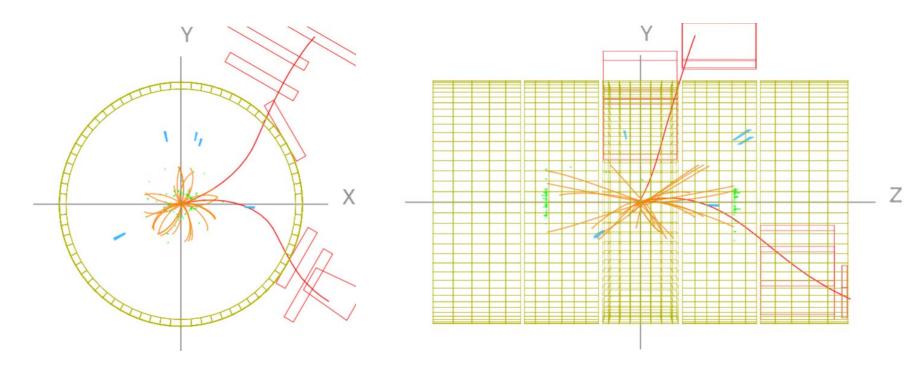
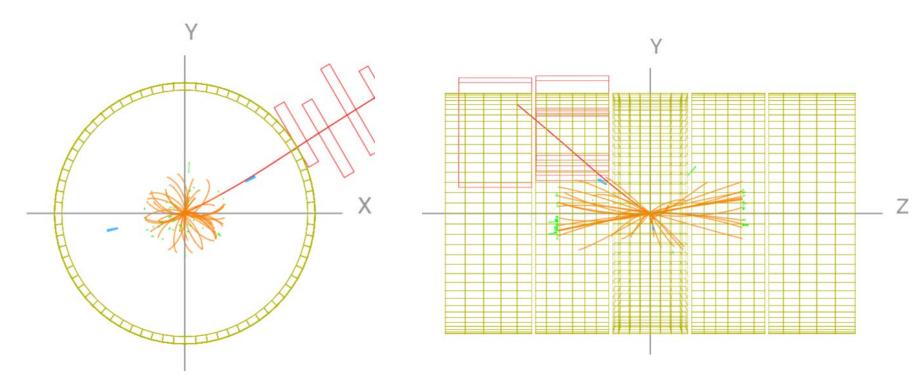
CMS-W2D2

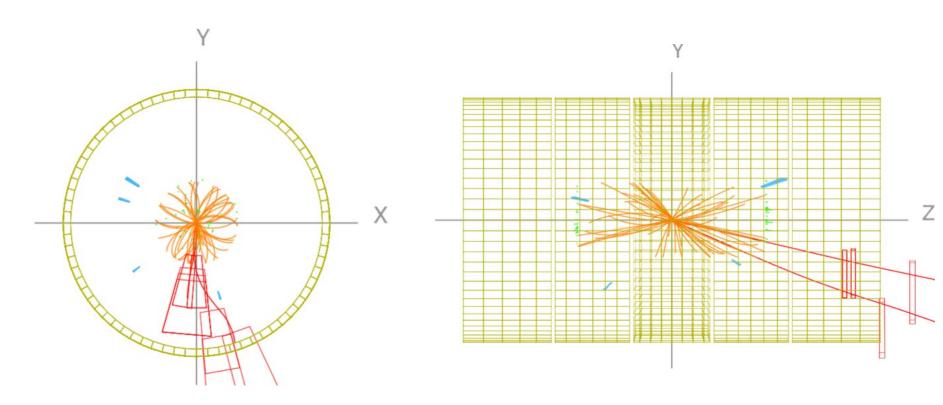
Measurement for
Masterclass-in-a-box
Data Set 3



