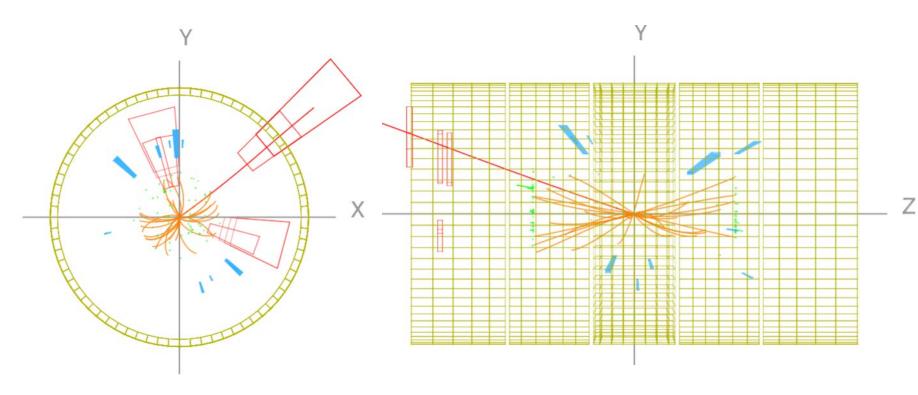
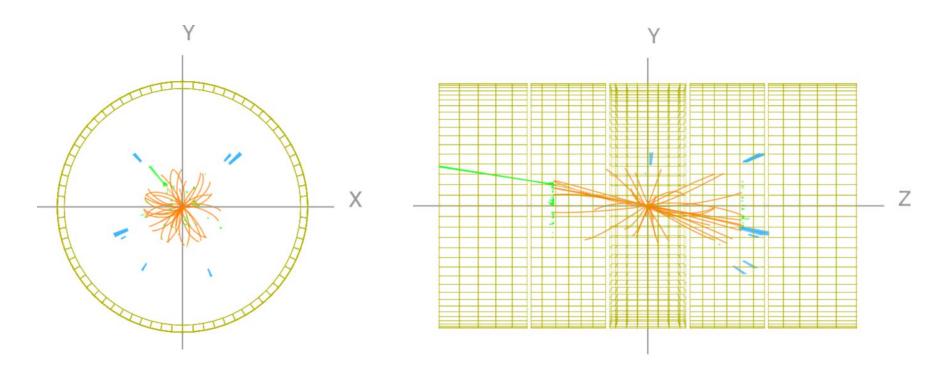
## CMS-W2D2

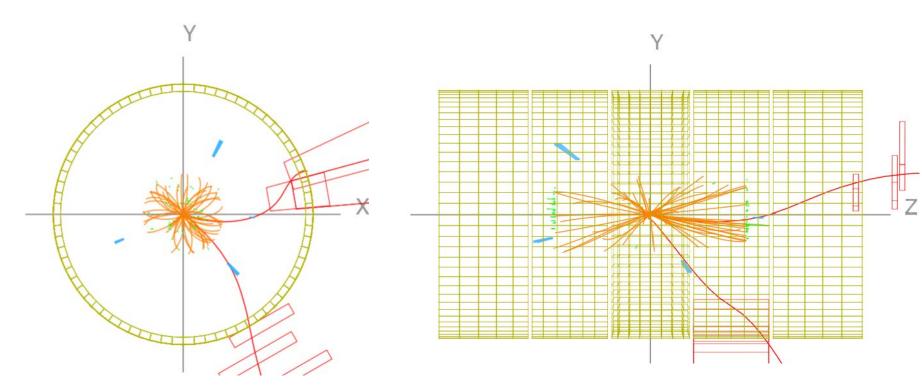
Measurement for
Masterclass-in-a-box
Data Set 2



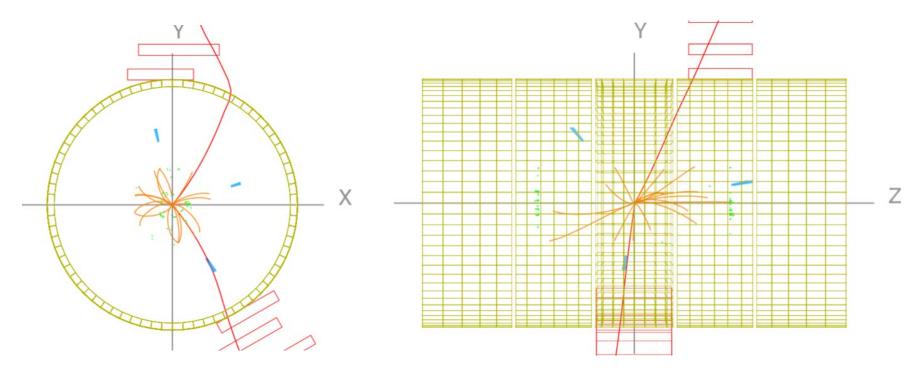
x-y view: measure  $\phi$  z-y view: measure  $\theta$ 



x-y view: measure  $\phi$  z-y view: measure  $\theta$ 

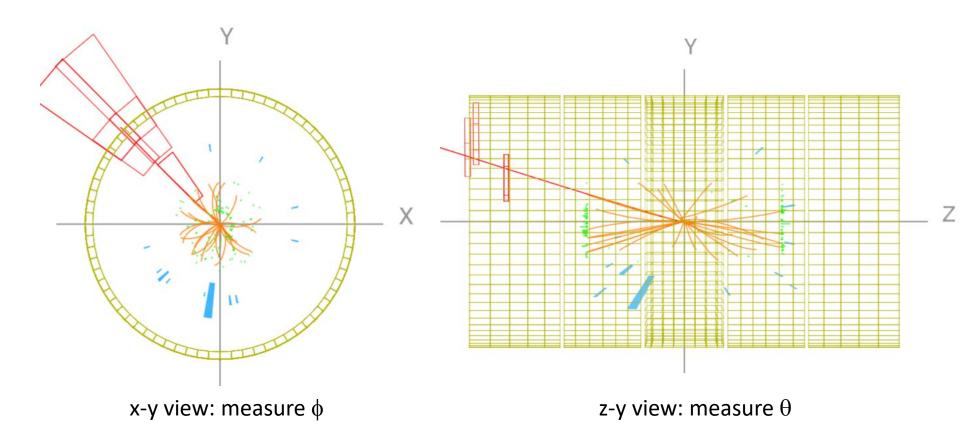


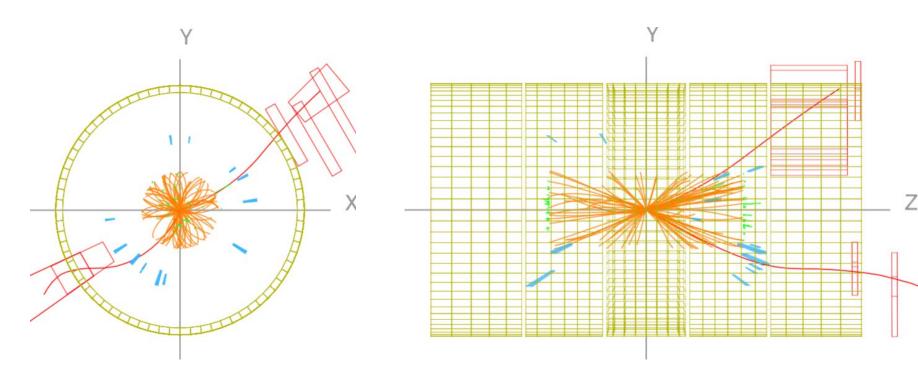
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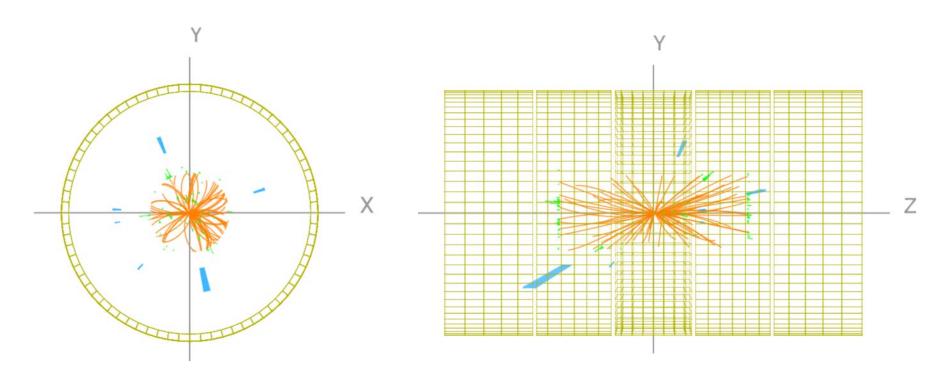
x-y view: measure  $\phi$ 

