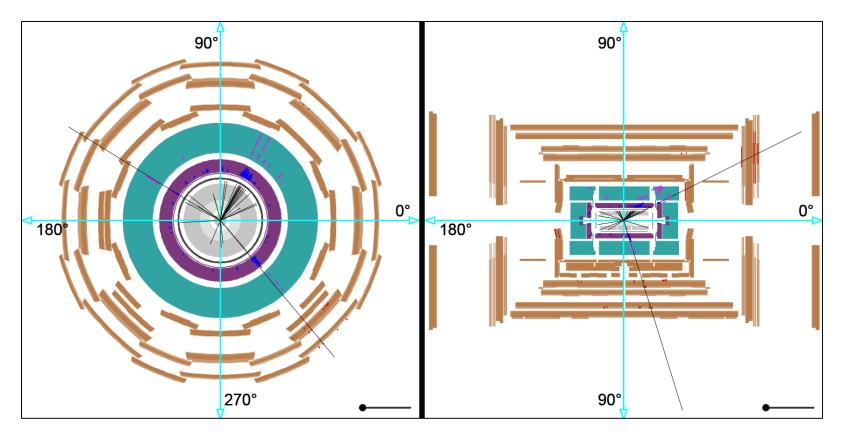
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



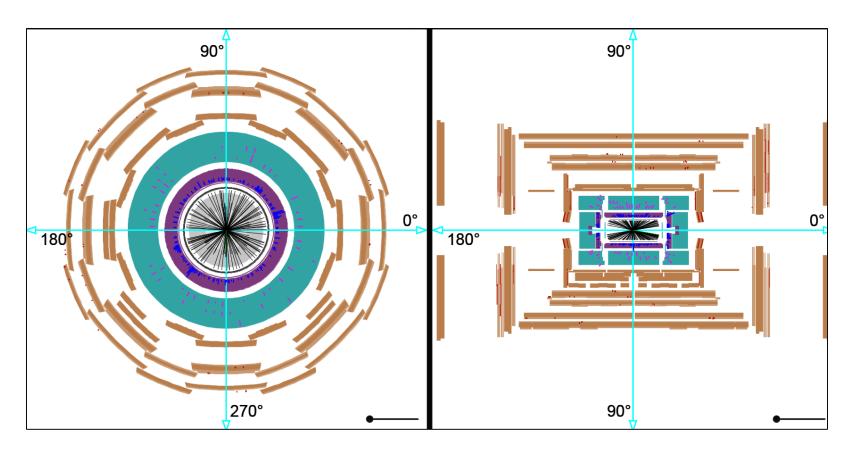
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



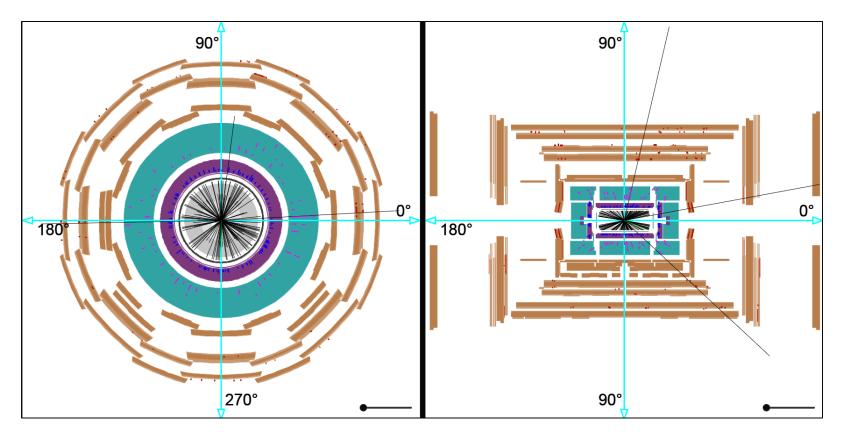
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



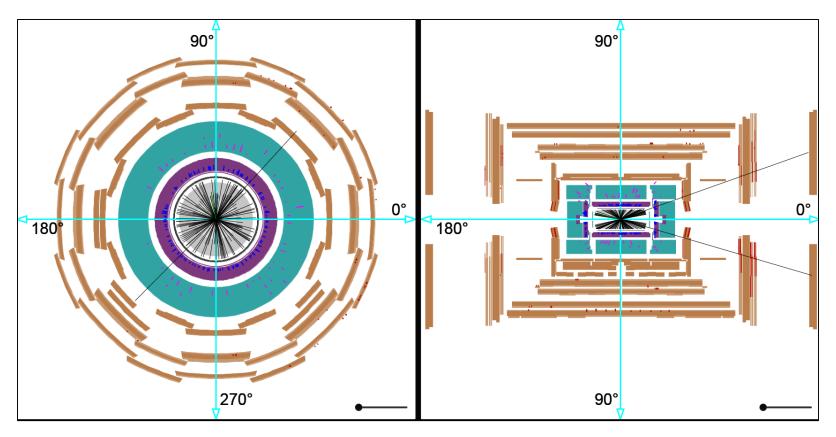
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