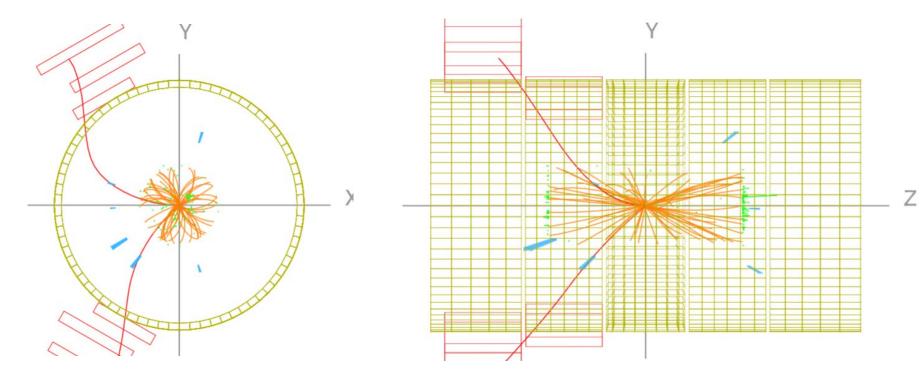
x-y view: measure ϕ z-y view: measure θ



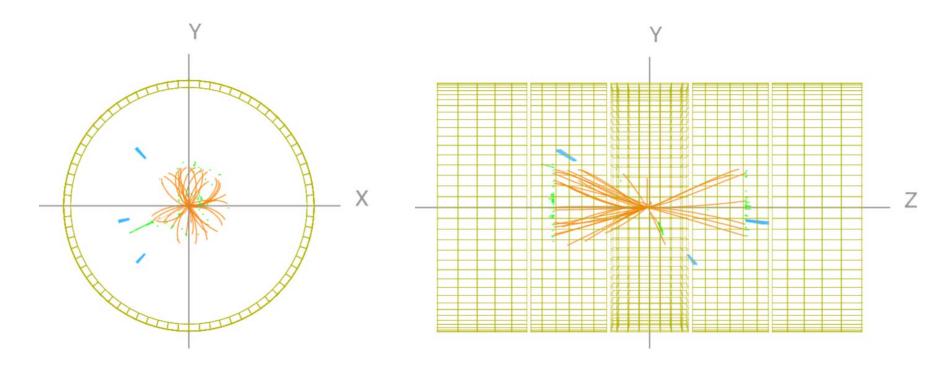
x-y view: measure ϕ z-y view: measure θ



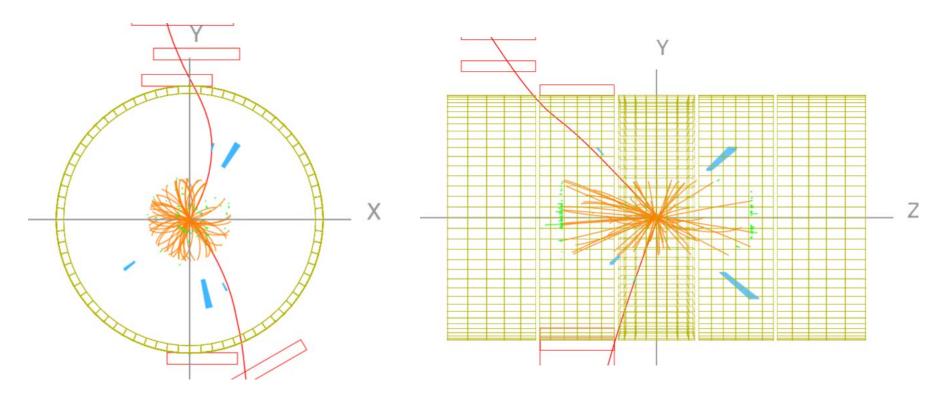
x-y view: measure ϕ z-y view: measure θ



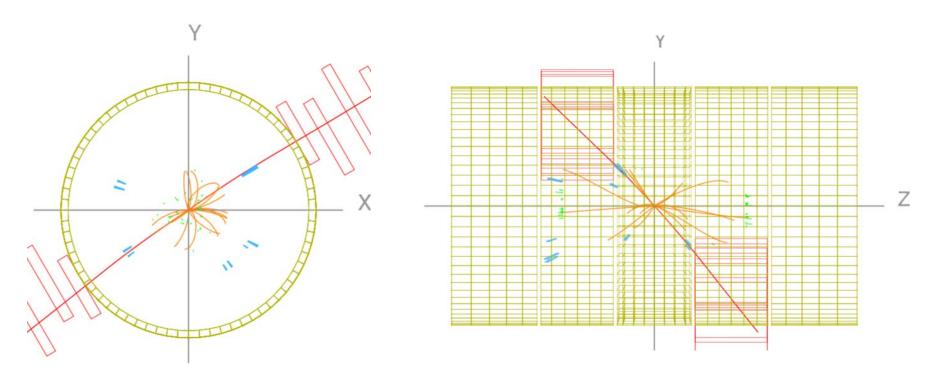
x-y view: measure ϕ z-y view: measure θ



x-y view: measure ϕ z-y view: measure θ

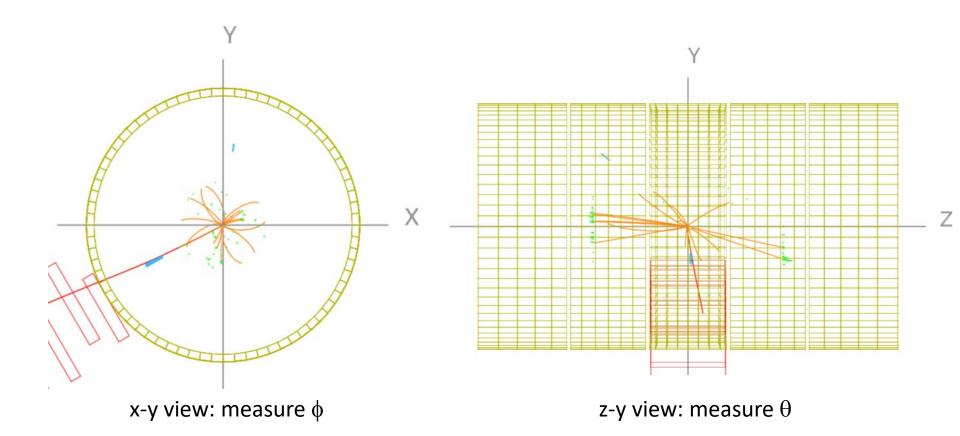


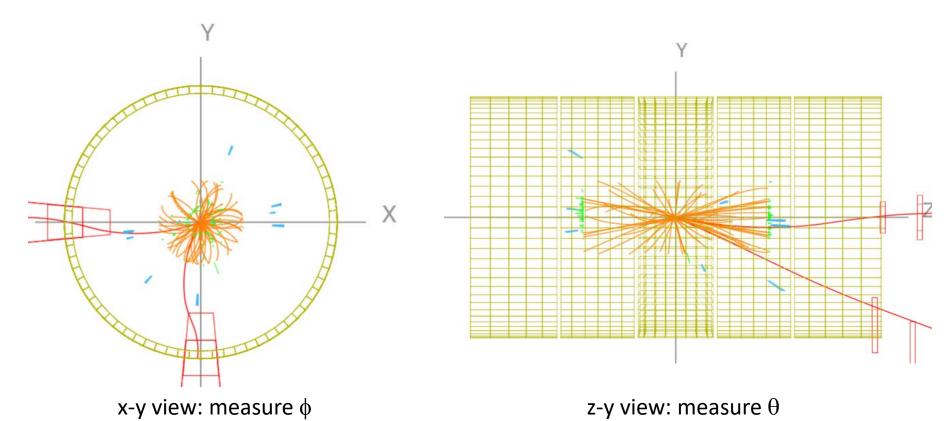
x-y view: measure ϕ z-y view: measure θ



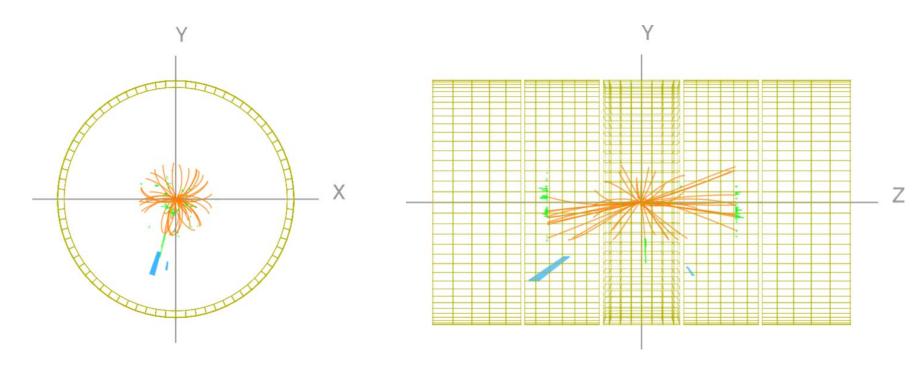
x-y view: measure φ

z-y view: measure $\boldsymbol{\theta}$

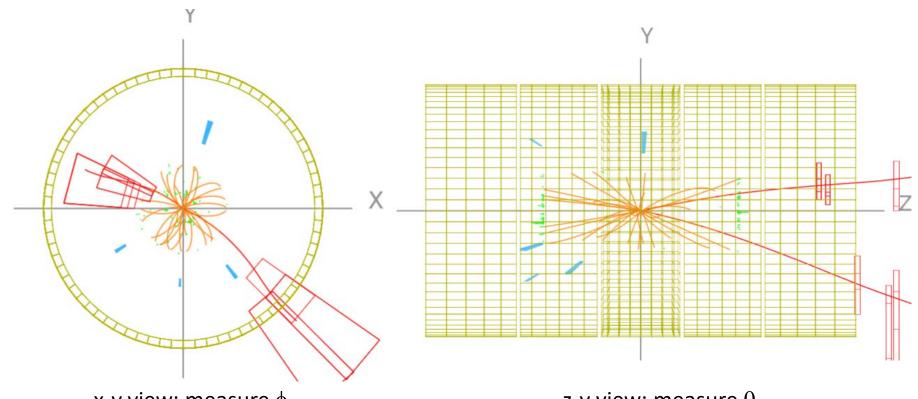




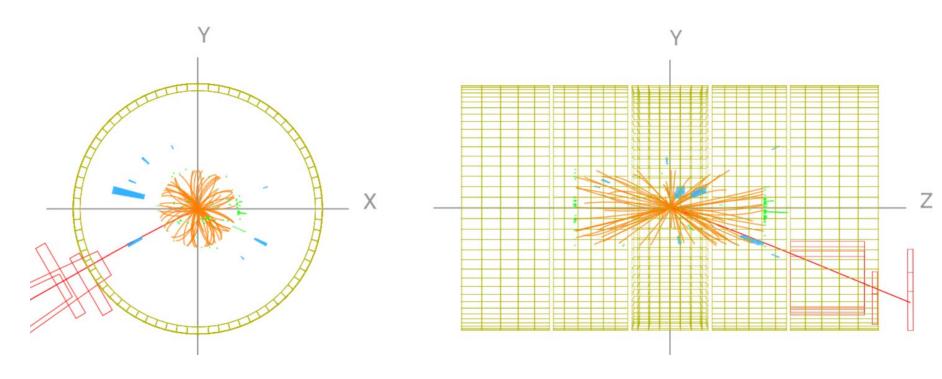
z-y view: measure $\boldsymbol{\theta}$



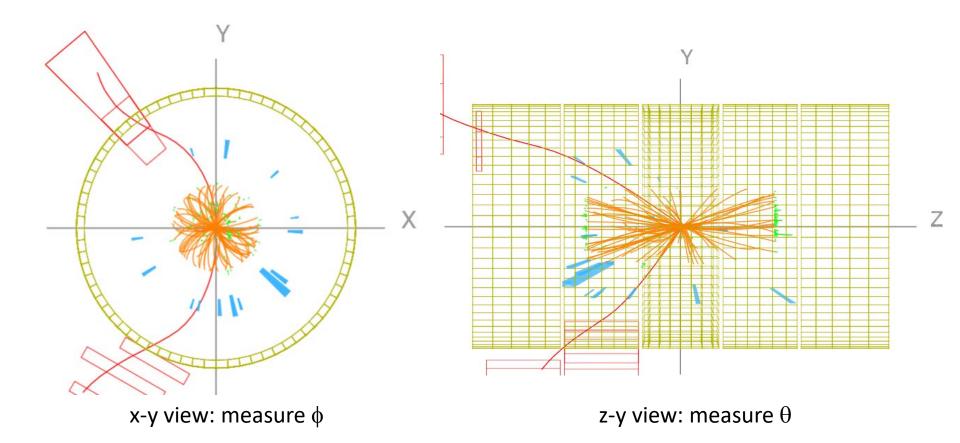
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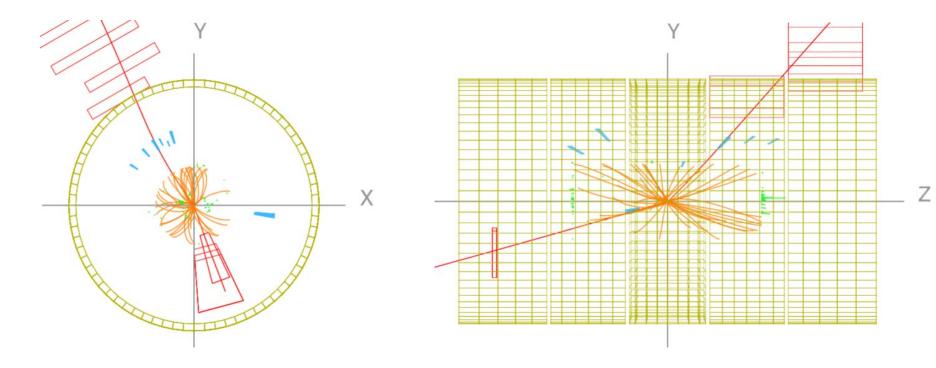