z-y view: measure  $\boldsymbol{\theta}$ 

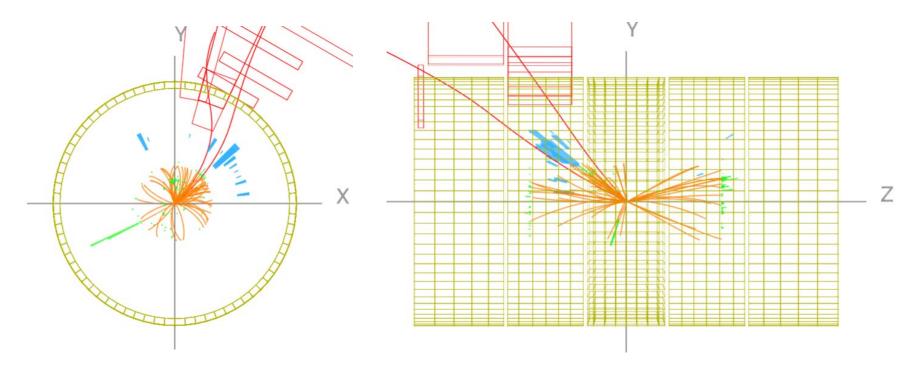




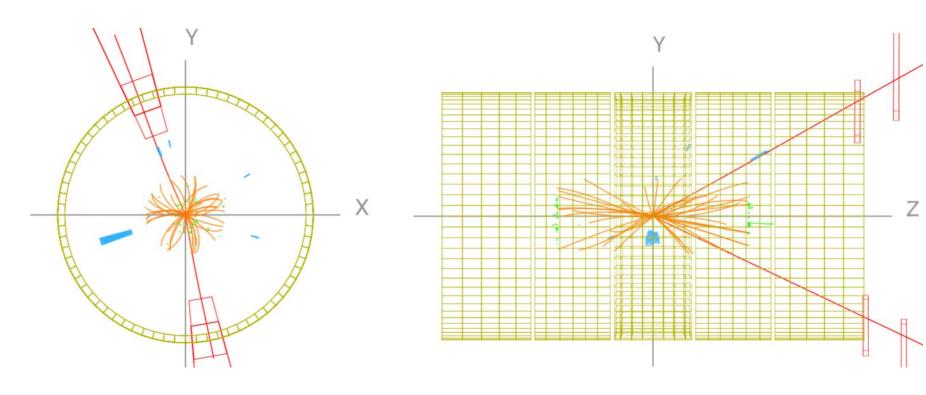
x-y view: measure  $\phi$  z-y view: measure  $\theta$ 



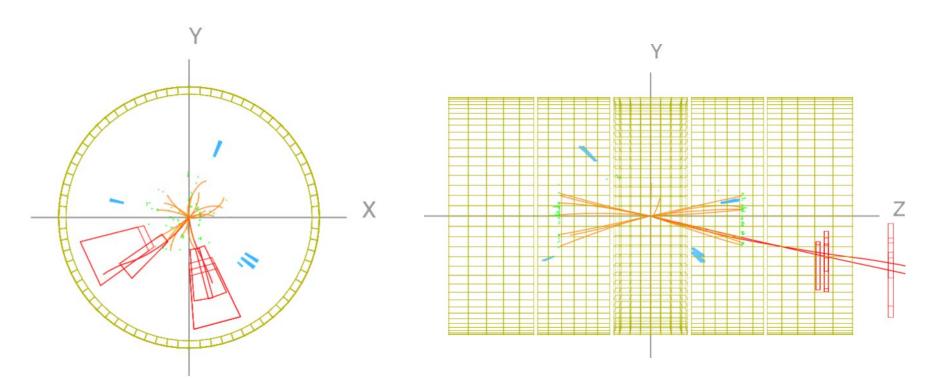
x-y view: measure  $\phi$  z-y view: measure  $\theta$ 



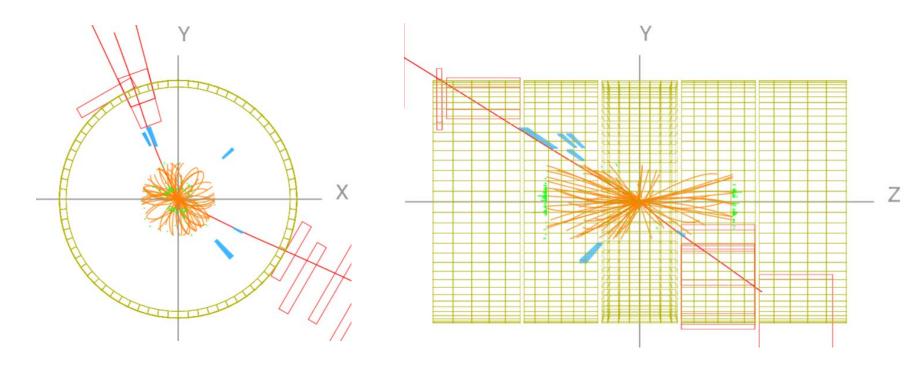
x-y view: measure  $\phi$  z-y view: measure  $\theta$ 



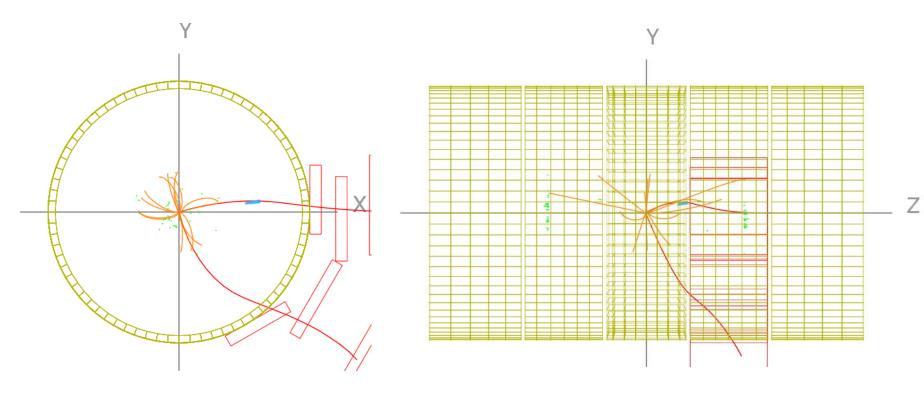
x-y view: measure  $\phi$  z-y view: measure  $\theta$ 