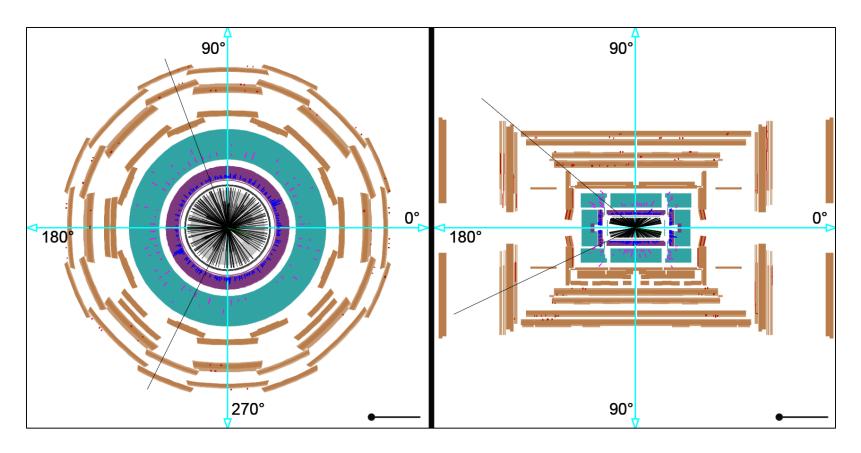
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



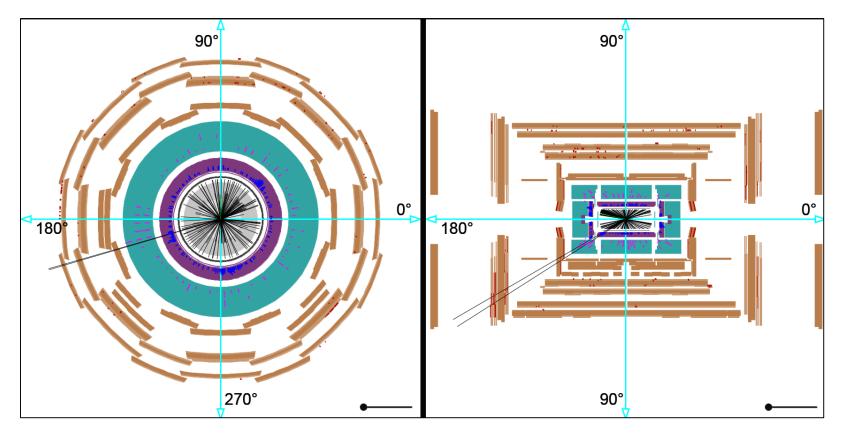
x-y view: measure $\boldsymbol{\varphi}$

z-y view: measure $\boldsymbol{\theta}$



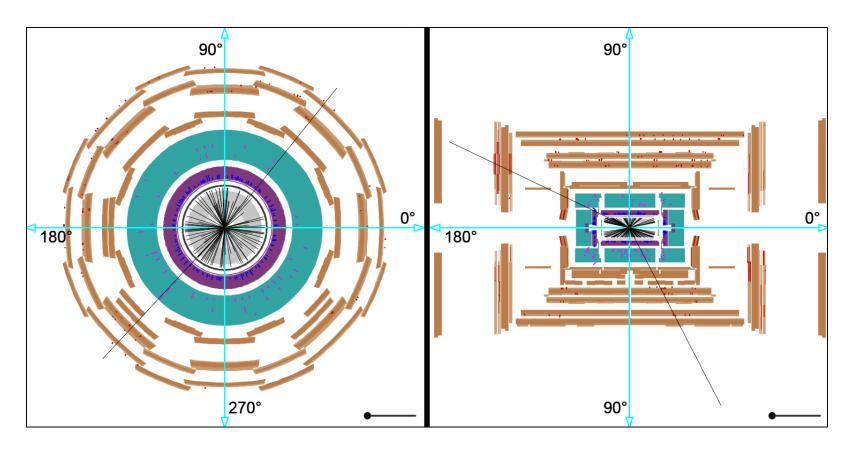
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



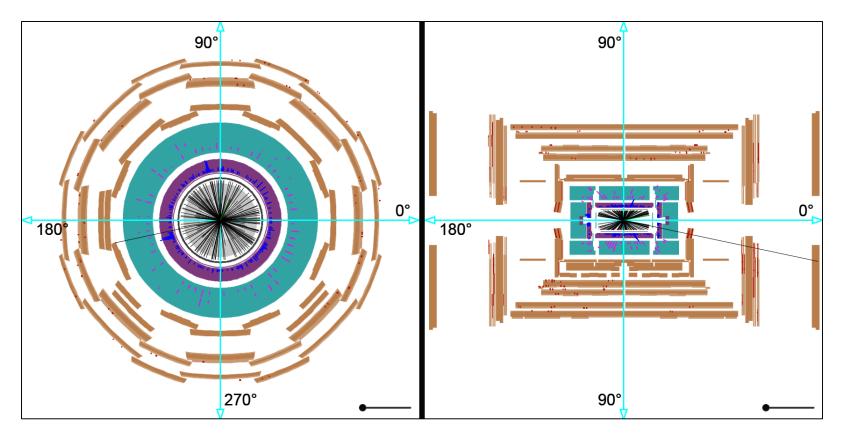
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