x-y view: measure ϕ z-y view: measure θ

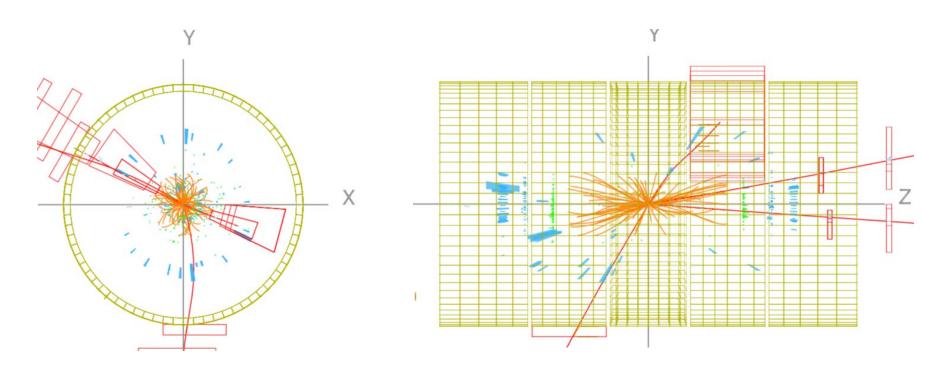


x-y view: measure ϕ z-y view: measure θ

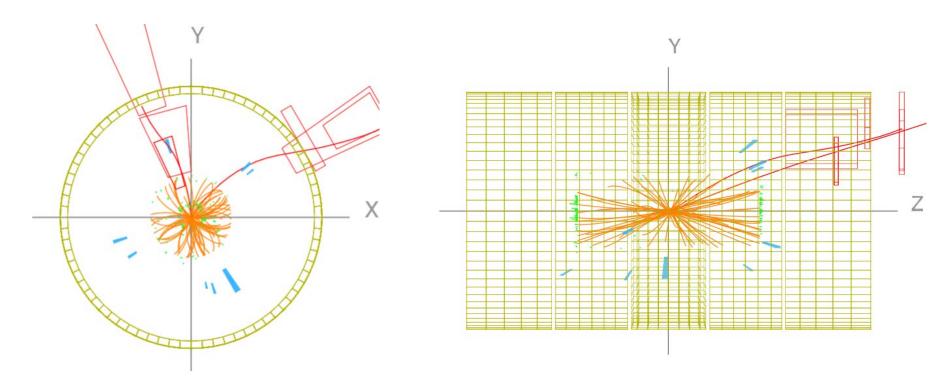




x-y view: measure ϕ z-y view: measure θ

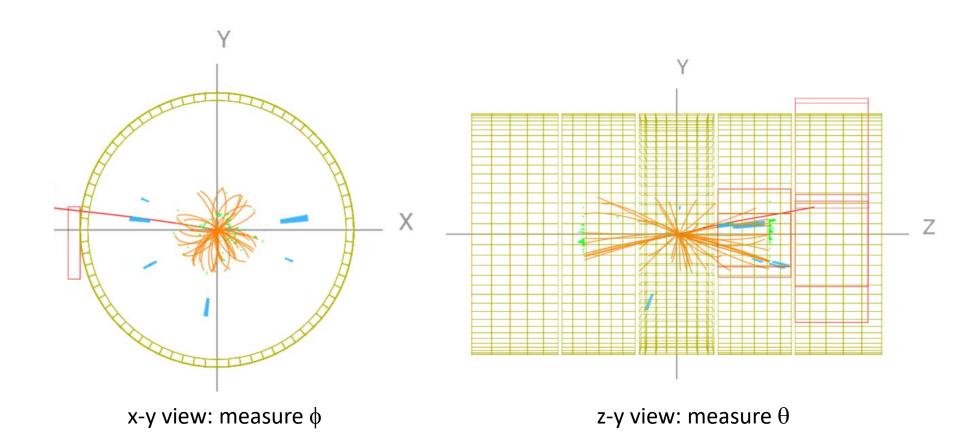


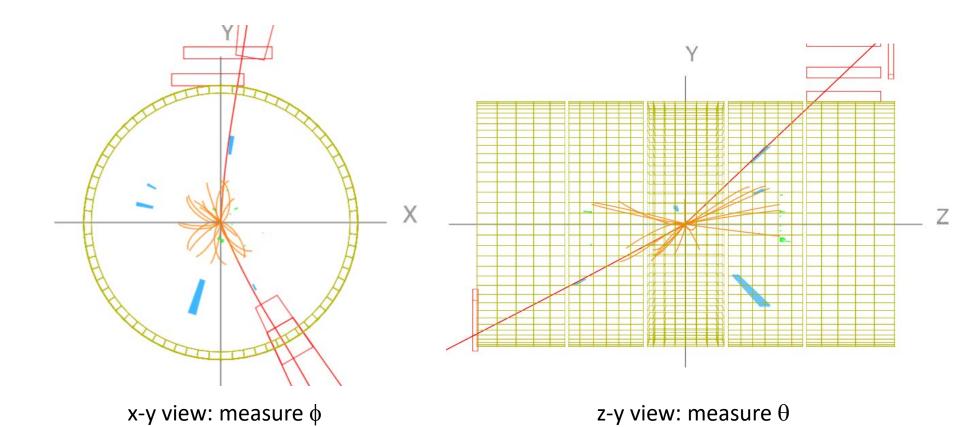
x-y view: measure ϕ z-y view: measure θ

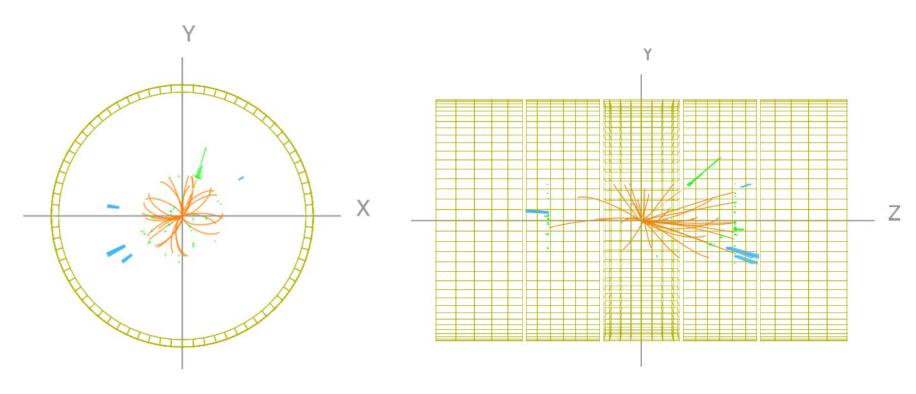


x-y view: measure φ

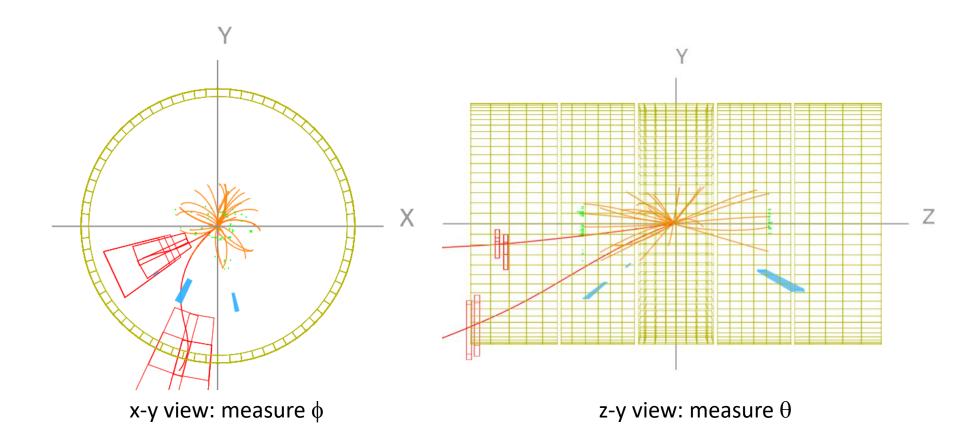