x-y view: measure  $\phi$  z-y view: measure  $\theta$ 

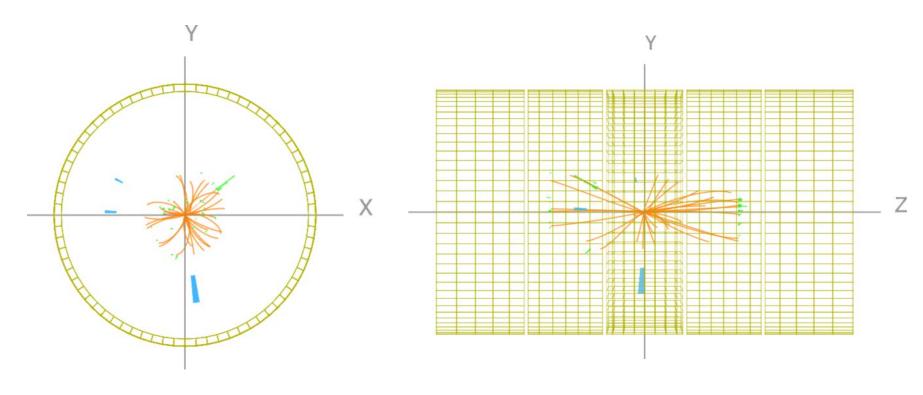


x-y view: measure  $\phi$  z-y view: measure  $\theta$ 

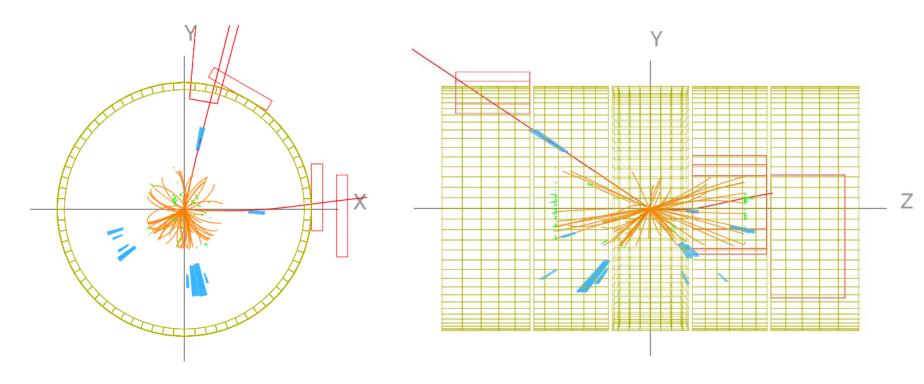


x-y view: measure φ

z-y view: measure  $\boldsymbol{\theta}$ 

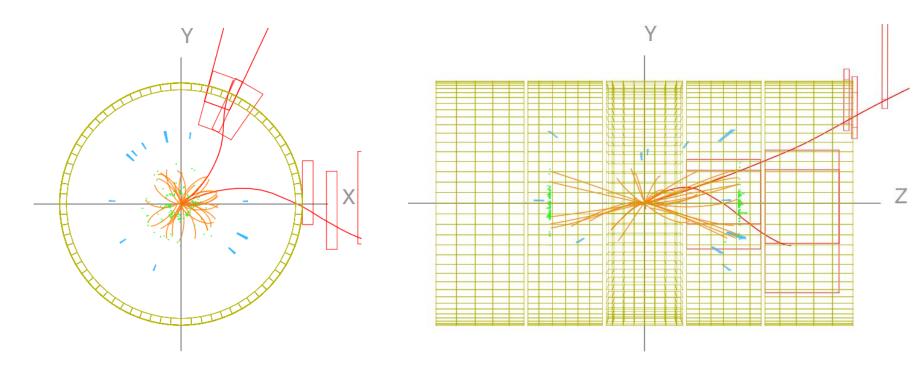


x-y view: measure  $\phi$  z-y view: measure  $\theta$ 



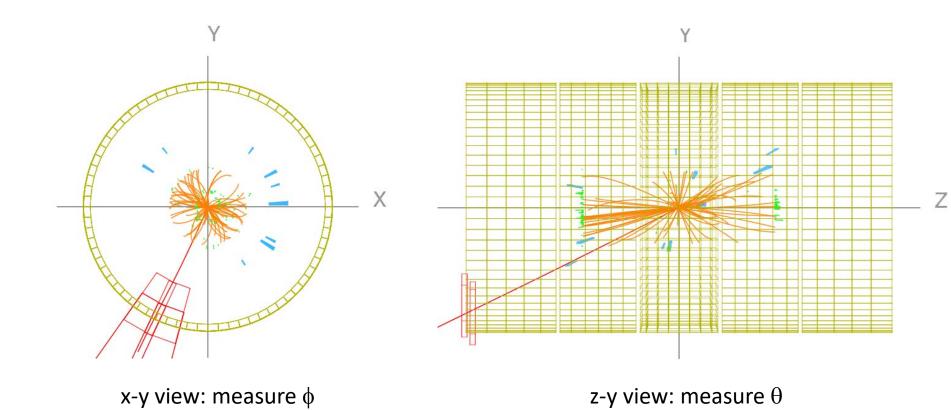
x-y view: measure φ

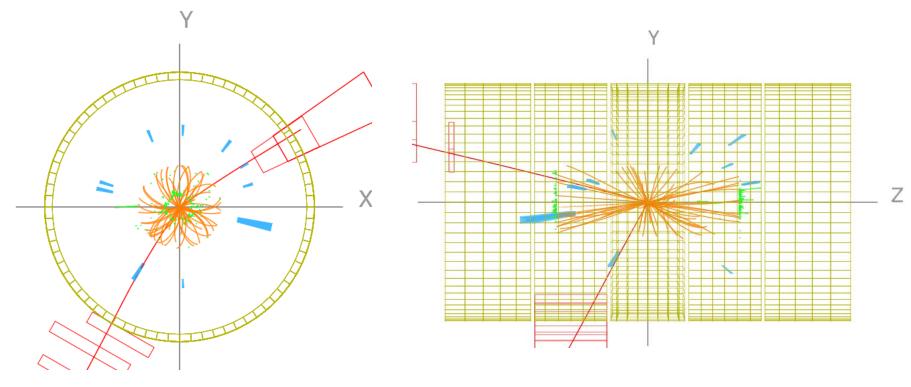
z-y view: measure  $\boldsymbol{\theta}$ 



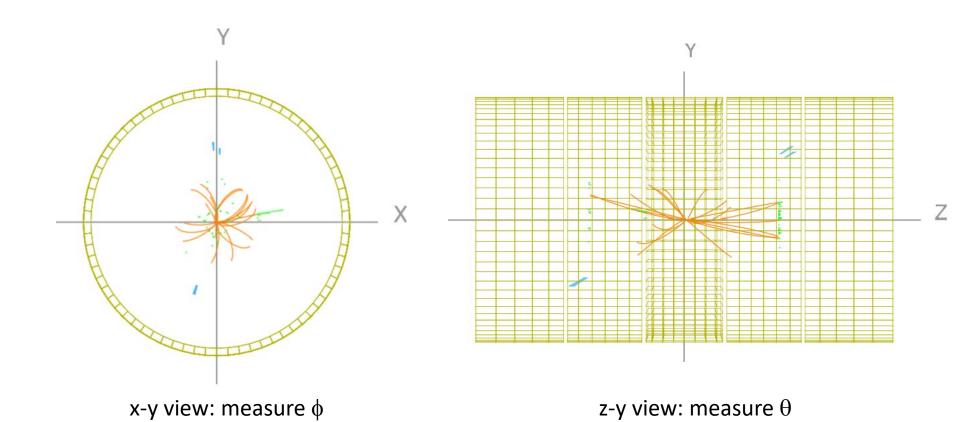
x-y view: measure φ

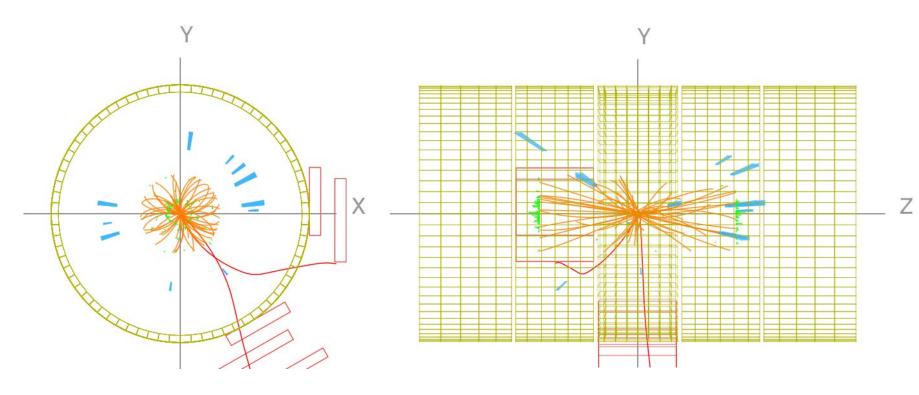
z-y view: measure  $\boldsymbol{\theta}$ 