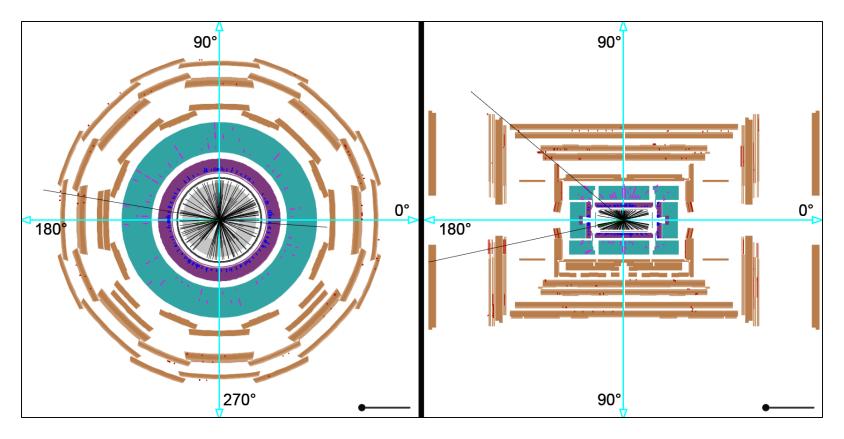
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



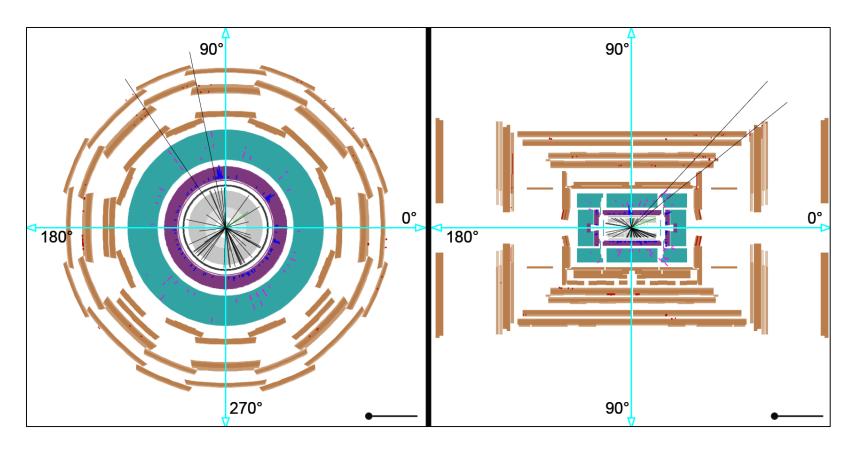
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



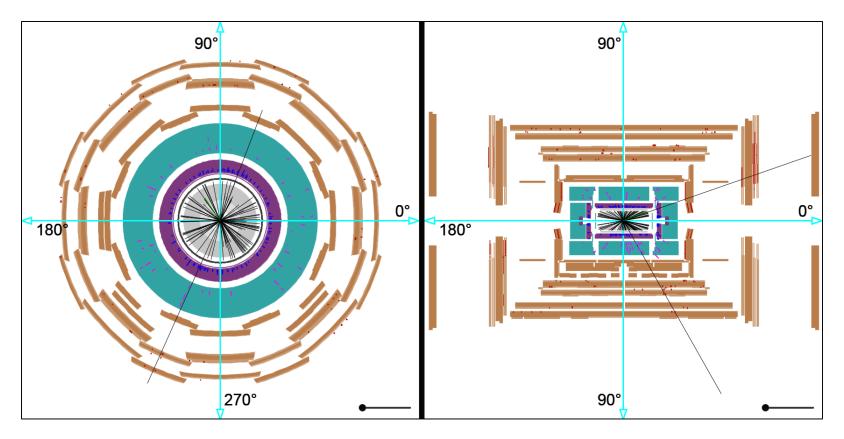
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



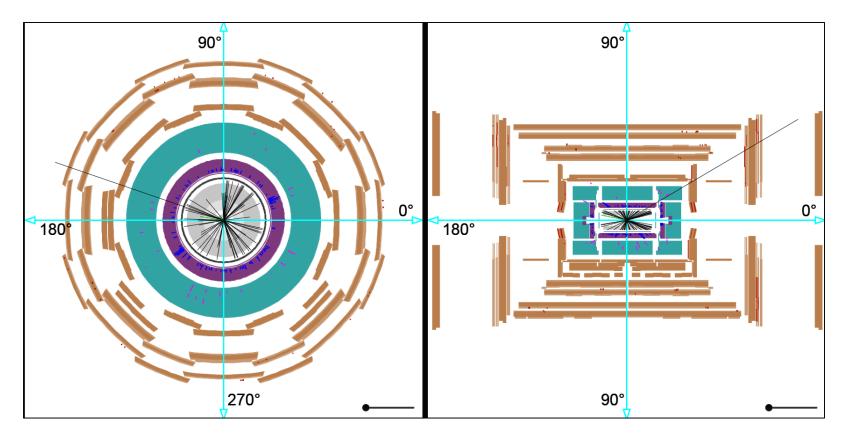
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