z-y view: measure $\boldsymbol{\theta}$

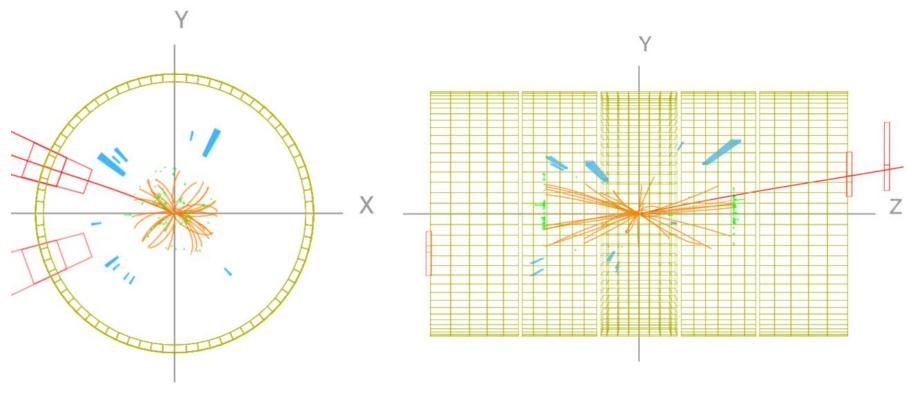




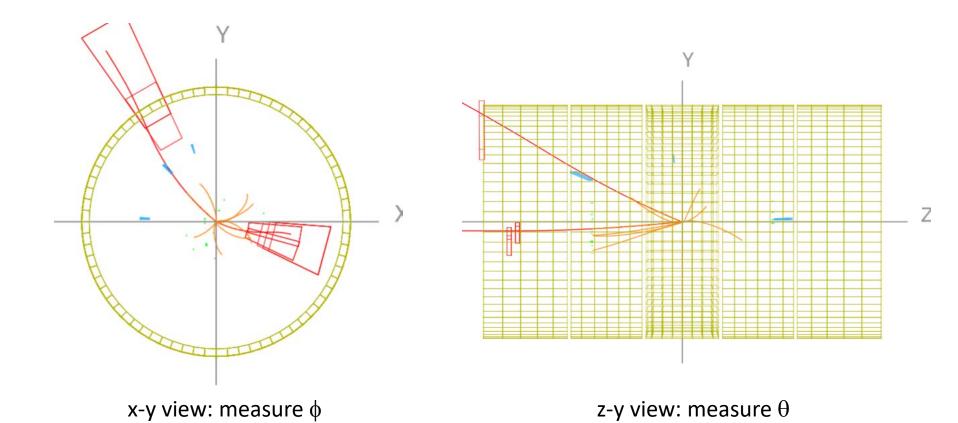


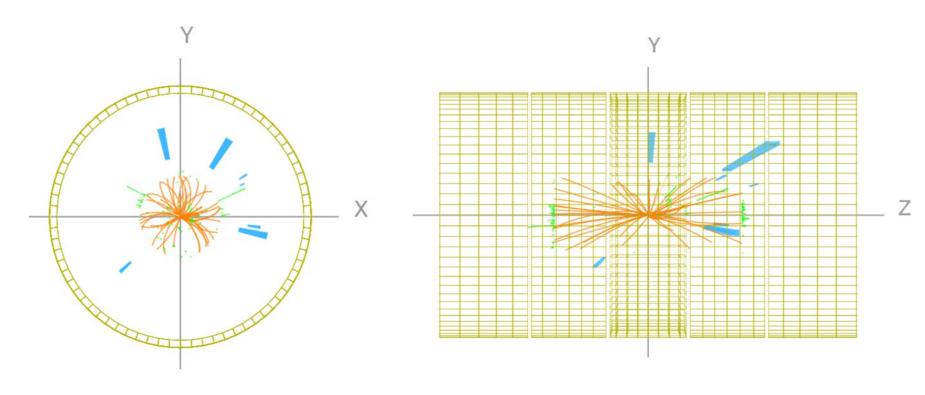
x-y view: measure ϕ z-y view: measure θ



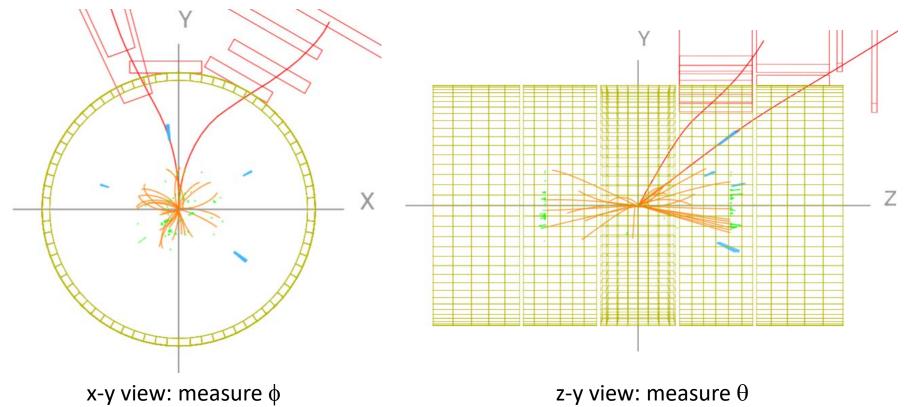


x-y view: measure ϕ z-y view: measure θ

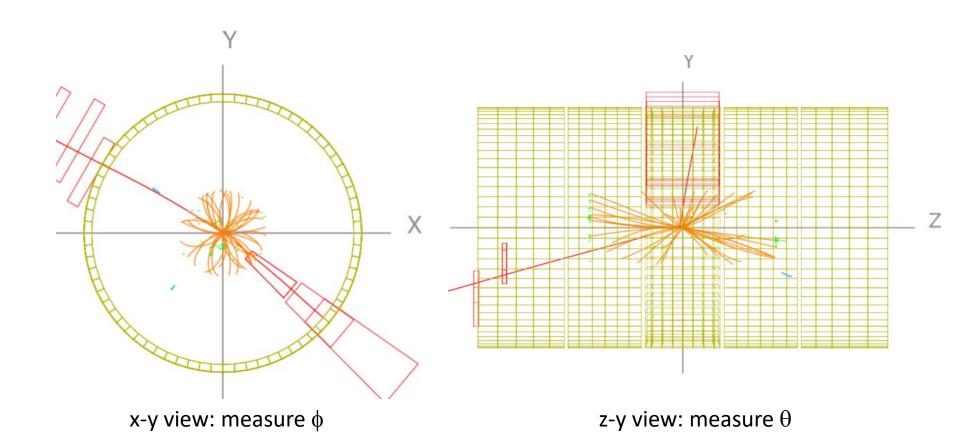


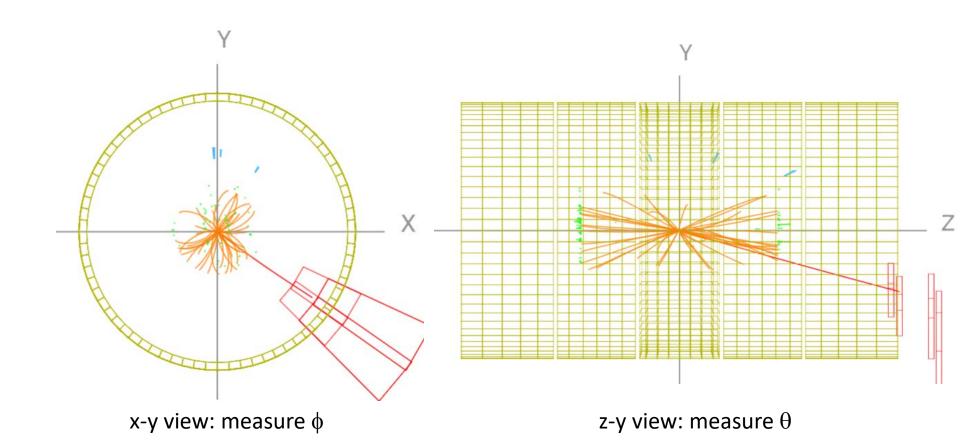


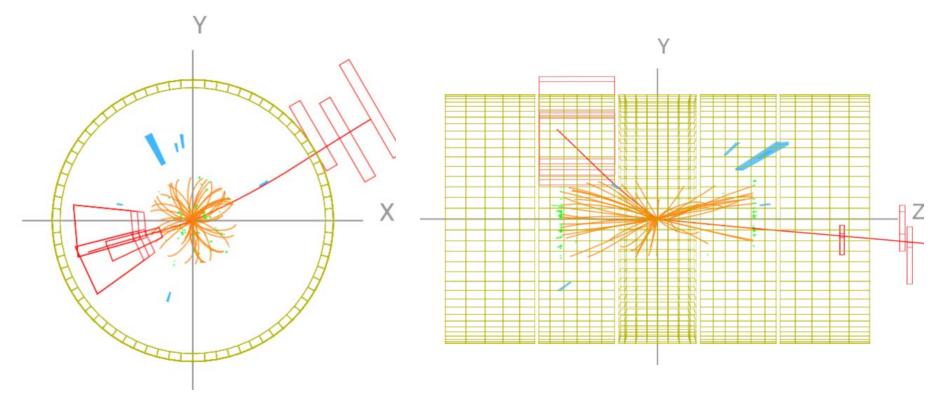