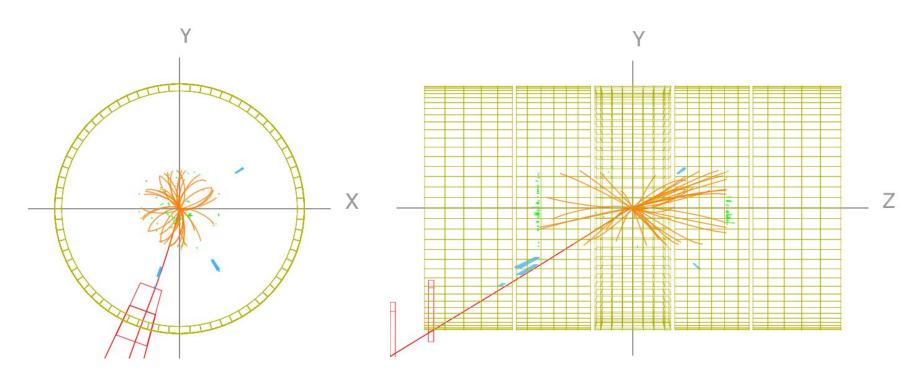


x-y view: measure  $\phi$  z-y view: measure  $\theta$ 

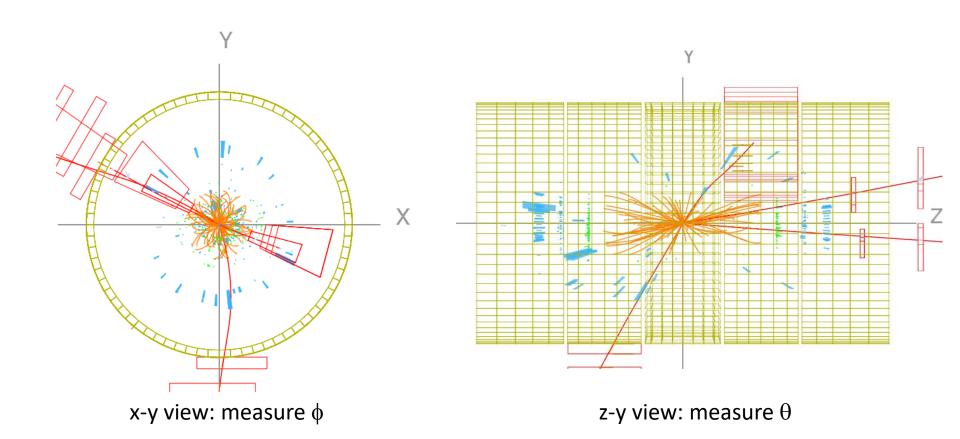


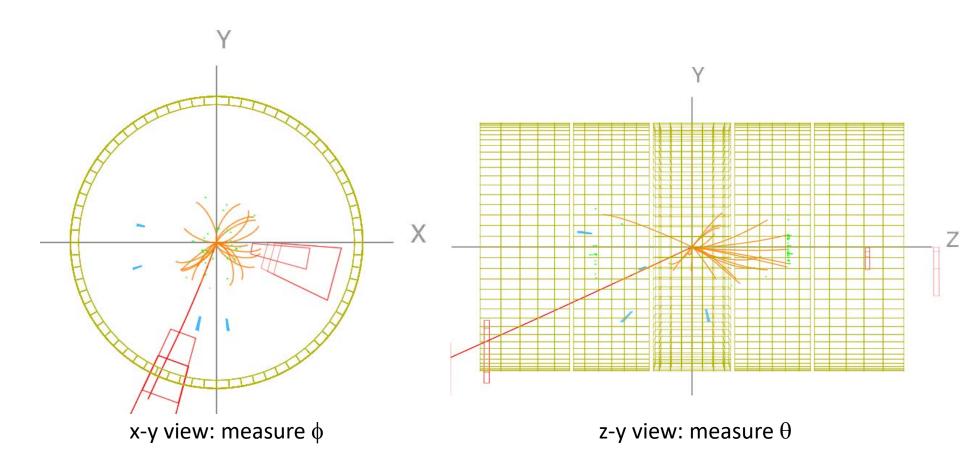


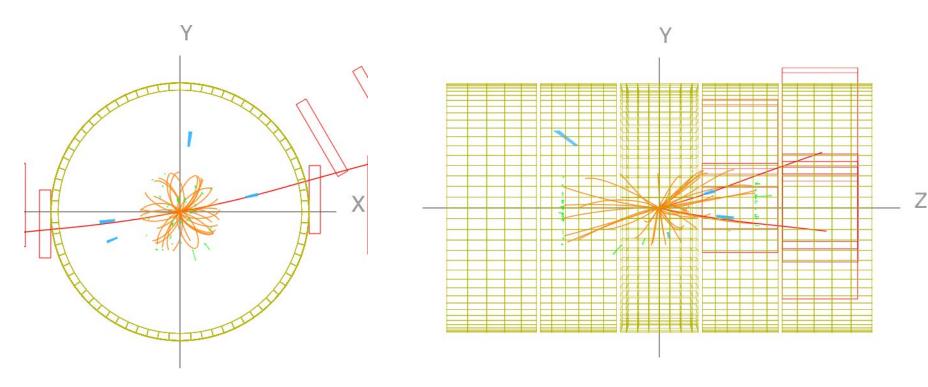
x-y view: measure  $\phi$  z-y view: measure  $\theta$ 



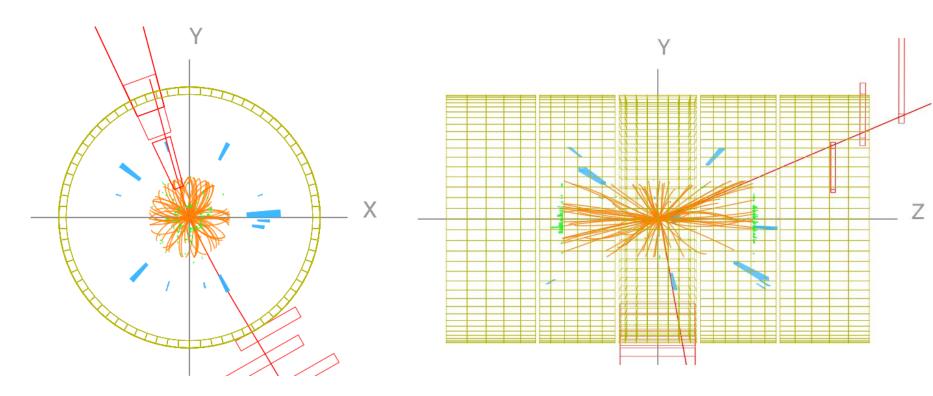
x-y view: measure  $\phi$  z-y view: measure  $\theta$ 