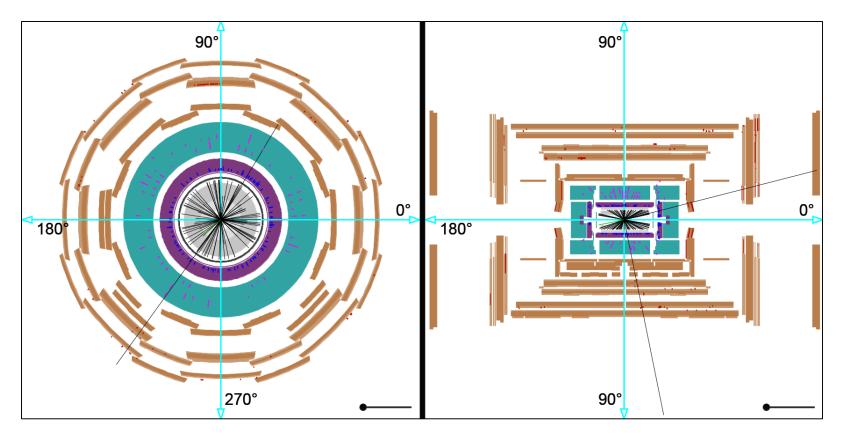
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



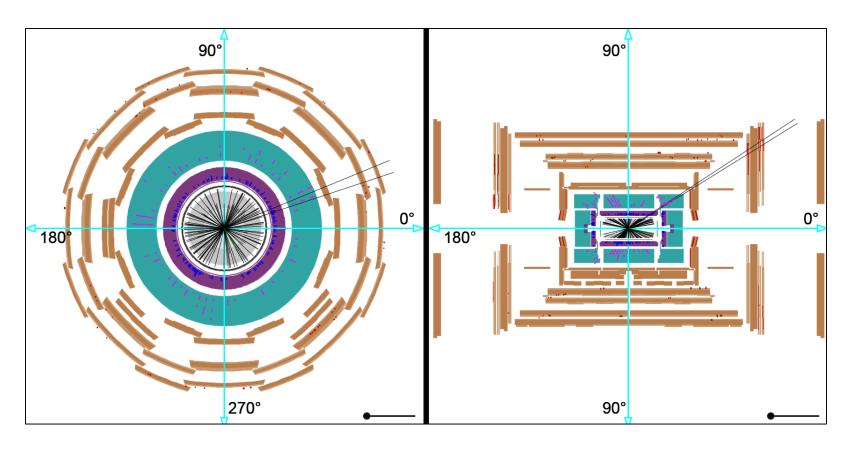
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



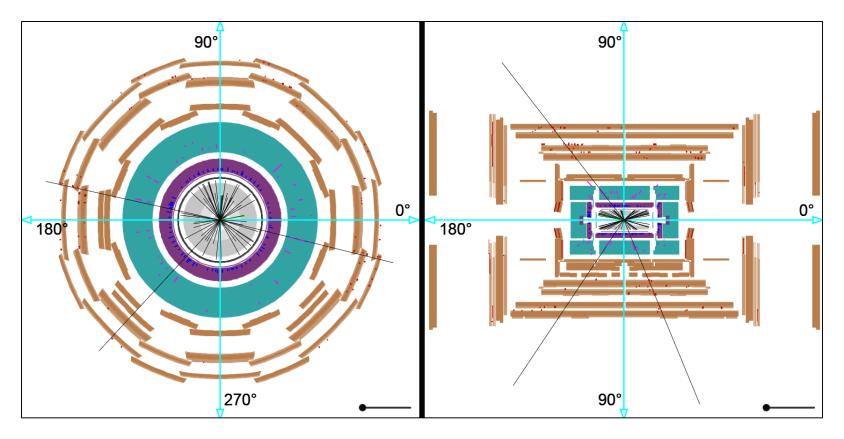
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



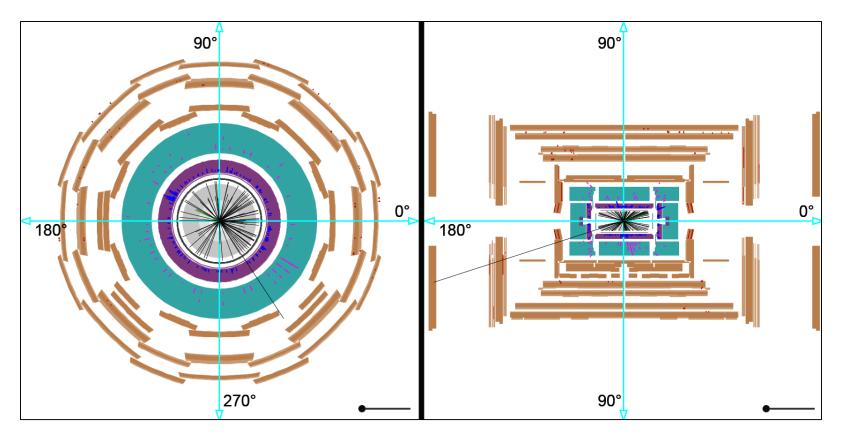
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