x-y view: measure ϕ z-y view: measure θ



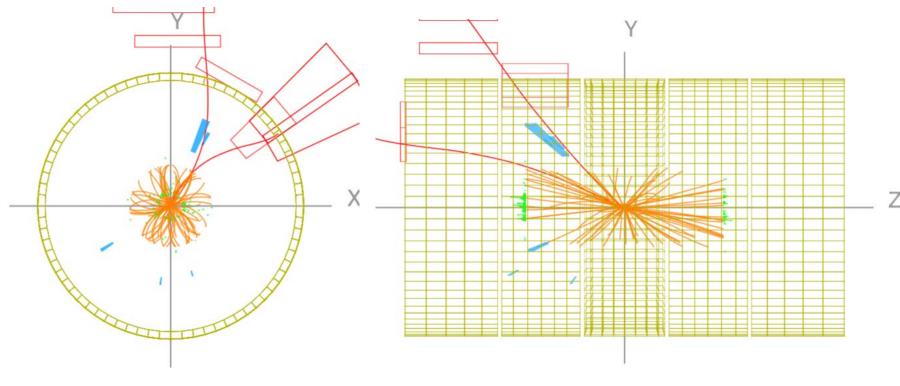
z-y view: measure $\boldsymbol{\theta}$



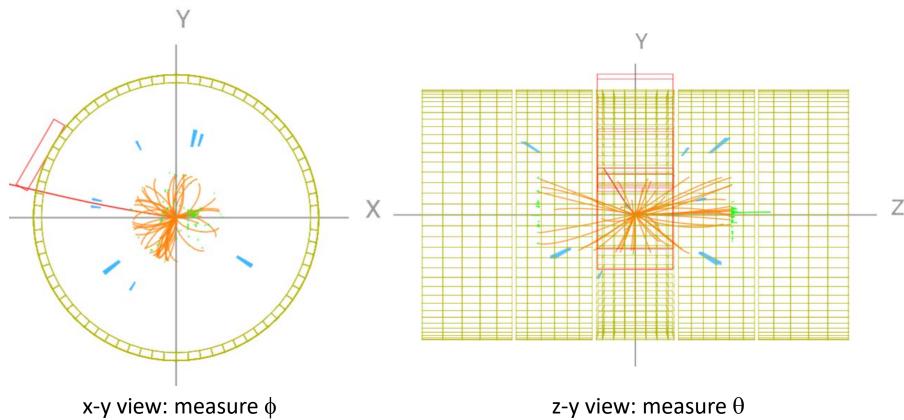




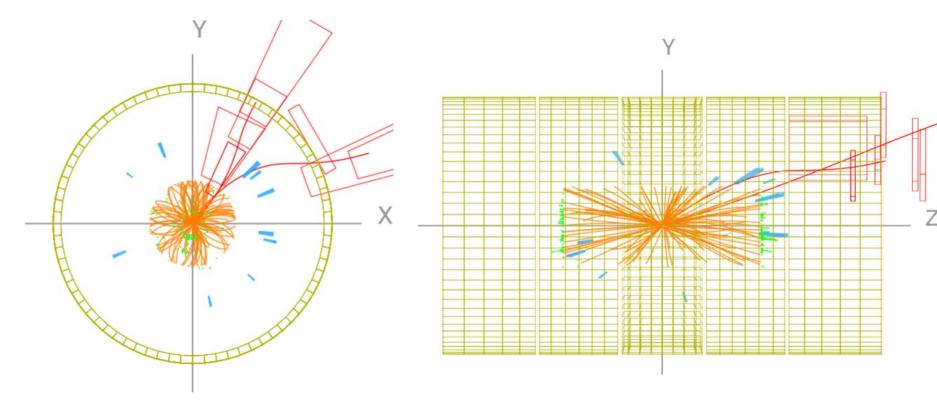
x-y view: measure ϕ z-y view: measure θ



x-y view: measure ϕ z-y view: measure θ

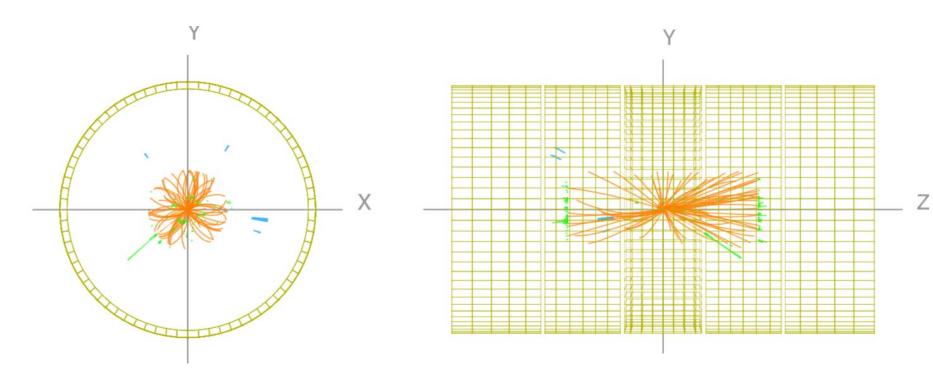


z-y view: measure $\boldsymbol{\theta}$

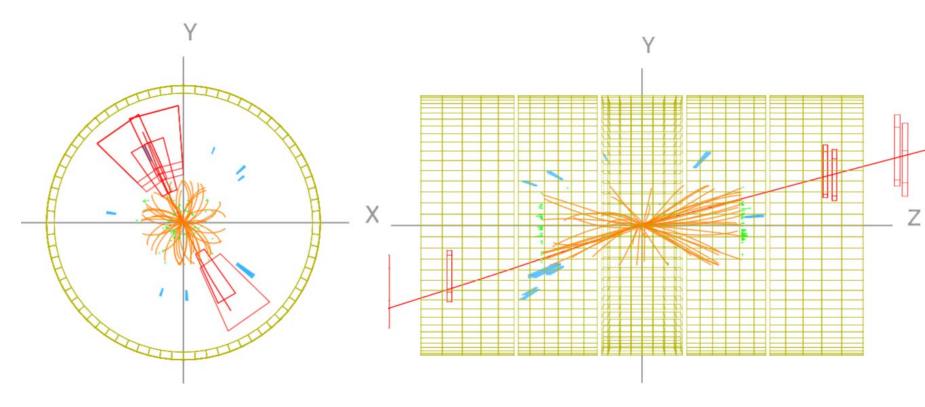