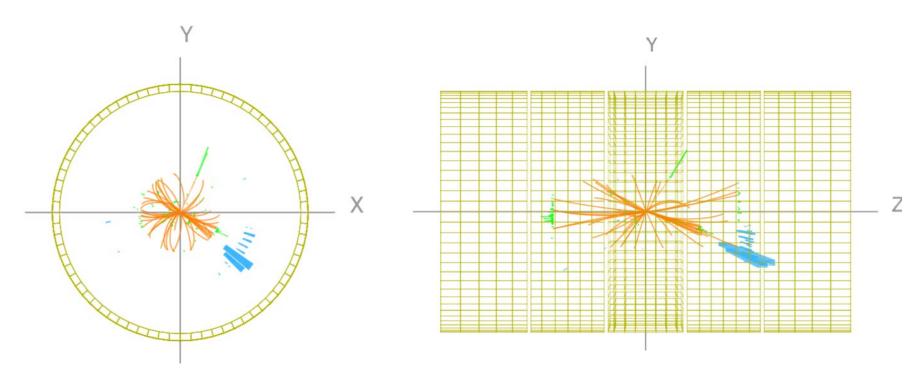


x-y view: measure  $\phi$  z-y view: measure  $\theta$ 

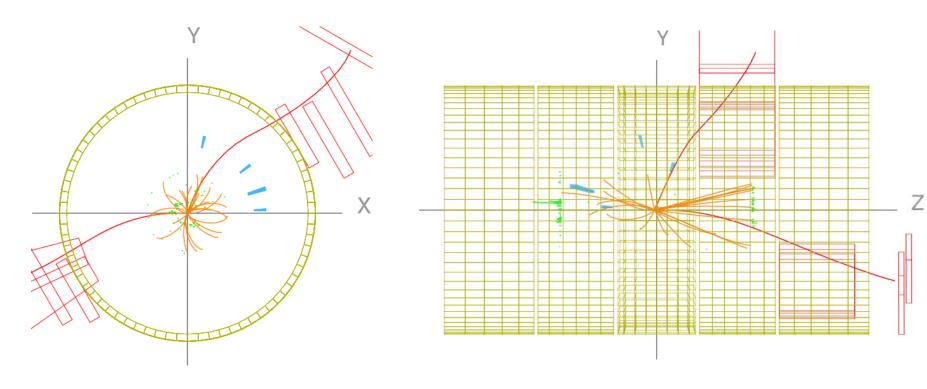


x-y view: measure φ

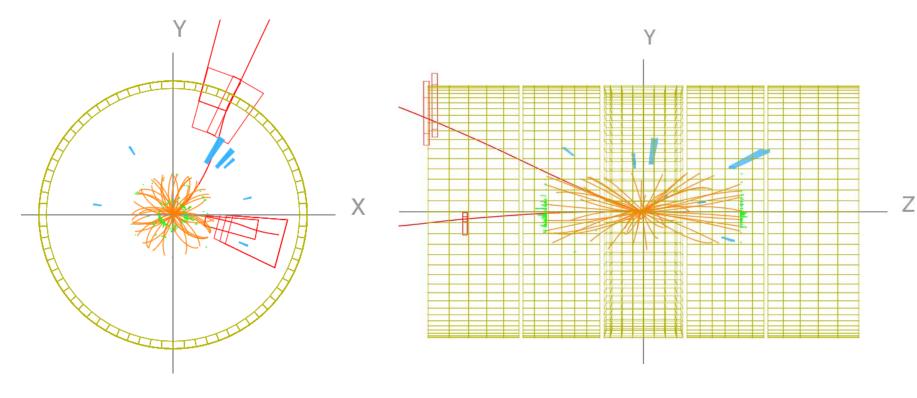
z-y view: measure  $\boldsymbol{\theta}$ 



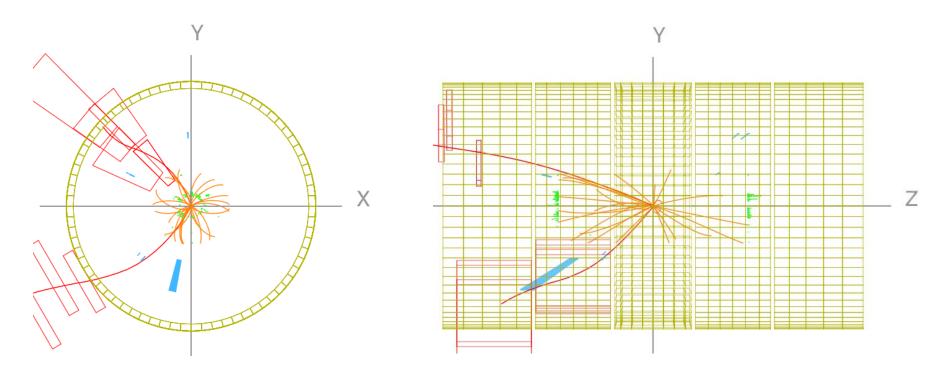
x-y view: measure  $\phi$  z-y view: measure  $\theta$ 



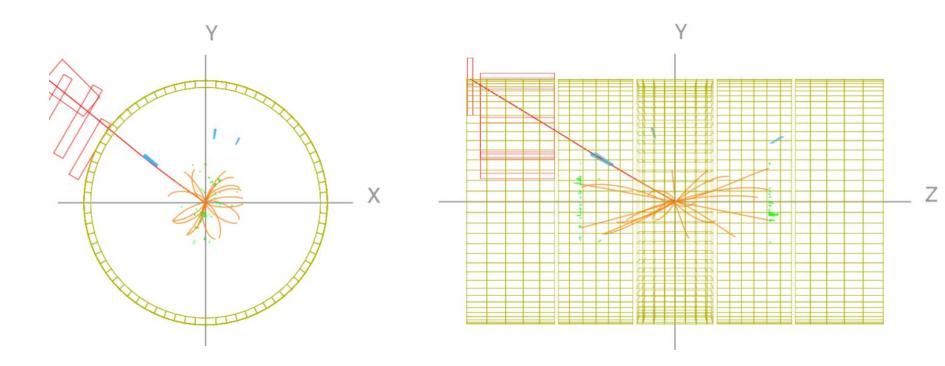
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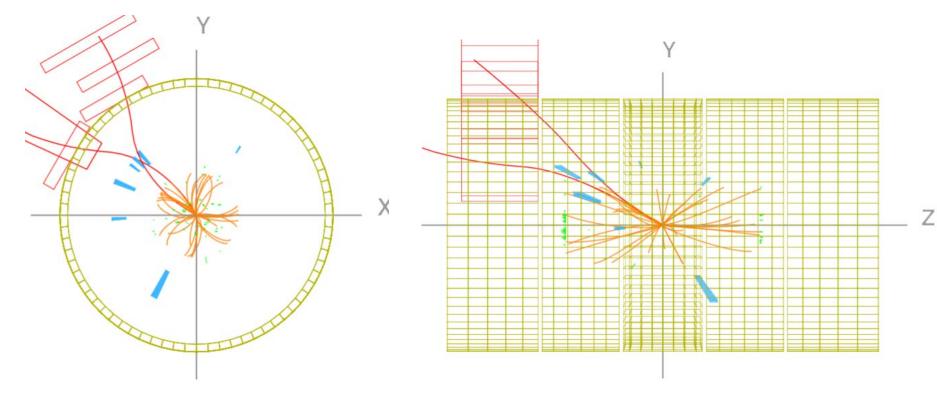
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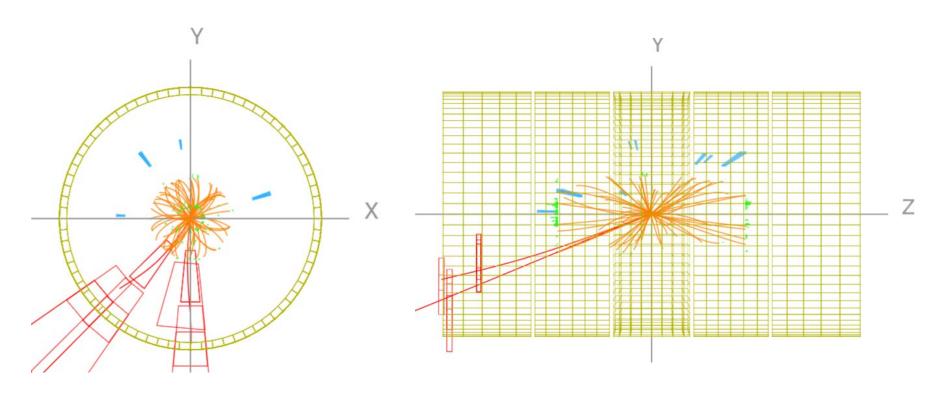
x-y view: measure  $\phi$  z-y view: measure  $\theta$ 



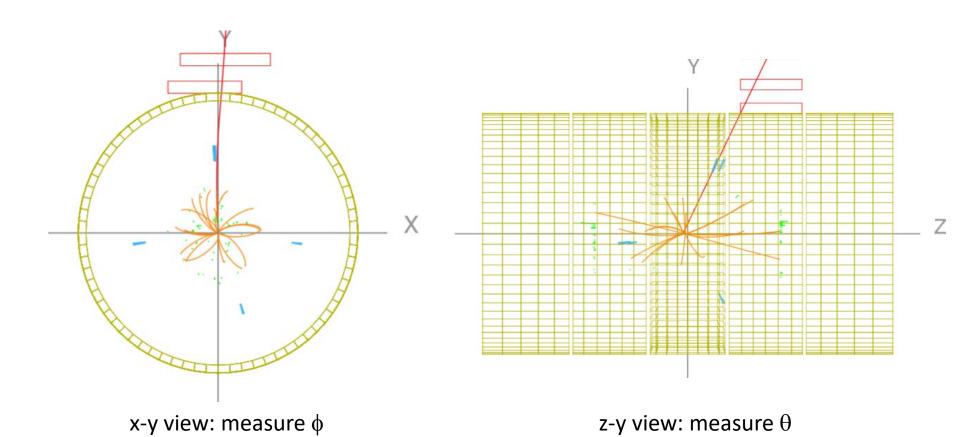
x-y view: measure  $\phi$  z-y view: measure  $\theta$ 