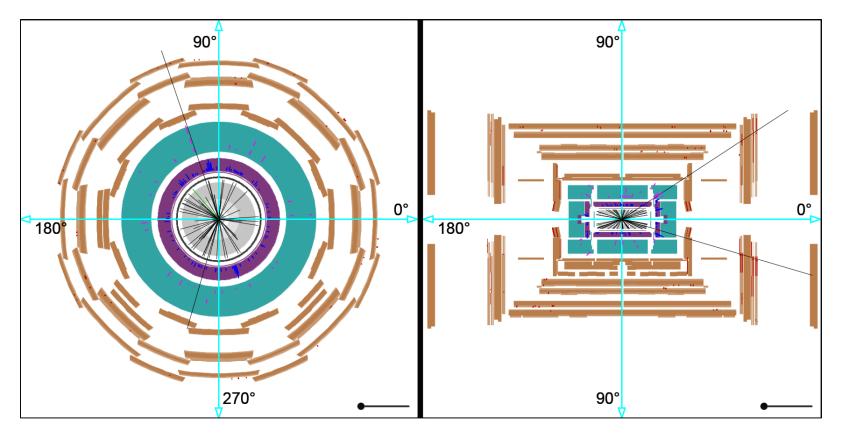
x-y view: measure $\boldsymbol{\varphi}$

z-y view: measure $\boldsymbol{\theta}$



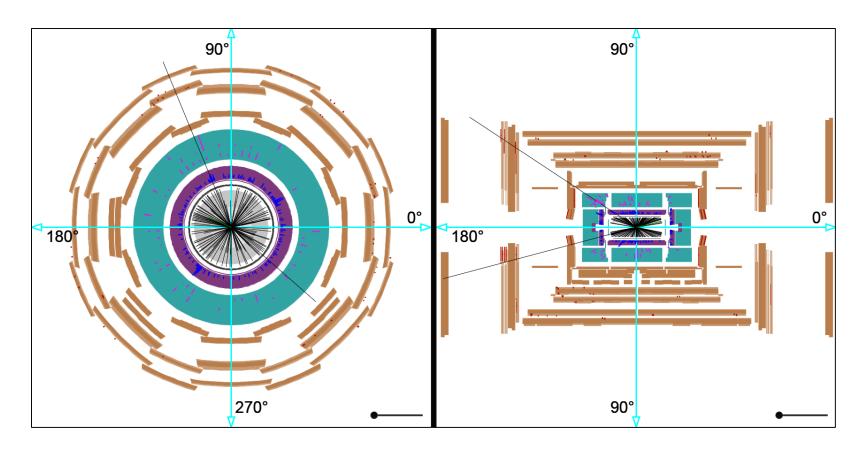
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



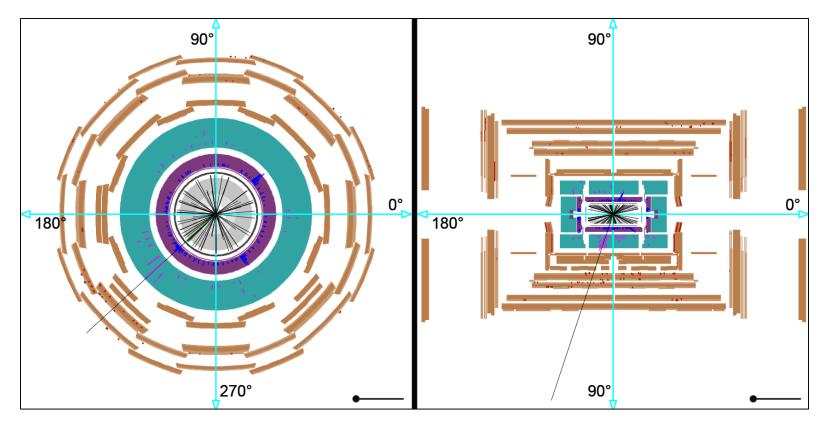
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



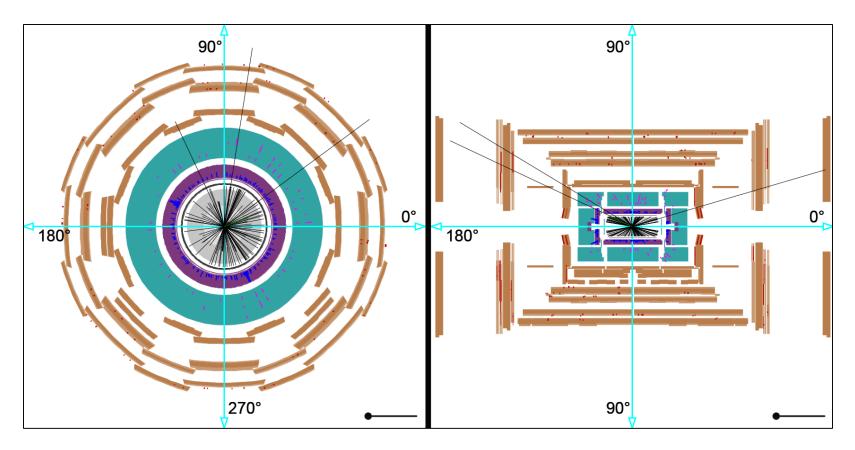
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