x-y view: measure φ

z-y view: measure $\boldsymbol{\theta}$

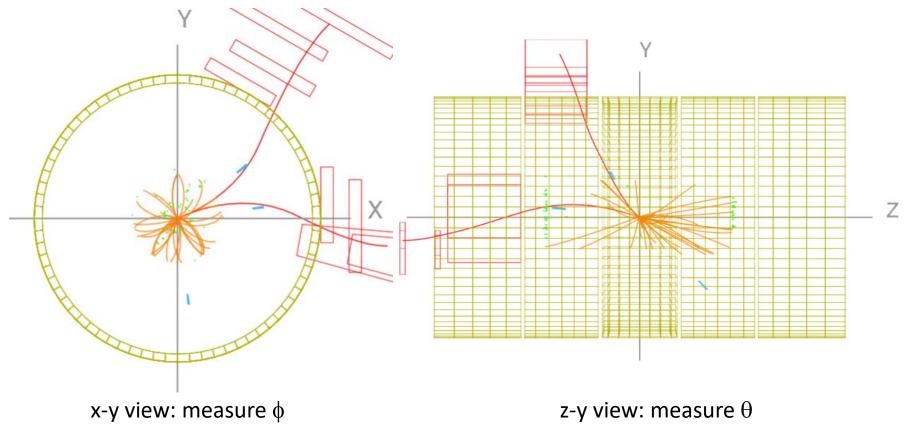


x-y view: measure ϕ z-y view: measure θ

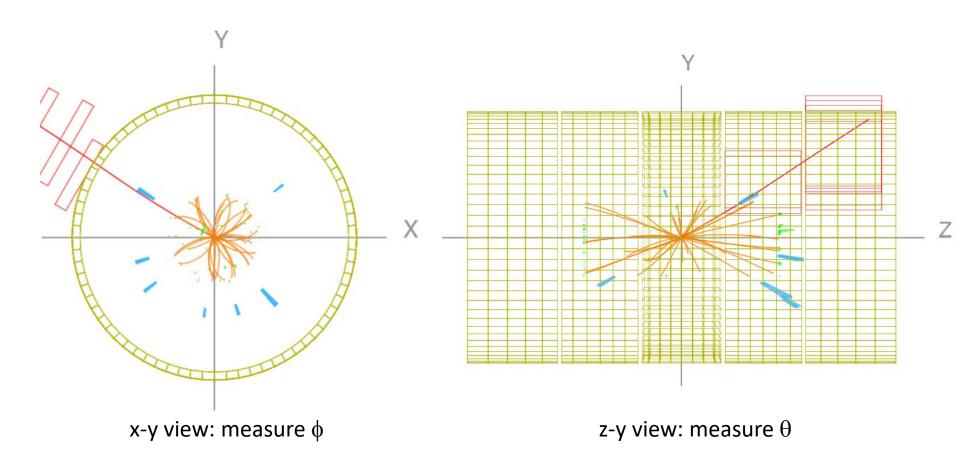


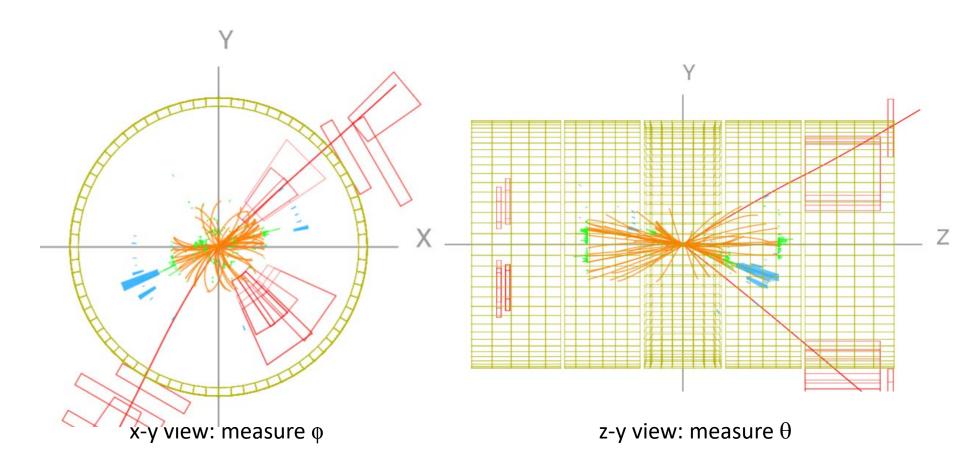
x-y view: measure φ

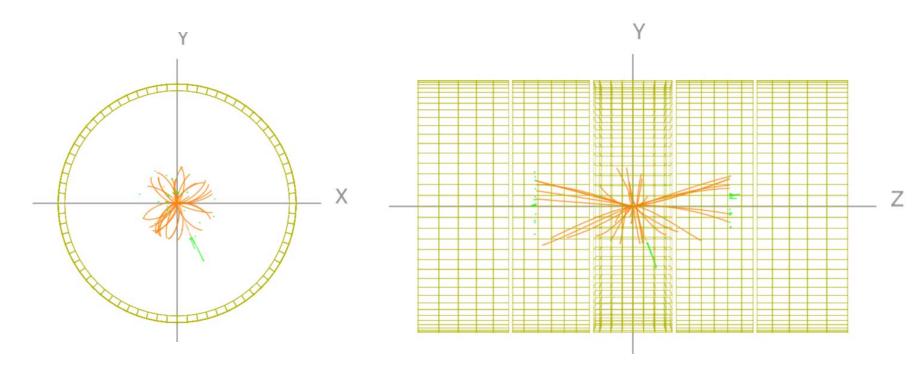
z-y view: measure $\boldsymbol{\theta}$



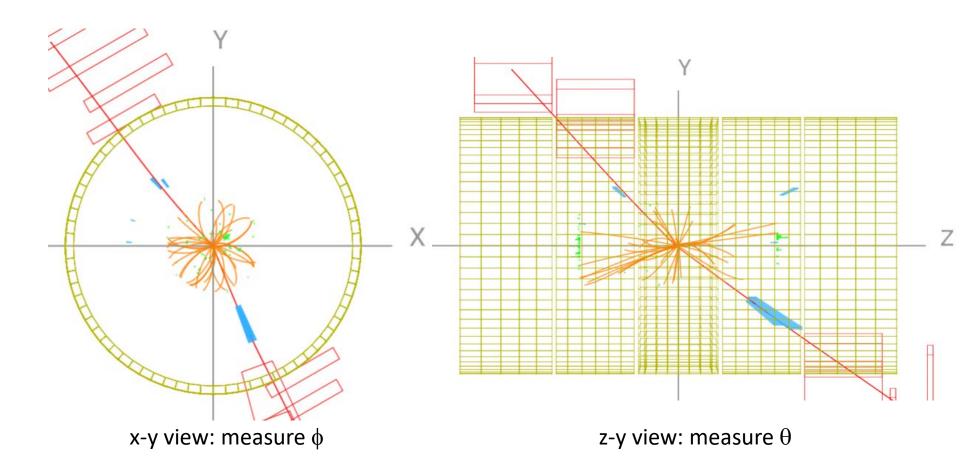
z-y view: measure $\boldsymbol{\theta}$