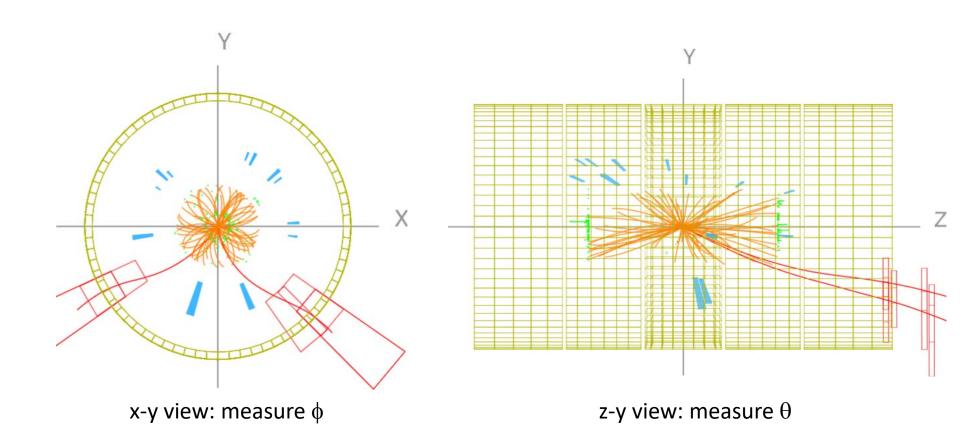


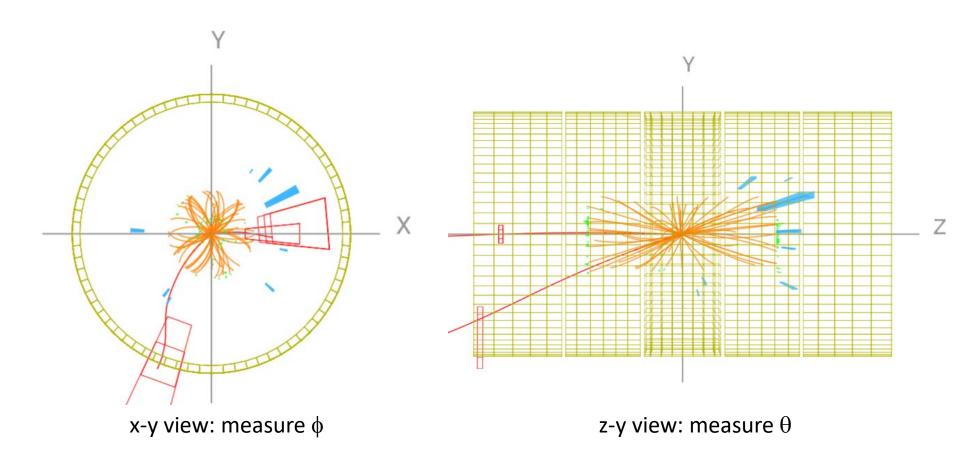
x-y view: measure  $\phi$  z-y view: measure  $\theta$ 