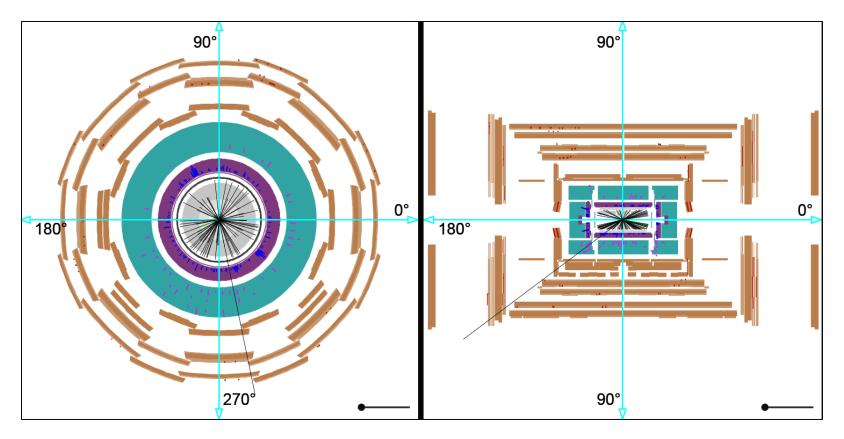
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



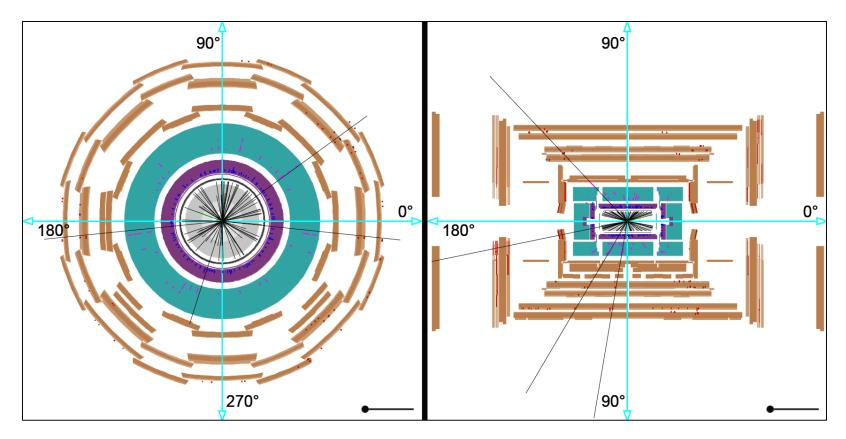
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



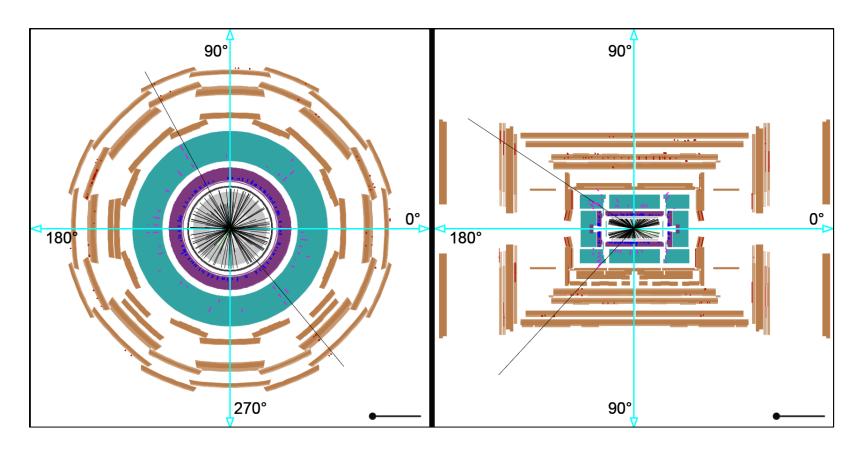
x-y view: measure $\boldsymbol{\varphi}$