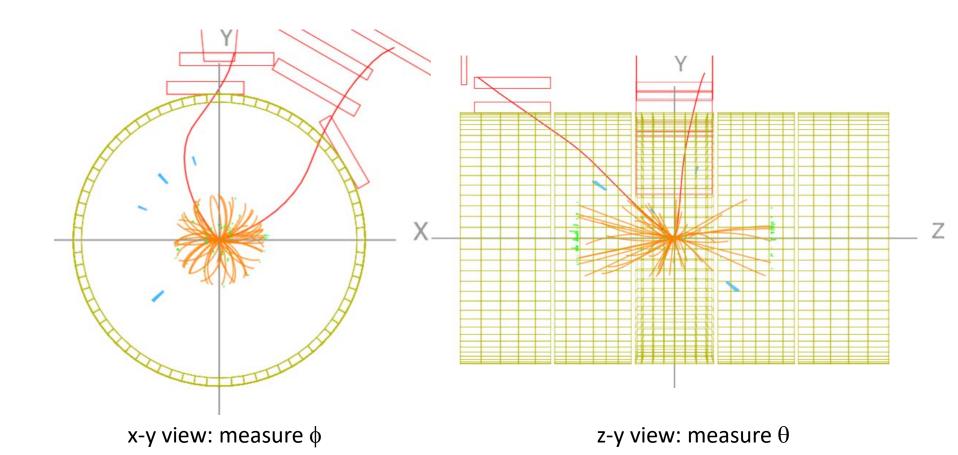


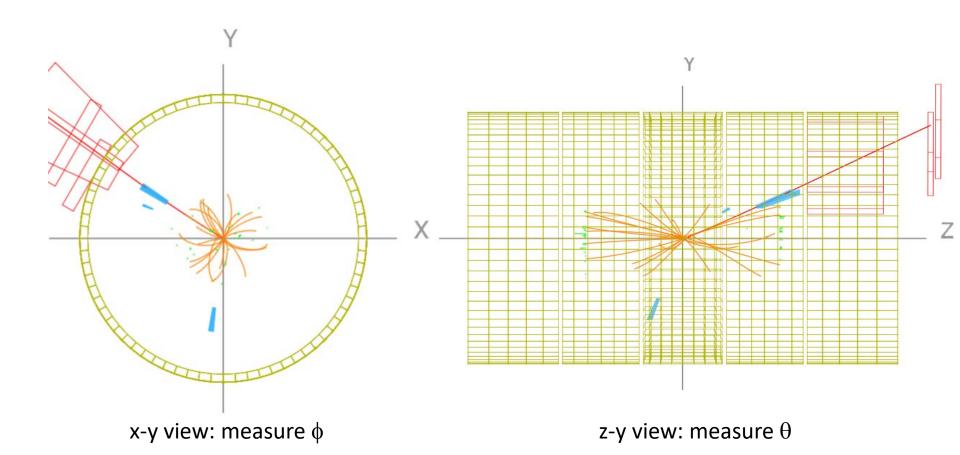


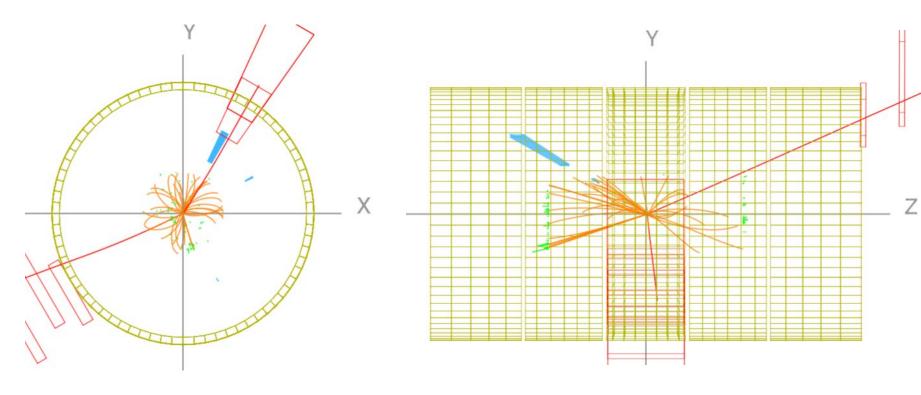


x-y view: measure ϕ z-y view: measure θ

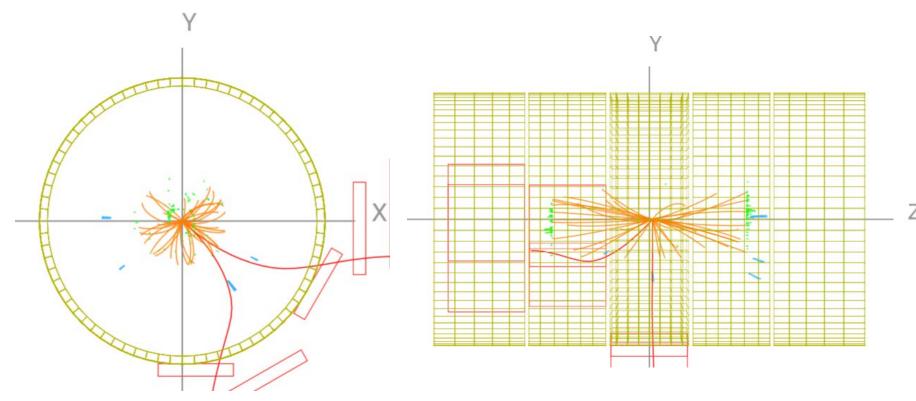




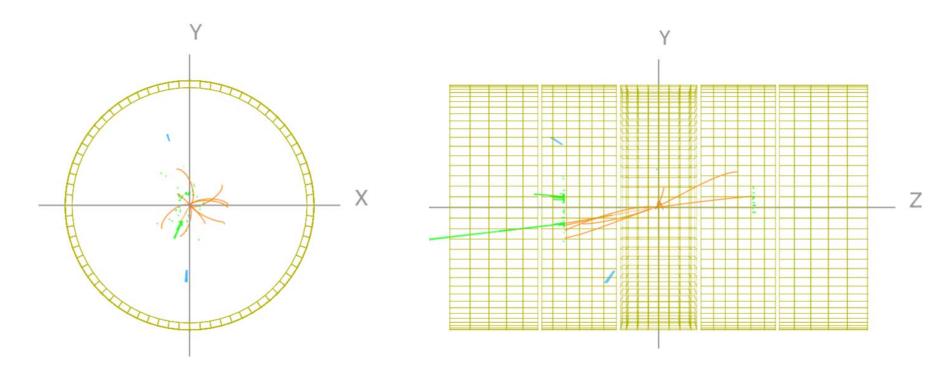




x-y view: measure ϕ z-y view: measure θ

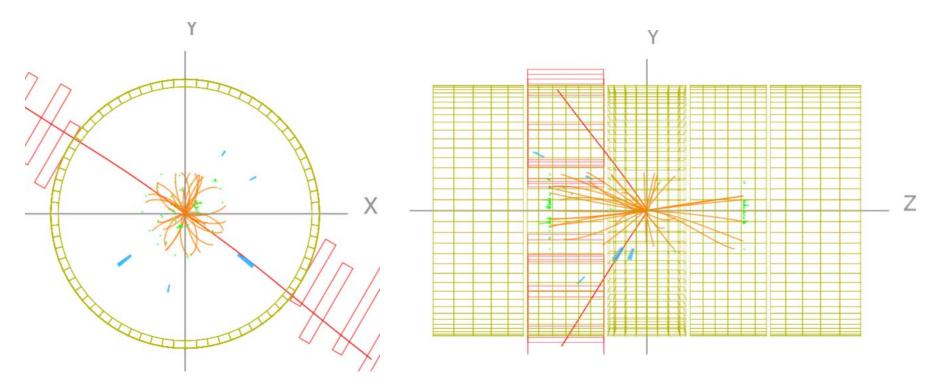


x-y view: measure ϕ z-y view: measure θ

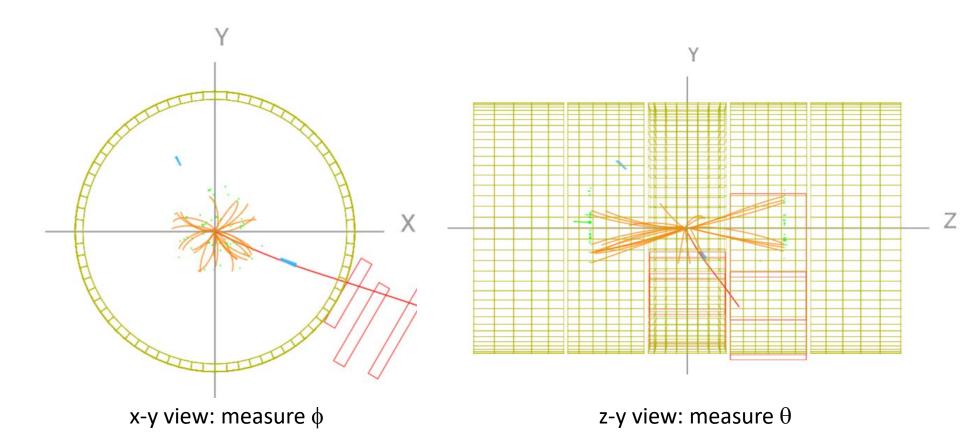