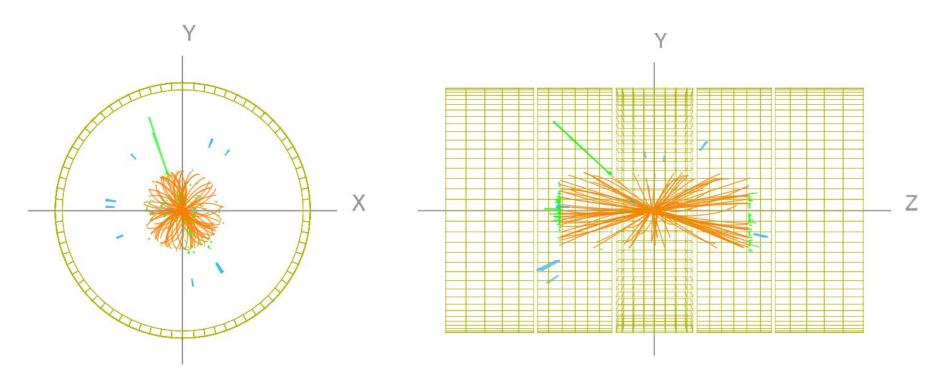


x-y view: measure  $\phi$  z-y view: measure  $\theta$ 

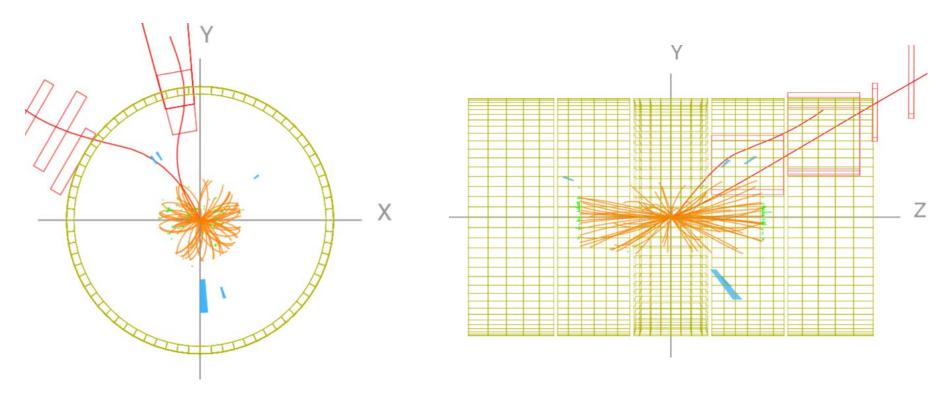




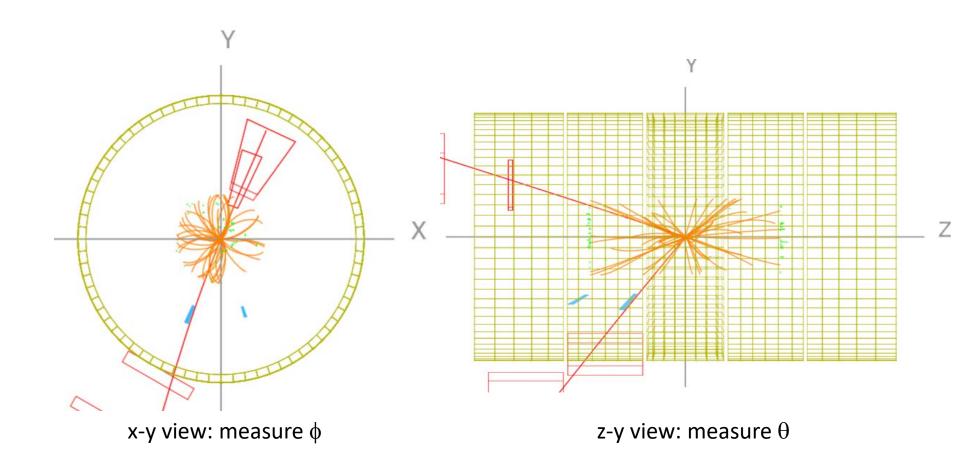


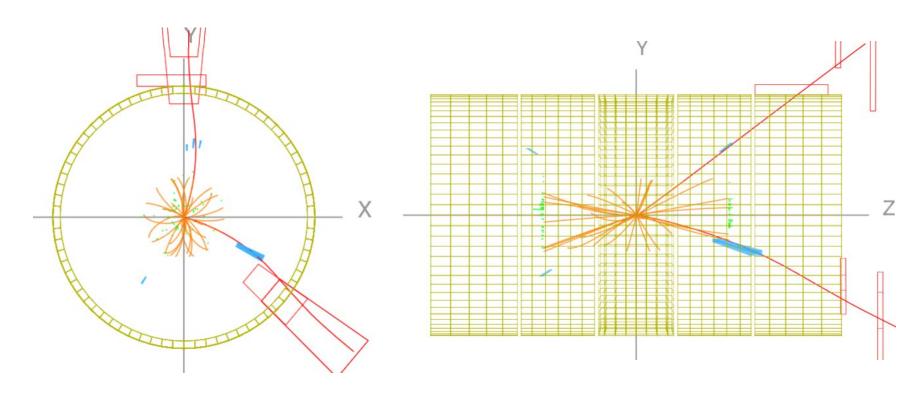


x-y view: measure  $\phi$  z-y view: measure  $\theta$ 

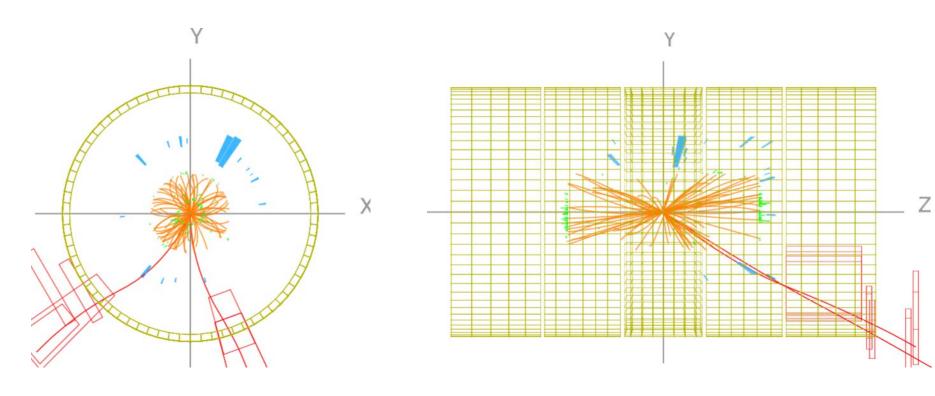


x-y view: measure  $\phi$  z-y view: measure  $\theta$ 

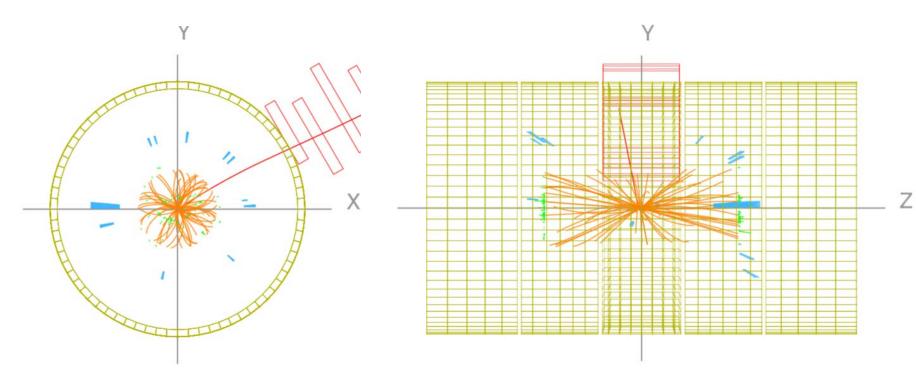




x-y view: measure  $\phi$  z-y view: measure  $\theta$ 

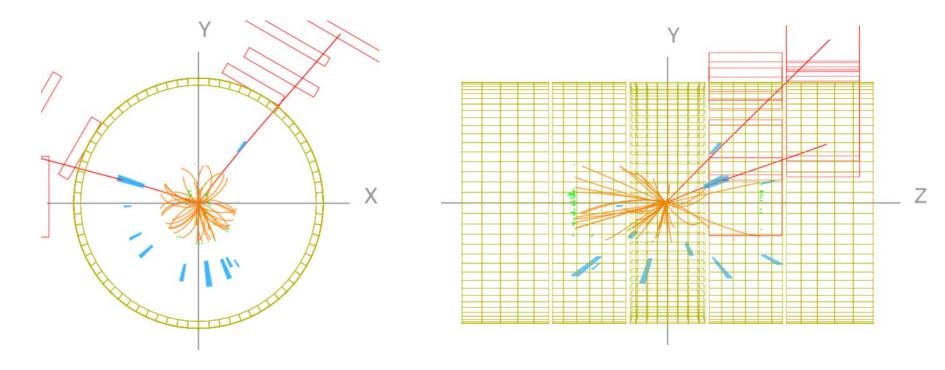


x-y view: measure  $\phi$  z-y view: measure  $\theta$ 



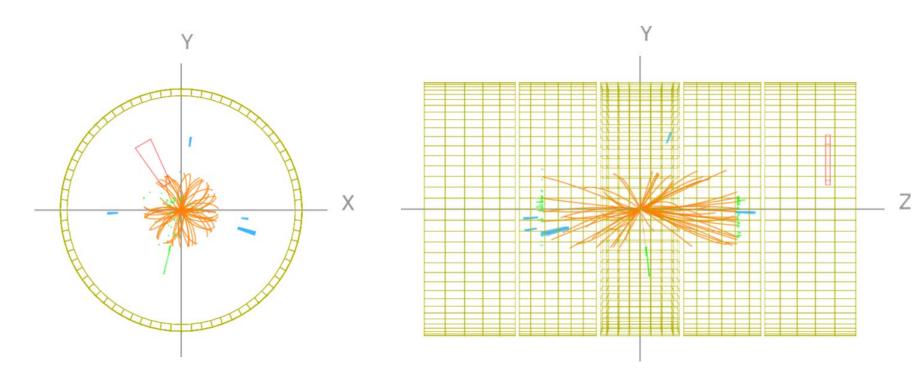
x-y view: measure φ

z-y view: measure  $\boldsymbol{\theta}$ 

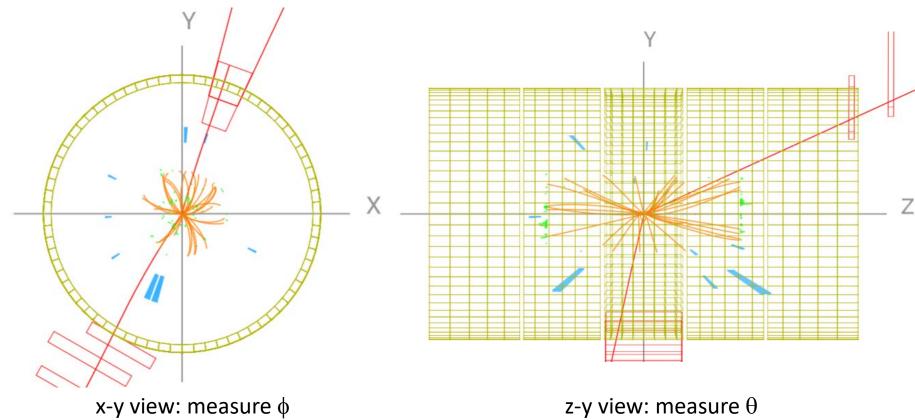


x-y view: measure φ

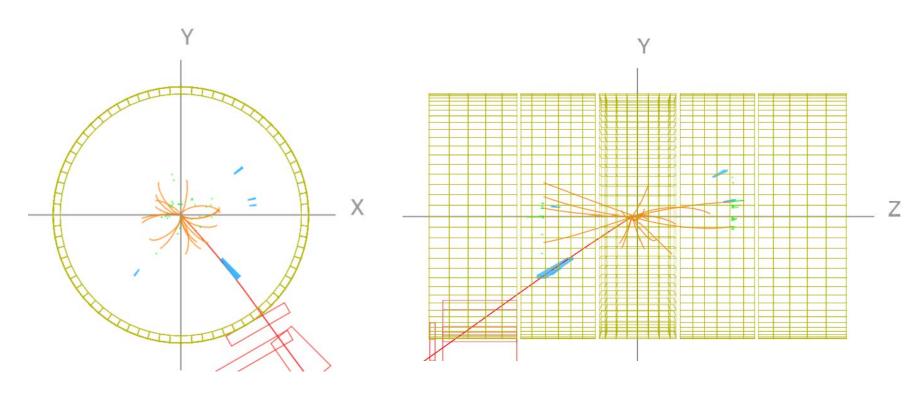
z-y view: measure  $\boldsymbol{\theta}$ 