z-y view: measure $\boldsymbol{\theta}$



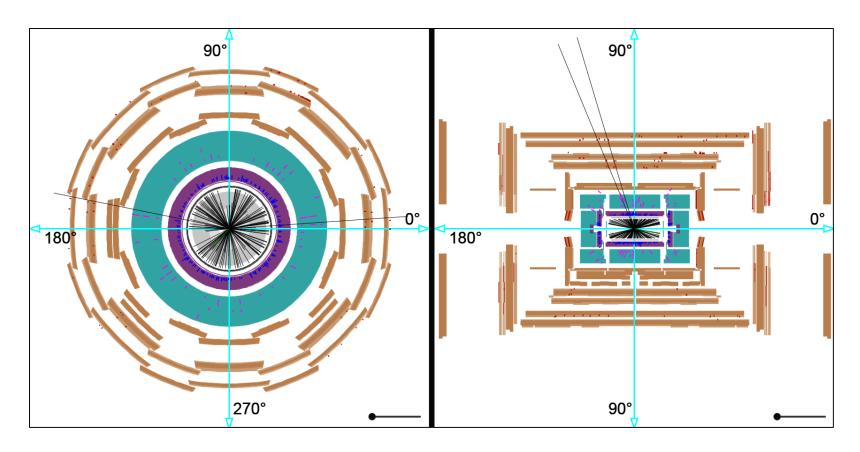
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



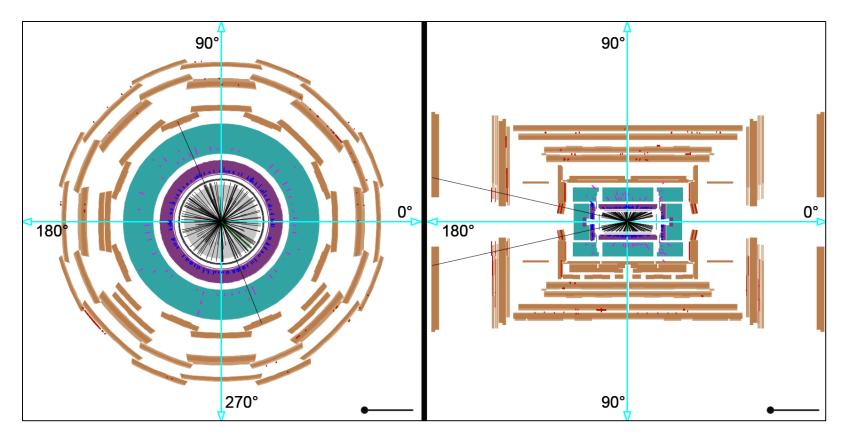
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



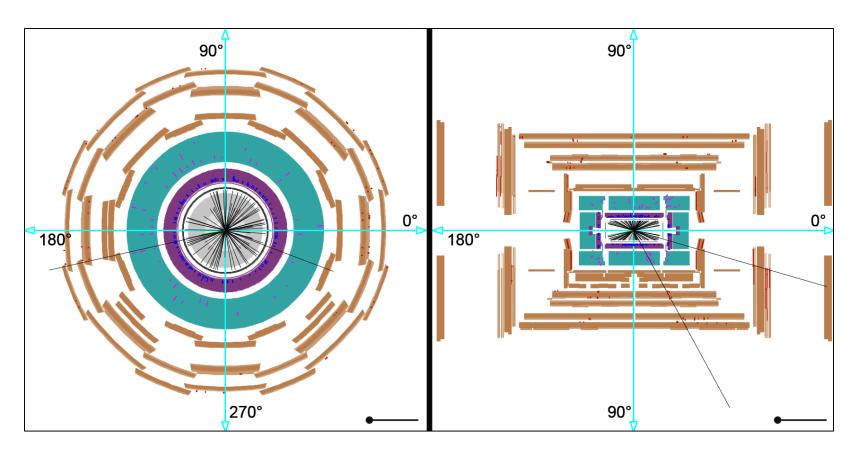
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



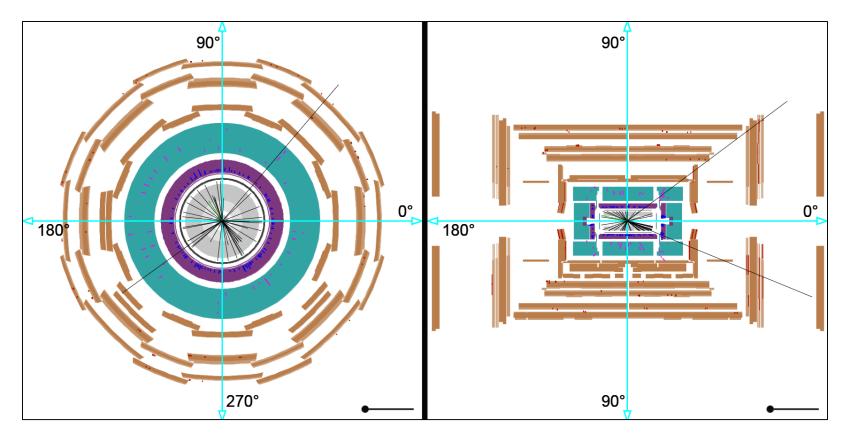
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