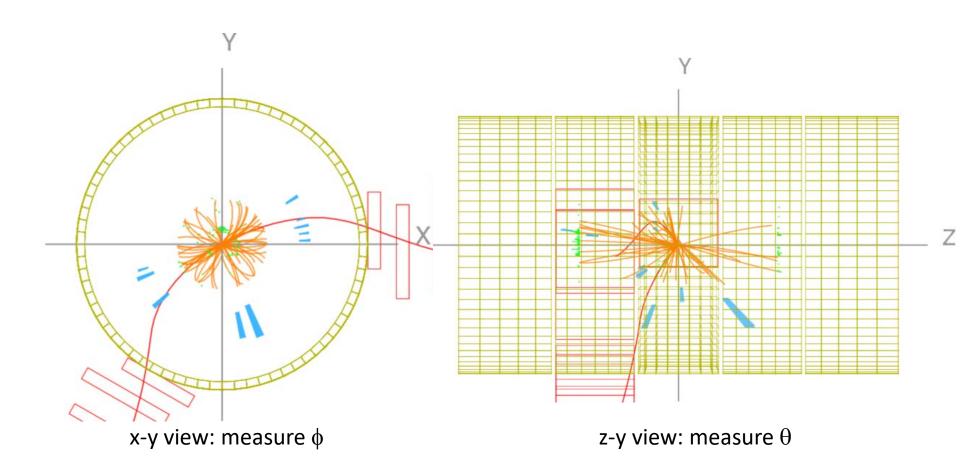
x-y view: measure φ

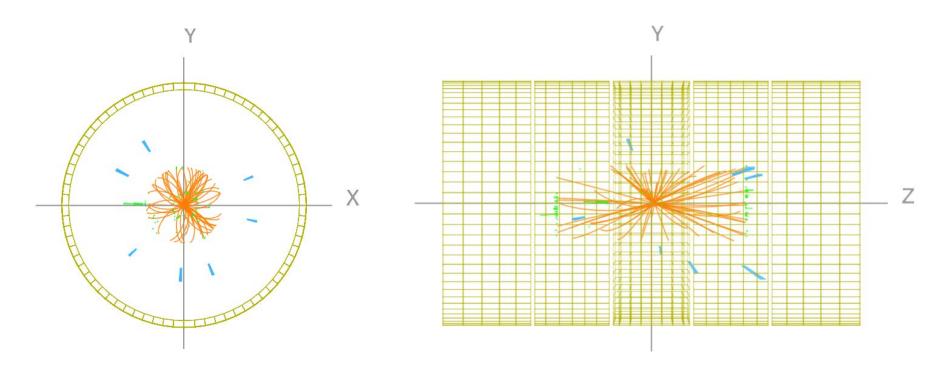
z-y view: measure $\boldsymbol{\theta}$



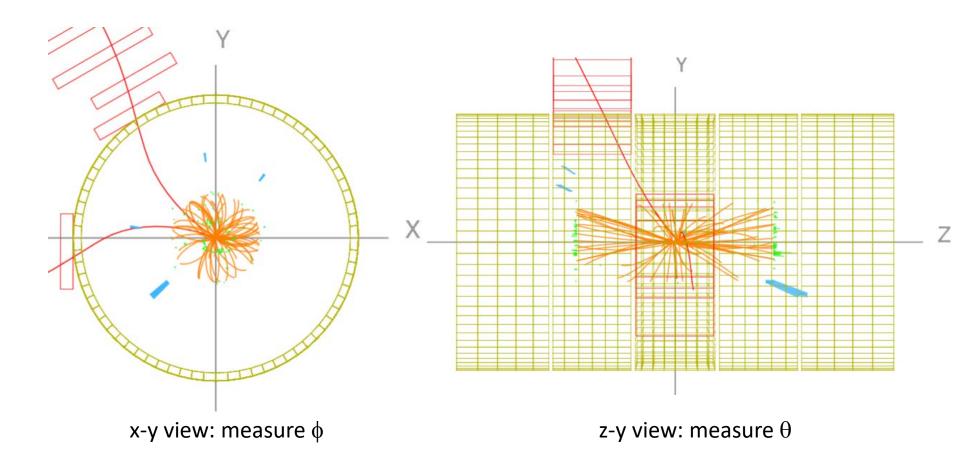
x-y view: measure ϕ z-y view: measure θ

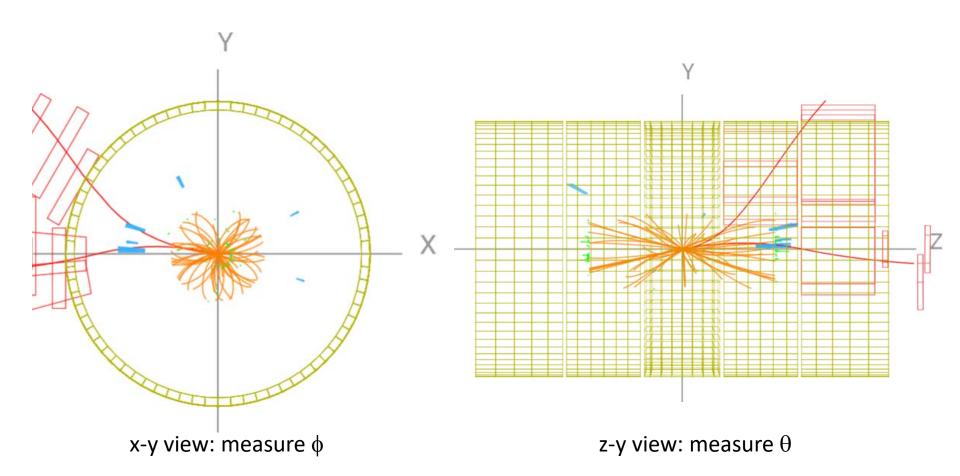


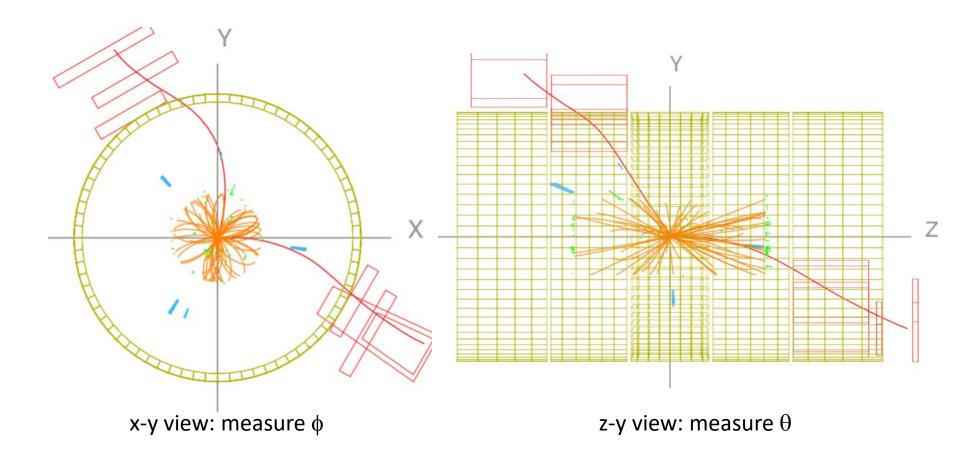


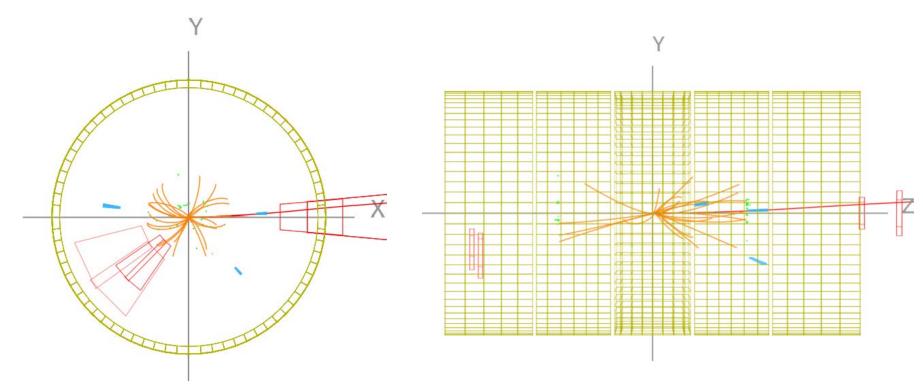


x-y view: measure ϕ z-y view: measure θ









x-y view: measure ϕ z-y view: measure θ