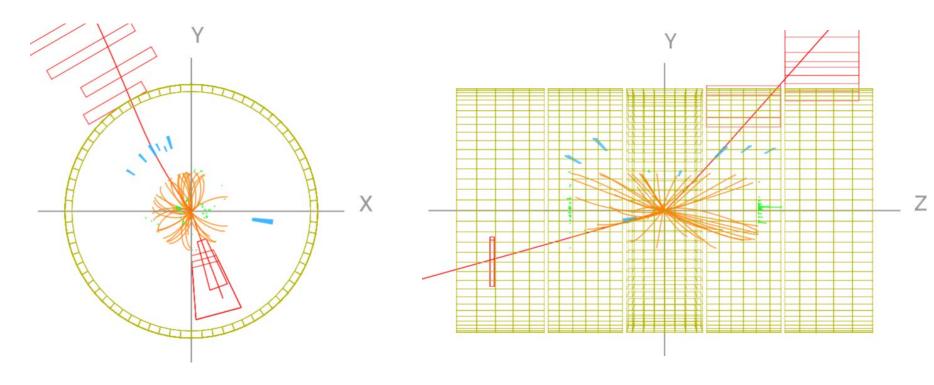
x-y view: measure  $\phi$  z-y view: measure  $\theta$ 



z-y view: measure  $\boldsymbol{\theta}$ 

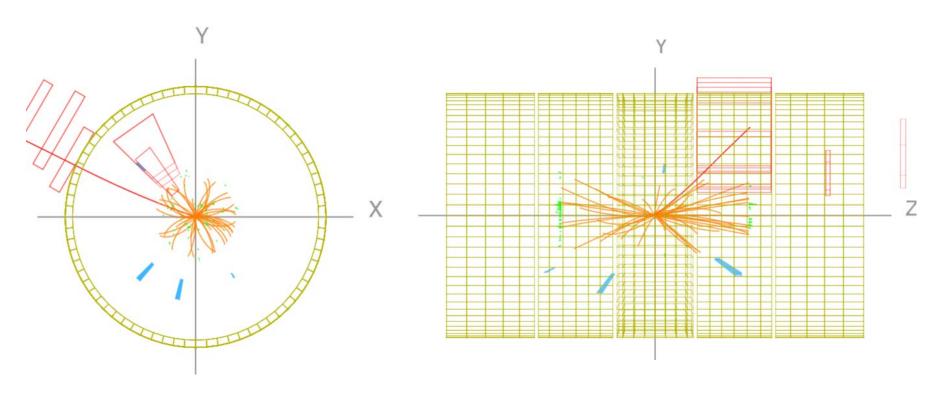


x-y view: measure  $\phi$  z-y view: measure  $\theta$ 

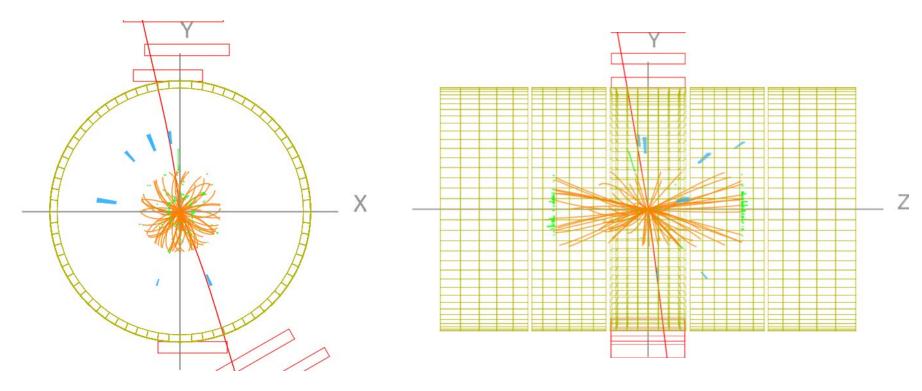


x-y view: measure φ

z-y view: measure  $\boldsymbol{\theta}$ 

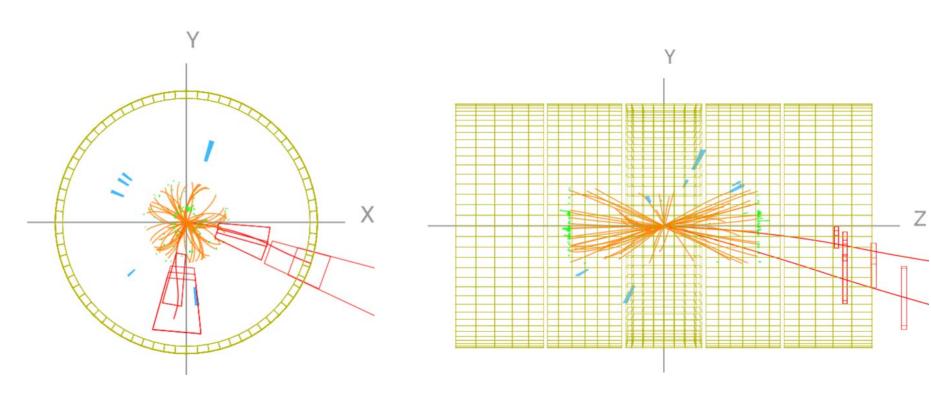


x-y view: measure  $\phi$  z-y view: measure  $\theta$ 



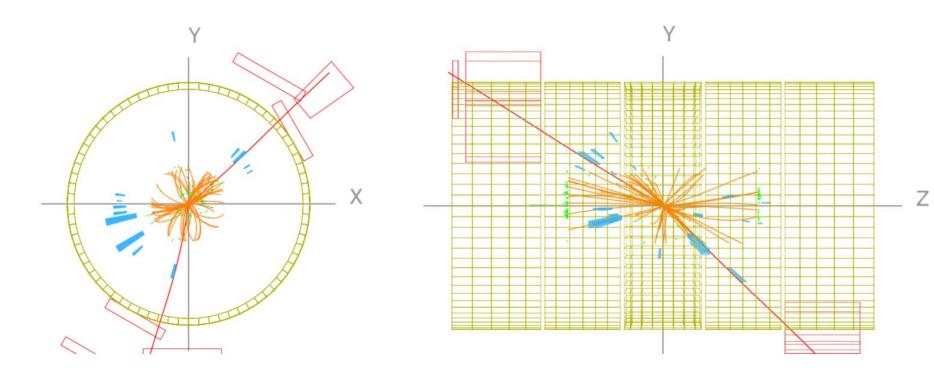
x-y view: measure φ

z-y view: measure  $\boldsymbol{\theta}$ 

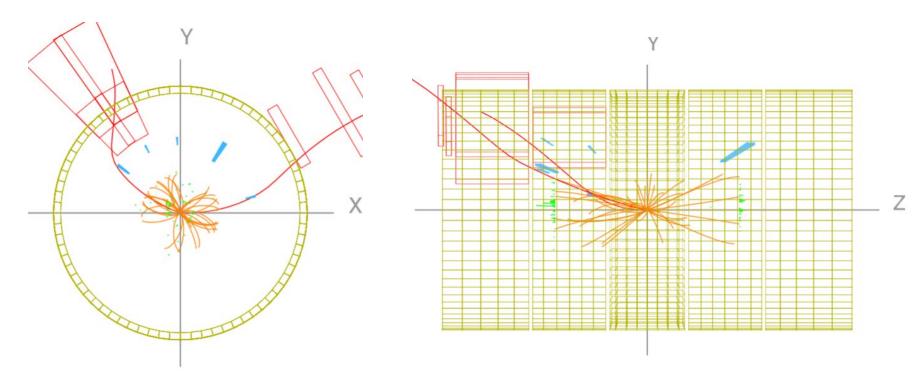


x-y view: measure φ

z-y view: measure  $\boldsymbol{\theta}$ 



x-y view: measure  $\phi$  z-y view: measure  $\theta$ 



x-y view: measure  $\phi$  z-y view: measure  $\theta$