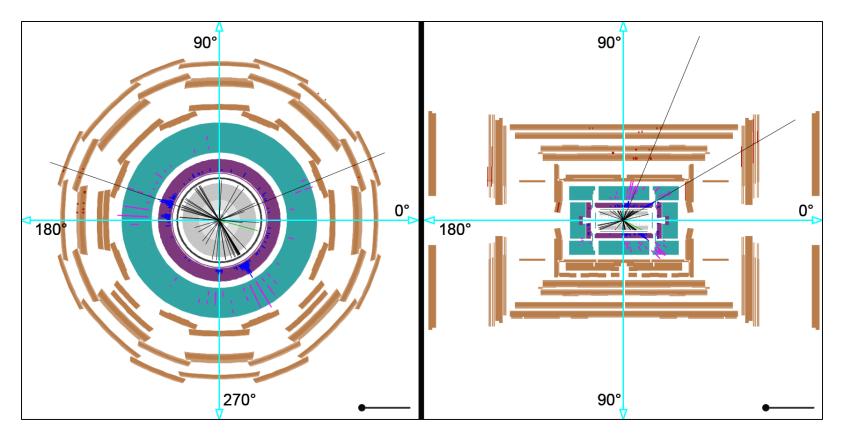
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



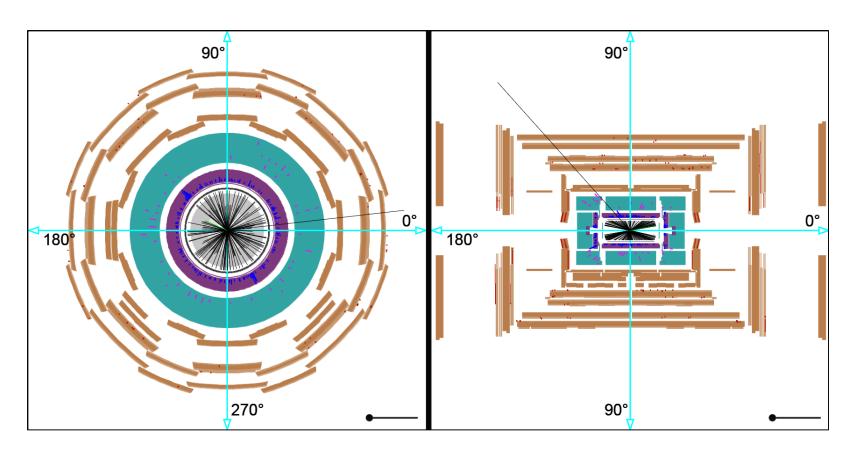
x-y view: measure $\boldsymbol{\varphi}$

z-y view: measure $\boldsymbol{\theta}$



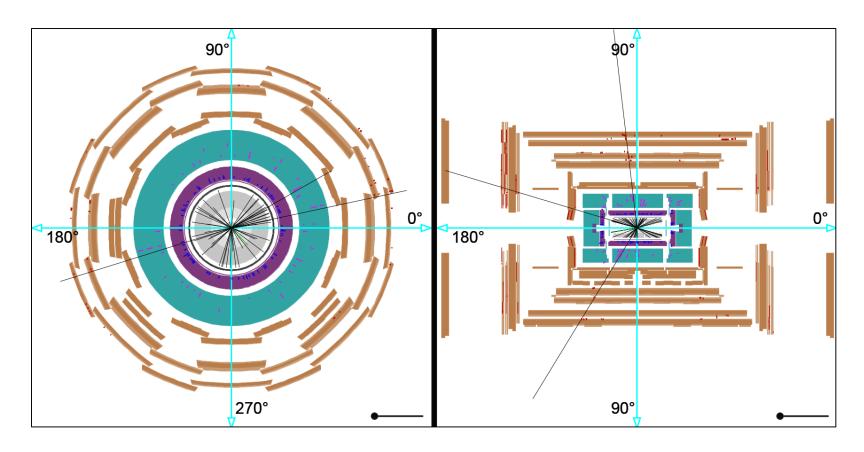
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



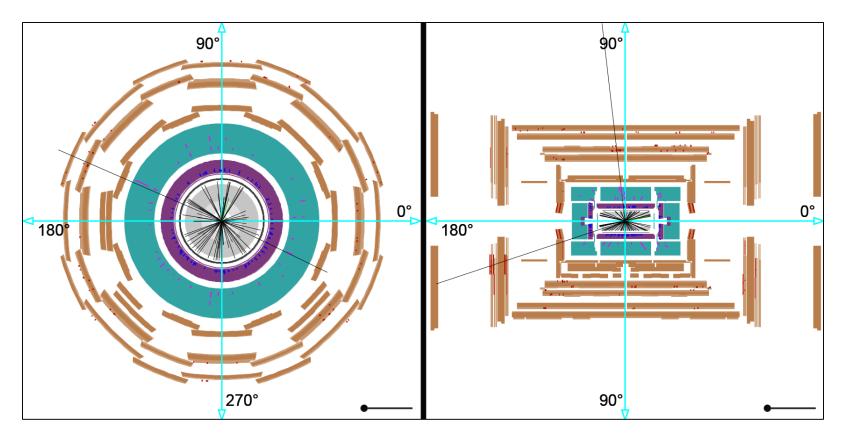
x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$



x-y view: measure ϕ

z-y view: measure $\boldsymbol{\theta}$